IDS-20d

Icing measurement system

Manual

Setup version 2.27.01 (Firmware 1.66.00)

22.08.2022

Sommer Messtechnik

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Validity

This manual applies to the Icing measurement system with the setup version 2.27.01, including all its subversions.

Created: 31 Mar 2020 Last update: 22.08.2022

EU conformity

This product is in conformity with the following standards:

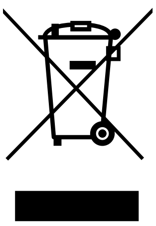
EMC	2014/30/EU	EN 301 489-1 V1.9.2
LVD	2014/35/EU	EN 62311:2008
		EN 62368-1:2014
RoHS II	2011/65/EU	
RoHS III	2015/863/EU	

Safety information

Please read this manual carefully before installing or operating this equipment. Non-compliance with the instructions given in this manual can result in failure or damage of the equipment or may put people at risk by injuries through electrical or mechanic impact.

- Make sure that the personnel responsible for installation, configuration and maintenance is familiar with the applicable regulations and standards!
- Do not perform any installations in bad weather conditions, e.g. thunderstorms.
- Prior to installation of equipment inform the owner of the measurement site or the authority responsible for it. Upon completion, secure the installation from trespassers.
- Maintenance and repair must be performed by trained personnel or an engineer of Sommer Messtechnik. Only replacement parts supplied by Sommer Messtechnik should be used for repairs.
- Make sure that NO power is connected to the equipment during installation and wiring!
- Only use a power supply that complies with the power rating specified for this equipment!
- Keep equipment dry during wiring and maintenance!
- If applicable, it is recommended to use accessories of Sommer Messtechnik with this equipment.

Disposal



After this device has reached the end of its lifetime, it must not be disposed of with household waste! Instead, dispose of the device by returning it to a designated collection point for the recycling of waste electrical and electronic equipment.

Feedback

Should you come across any error in this manual, or if you miss information to handle and operate the IDS-20d we are pleased to receive your feedback to office@sommer.at.

Content

1 What is the IDS-20d?

During the winter season a lot of our infrastructure is affected by icing. In the transportation sector icing may not only impair the proper functioning of engines, sensors and signaling systems but may also pose serious hazards through icy runways and ice accretion on airplanes. Power generation by wind turbines solar- and hydroelectric generators may not be reliable under icy conditions and power transmission may be interrupted by heavy ice loads on power lines. Last but not least, ice on a building or other structure, e.g. antenna, may add a lot of weight and increase the surface area exposed to wind.

Reliable ice detection systems can help avoid such risks and can contribute to reduce maintenance and replacement costs. The ice detection sensor IDS-20d, in the shape of a cube or of rods, is used for the reliable and precise measurement of icing in aviation, on wind power generators, high voltage power lines, cable cars, antennas, overhead wires, roads, buildings and other structures where the formation of ice constitutes a risk.

Depending on the application the IDS-20d provides a combination of different sensor versions which can measure ice loads from 0.01 mm to 80 mm. By measuring the complex impedance in the vicinity of the sensor the IDS-20d is able to distinguish between water and ice and capable to record ice accretion rates.

A unique and valuable feature of the IDS-20d is that it additionally considers meteorological data for the purpose of a plausibility check: Parallel to the ice-sensor the IDS-20d measures the air temperature and humidity and thereof calculates the dew and frost points. The sensor system then uses these data for a plausibility check together of the measured ice values. Thus, the reliability of ice-detection is improved.

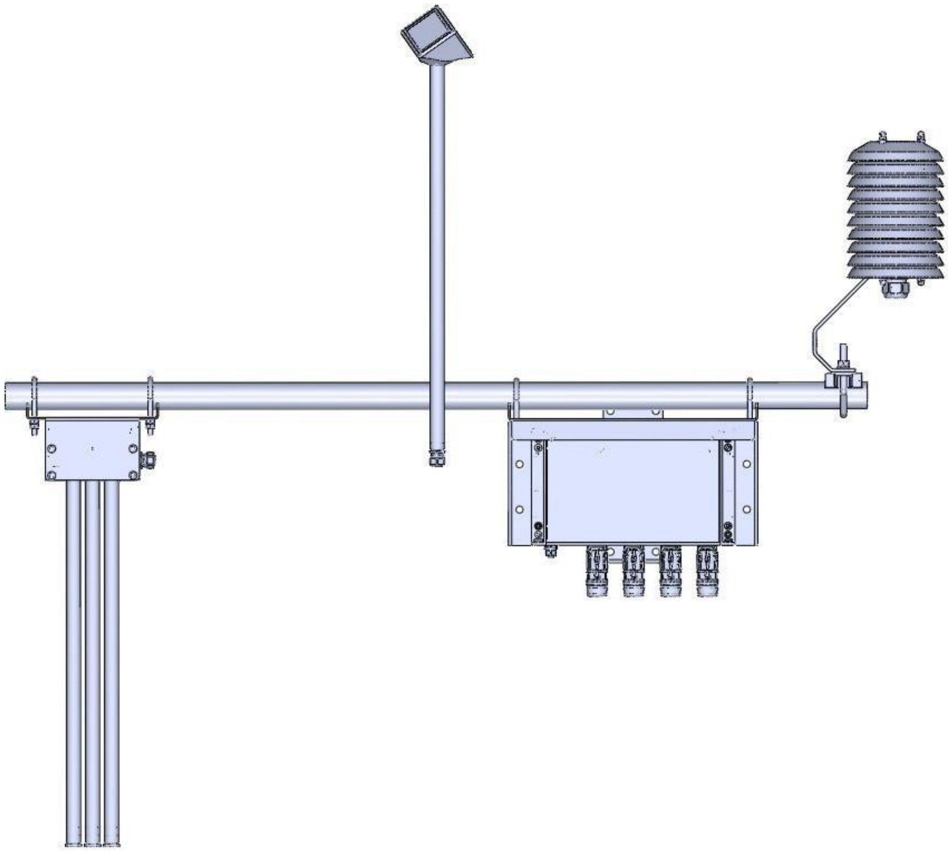


Figure 1 IDS-20d

2 Unpacking

When unpacking your IDS-20d sensor box please make sure that the following items are present:

Qty	Name
1	IDS-20d controller
1	Cube 5 ice sensor
1	Rod T sensor (optionally Cube 5 sensor)
1	Temperature and relative humidity probe
1	Radiation shield
1	Mounting pole Ø 34 x 800 mm
1	Mounting brackets for controller, sensors and radiation shield
1	MAIN sensor cable
1	USB to RS485 isolated converter cable
1	Manual and Commander Software on USB stick

In case of missing or damaged items please contact your Sommer Messtechnik sales partner.

3 Get started

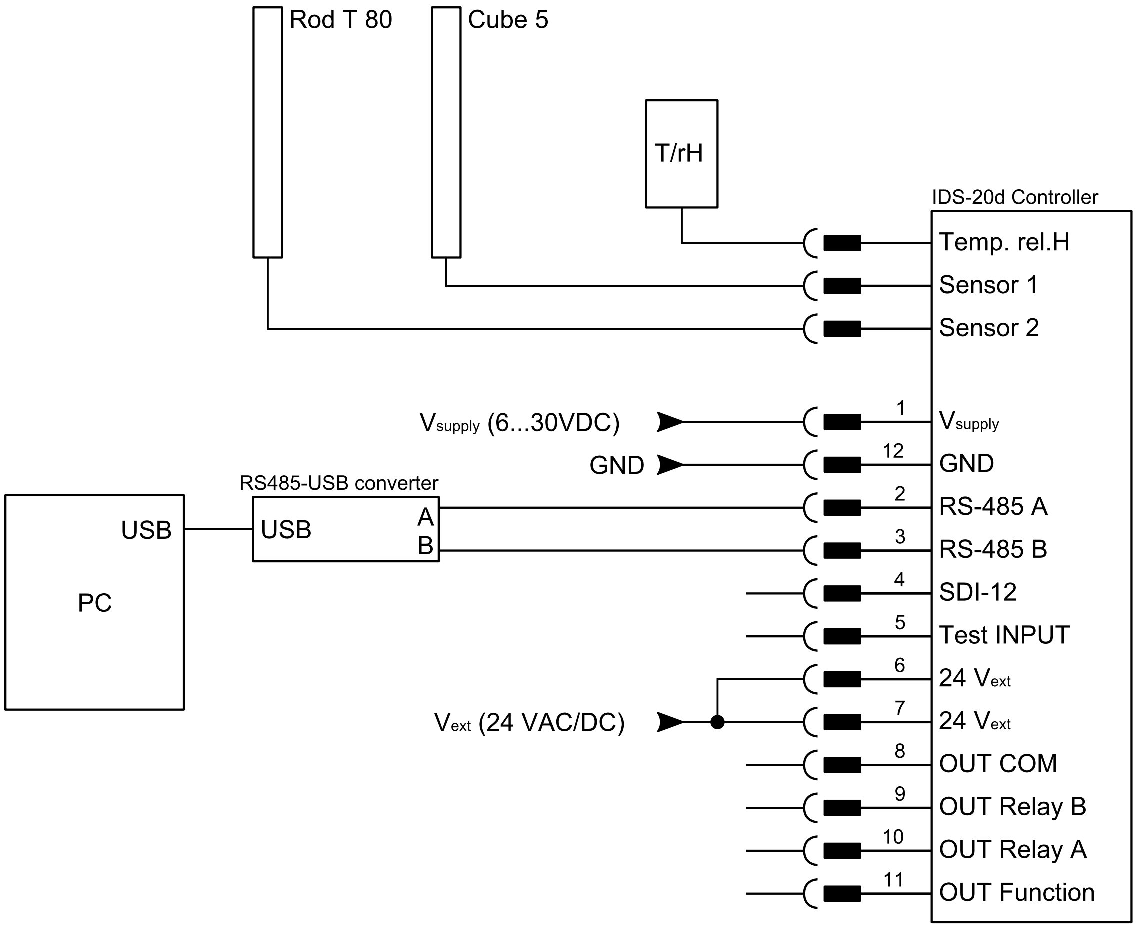
Follow the steps described below to set the basic configurations and to acquire the first measurement results.

NOTE Perform the first start-up in your lab or office before installing the equipment in the field!

3.1 Connect the IDS-20d to your PC

1. Install the Commander support software (see Installation of Commander).
2. Connect the yellow and gray wires of the sensor cable to the RS-485 to USB converter cable and plug it into your PC as illustrated in the figure below.
3. Connect a 9...28 VDC power supply to the IDS-20d as shown in the figure below.
4. Click on Communication assistant on the right-hand side of the Commander window and follow the instructions.
   a. As Type of connection select *Serial connection*
   b. As Device type select *Sensor (9600 Bd)*
   c. Select New connection and select the COM port

   During this procedure the communication assistant will search for connected devices. Upon successful completion, the new connection is added to the connections list (tab Connections (F8)).
5. In the Communication section at the right-hand side of the Commander window select Mode Connection and the previously created connection from the drop-down list.
6. Click Connect to establish a connection with the IDS-20d. If the connection was successful a green icon is displayed at the top-right corner of the Commander window.
7. Select the tab Parameters (F2) and click Download parameters from device on the left side of the Commander window. The complete parameter list is transferred from the sensor to your PC and displayed in the Parameter window.



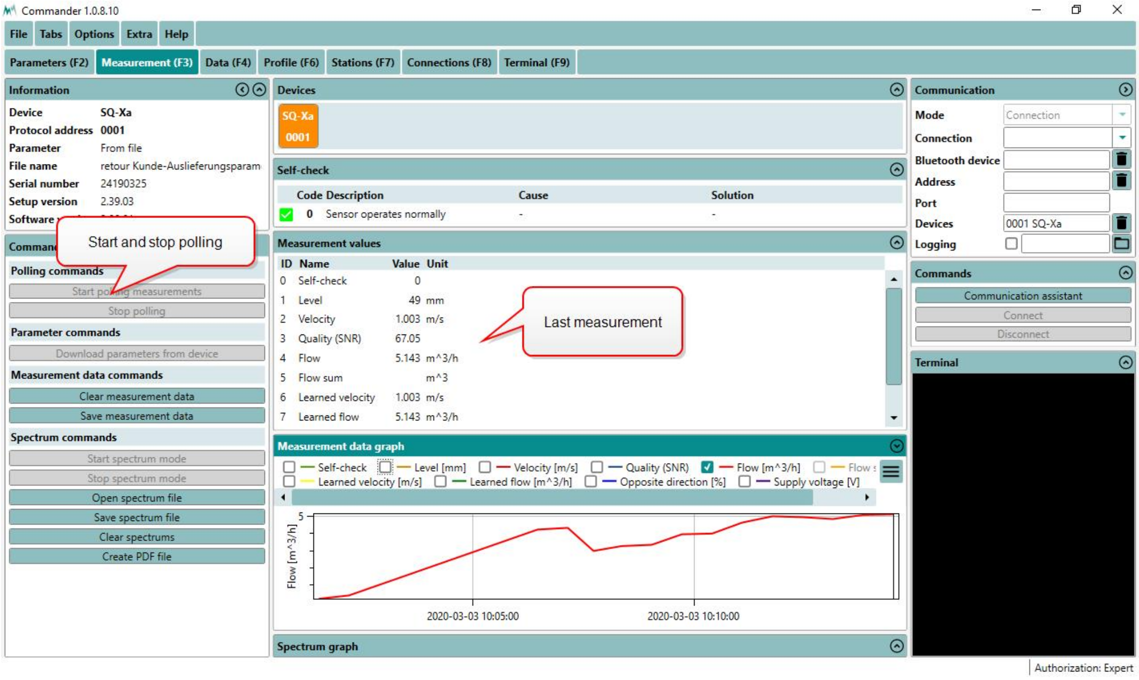
3.2 Configure the IDS-20d

1. Select language, decimal character, units and decimal places (see General settings)
2. Define scope and structure of the data output (see General settings)
3. Set the zero-reading of the sensor (see Sensor setup)
4. Set the limits at which the relays switch (see Relay switching)
5. Send any modifications to the IDS-20d by clicking Upload modified parameters to device.

3.3 Acquire measurements

1. Establish a connection to your device as described in Working with connections.
2. Download the setup of your device as described in Download setup.
3. Select the Measurement (F3) tab.
4. In the Commandssection click Start polling measurement.

5. Select the option Polling with measurements. Now, the Commander will trigger measurements of the IDS-20d without any delays between measurements. The results are displayed Measurement values and plotted in the Measurement data graph.
6. To finish polling mode click Stop polling.



4 How the IDS-20d works

The IDS-20d ice sensor makes use of the different physical characteristics of air, water and ice at varying frequencies of an applied voltage. As illustrated in Figure 2 a single ice-sensor consists of two conductive paths which generate an electric field between them when powered. This electric field is different for air, water and ice. By measuring the resulting complex impedance at different frequencies the volume content of ice, water and air can be detected.

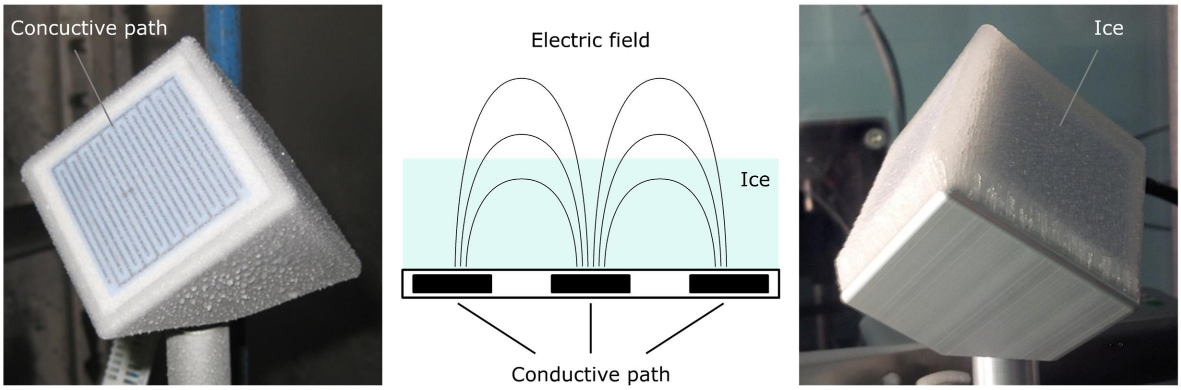


Figure 2 Principle of ice detection

4.1 Sensors

Depending on the application the IDS-20d is available in three versions with different sensor combinations. Figure 3 illustrates these versions.

The IDS-20s contains a single ice-sensor, either the Cube 5 or the Rod T 80. While the first option is primarily used to detect icing events, the latter is applied to monitor heavy ice loads.

The IDS-20a combines two Cube 1 sensors and is mainly applied in aviation. As these two sensors operate intermittently icing events can be detected without any interruption.

The IDS-20dd combines a Cube 5 and Rod T 80 sensor. This versatile system can detect icing events and heavy ice loads and is usually applied in monitoring of buildings and other structures, e.g. antennas or power lines.

4.1.1 Cube 1 sensor

The Cube 1 sensor contains three sensor plates arranged in an angle of 120° to each other. This arrangement allows the determination of the icing direction. The sensor plates can detect water, freezing rain and ice accretion from 0.01 to 1 mm.

The sensor head contains a Pt1000 sensor to monitor the surface temperature of the device. Sensor head and shaft can be heated separately with a 24 VAC/DC power supply.

4.1.2 Cube 5 sensor

The Cube 5 sensor contains three sensor plates arranged in an angle of 120° to each other. This arrangement allows the determination of the icing direction. The sensor plates can detect water, freezing rain and ice accretion from 0.1 to 5 mm.

The sensor head contains a Pt1000 sensor to monitor the surface temperature of the device. Sensor head and shaft can be heated separately with a 24 VAC/DC power supply.

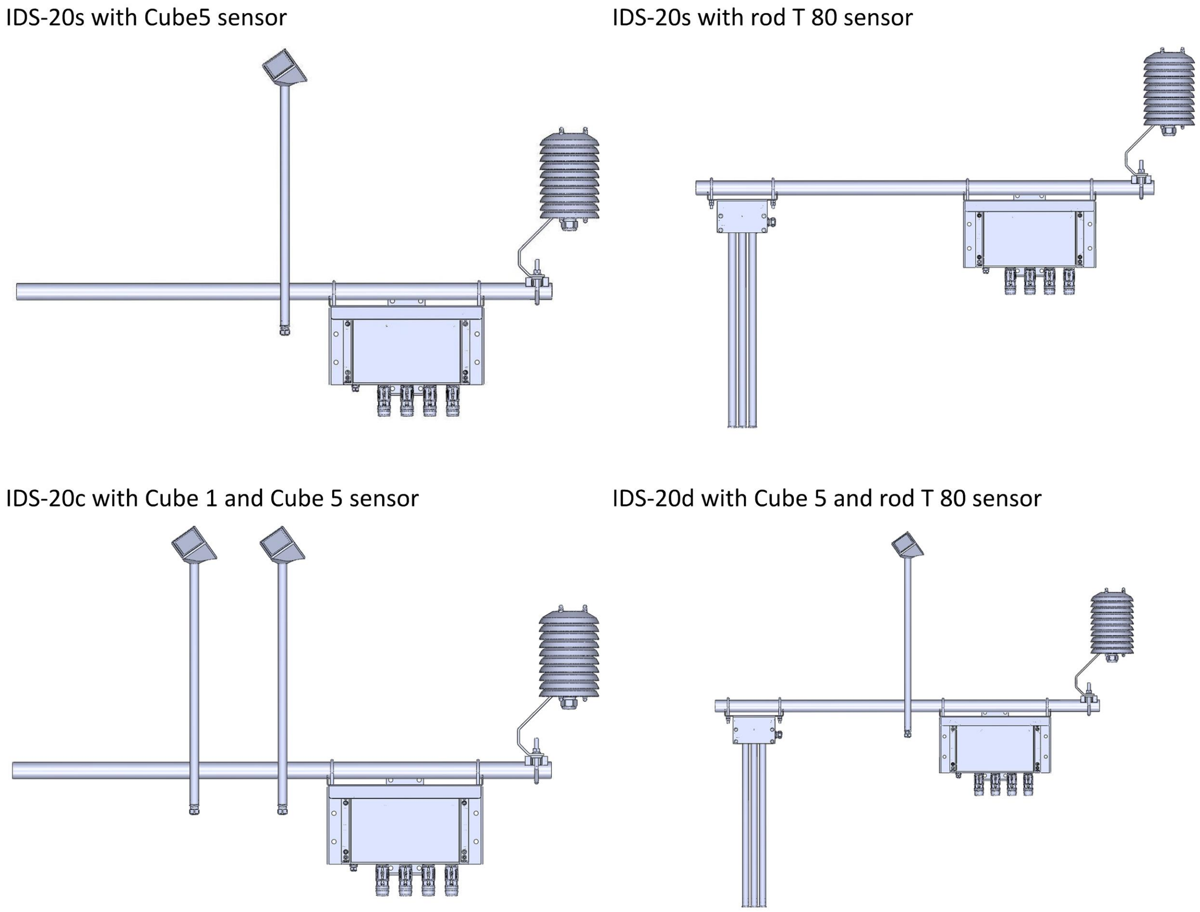


Figure 3 IDS-20d versions

4.1.3 Rod T 80 sensor

The Rod T 80 sensor consists of three metal rods arranged in a triangle. The sensor can detect water, freezing rain and ice accretion from 1 to 80 mm.

The sensor head contains a Pt1000 sensor to monitor the surface temperature of the device. The sensor does not contain a heating option.

4.1.4 T/rH sensor

To validate the icing detected by the ice-sensors an additional T/rH-probe is mounted with the system. See Plausibility check for details.

4.2 Controller

The ice- and T/rH-sensors are connected to the controller of the IDS-20d which reads and processes the acquired data and controls the sensor heating. It also provides an interface to connect to a data processing device, e.g. PC or data logger, and a power supply.

4.3 Plausibility check

Formation and accretion of ice on a surface depends on specific environmental conditions determined by air temperature, humidity and surface temperature.

The IDS-20d uses the present meteorological conditions to verify the icing measured by the ice-sensors: Parallel to the ice detection the IDS-20d measures the air temperature and humidity and calculates the dew and frost points. With these data the IDS-20d checks if the conditions actually permit the formation of ice as detected by the ice-sensors. Thus, icing events are detected with high reliability.

4.4 Relay outputs

The IDS-20d provides two relay outputs to record the occurrence of icing events or to trigger an action upon ice detection. Both relays can be configured to switch at a specified ice or water layer thickness or icing rate. By doing so, different switching combinations can be selected:

- relay A and B respond to limit values of one sensor, e.g. ice layer thickness and icing rate
- relay A responds to a limit value of sensor 1, e.g. presence of water, and relay B to a limit value of sensor 2, e.g. icing rate
- one relay responds to a limit value of one sensor, e.g. icing rate, and the other is turned off

The IDS-20d contains an additional relay that responds to the state of the device, i.e. switches if the IDS-20d detects an error. The relay output can be configured to either close on proper functioning of the device or if the device detects an error.

4.5 Data interpretation

Ice forms at certain air and surface temperatures under high humidity levels. In many applications the information of instantaneous icing on a surface is required. In others, the duration and intensity of an icing event is of interest. In the following examples the interaction between atmospheric conditions and the occurrence of icing is illustrated.

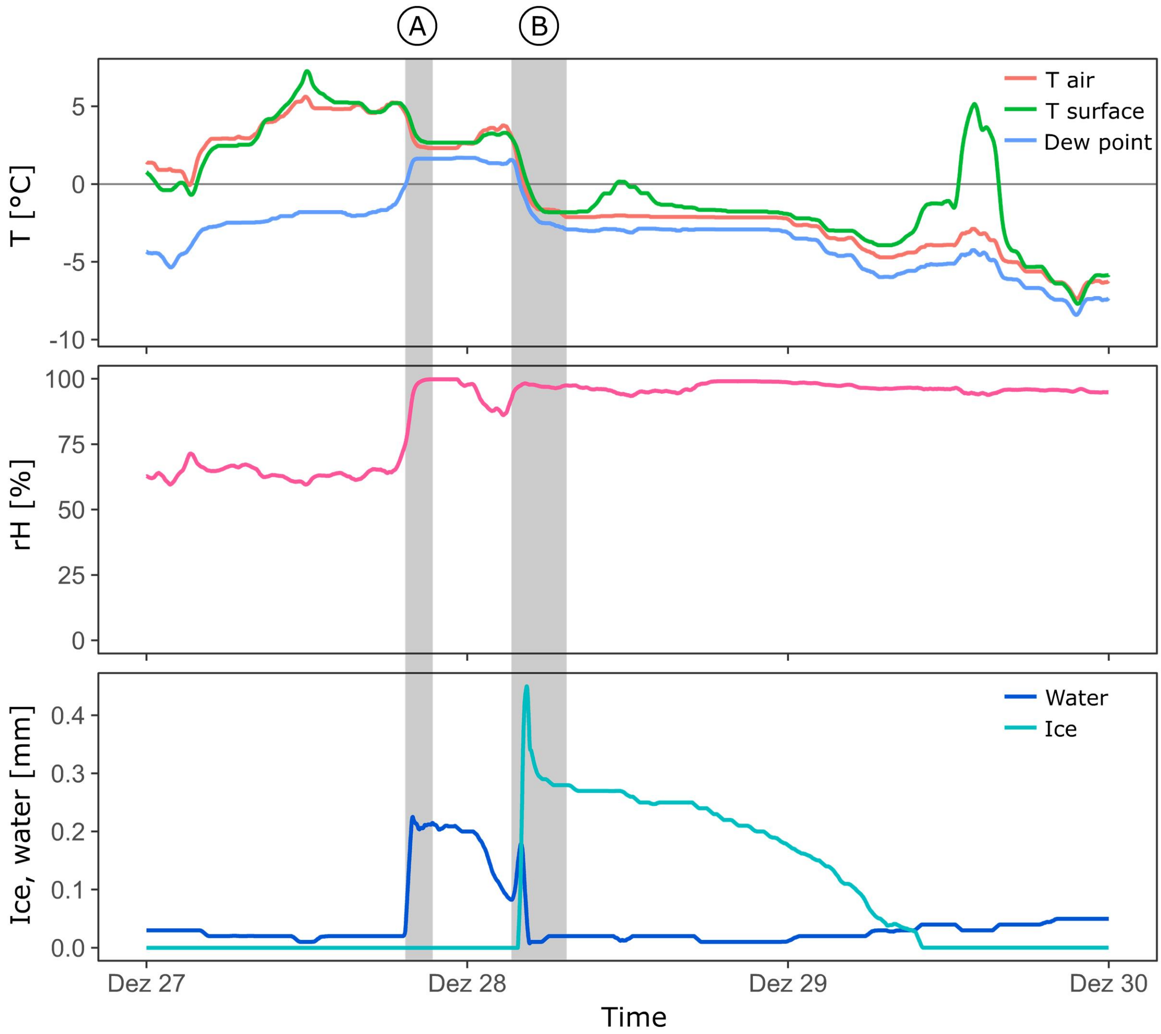


Figure 4 Dew and ice on a Cube 5 sensor

In Figure 4 the formation of water and ice on a Cube 5 sensor is shown. In period A the air and surface temperature of the sensor drop and closely reach the dew point, thus increasing the relative humidity. As a consequence water condenses on the sensor surface as illustrated in the lower plot.

During the early morning hours the air and surface temperature further drop below freezing. This temperature drop first leads to more water condensation and is then followed by a sharp rise in ice formation as the water freezes. Shortly after, the sun rises and transforms the thin ice layer on the sensor through irradiation. This is visible by a quick drop of the ice thickness. During the day more ice sublimates despite below-zero temperatures.

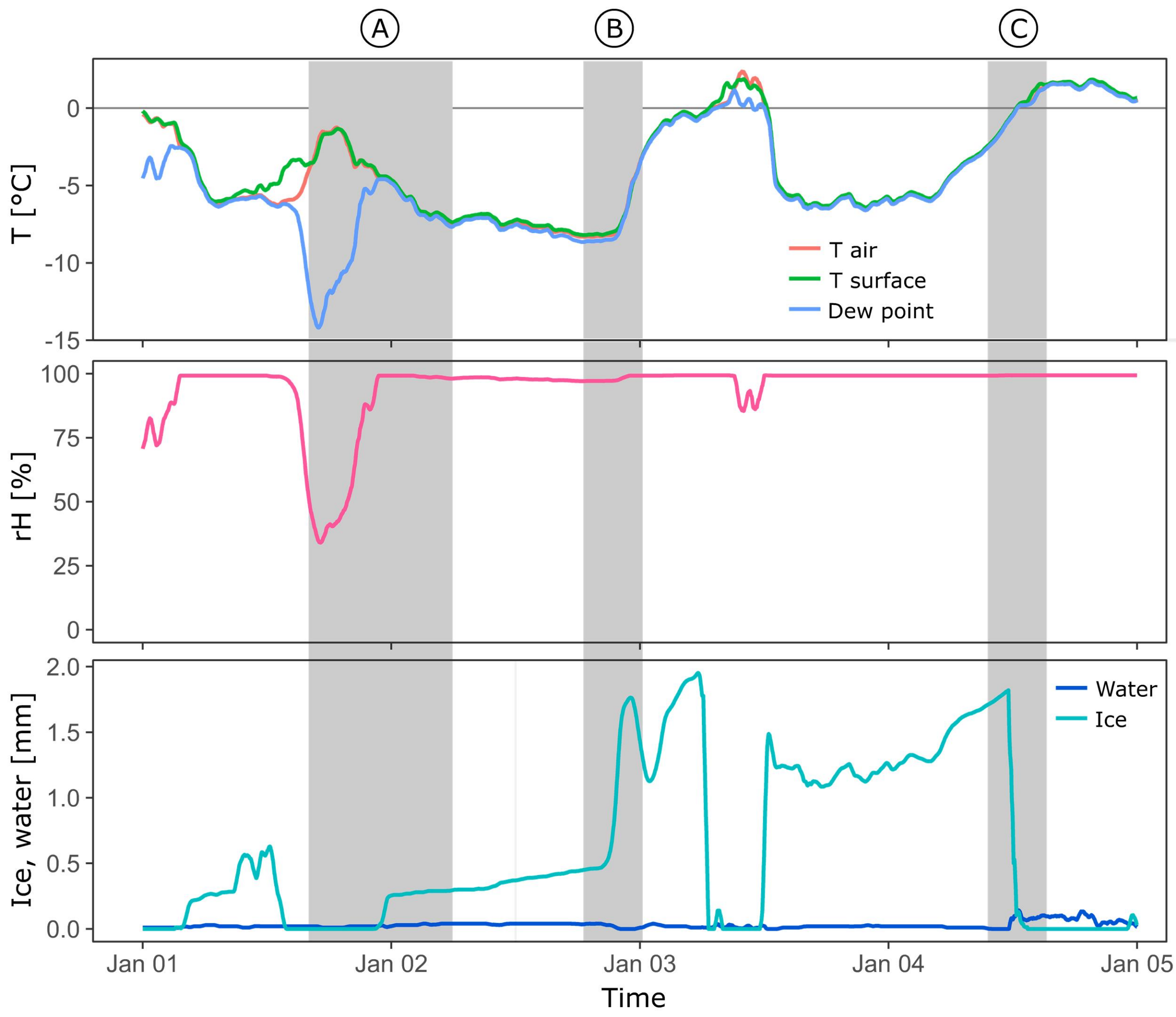


Figure 5 Icing of a Cube 5 sensor

In Figure 5 several icing events of a Cube 5 sensor are illustrated. During period A air and sensor surface temperature are below zero. However, due to relatively dry air no ice is formed on the sensor. Later on, as the temperature drops again, the humidity approaches saturation. As soon as the frost point is reached, ice starts to accrete on the sensor surface and keeps doing so with further falling temperatures.

During period B the temperature reaches a minimum and then rises within a few hours by more than 5°C. Consequently, the ice layer on the sensor grows considerably faster.

In period C the temperature rises from below zero to positive temperatures, keeping its water saturation. Once the temperature passes 0°C the ice on the sensor melts rapidly, which is marked by a sharp drop in ice layer thickness and a slight increase of water on the surface.

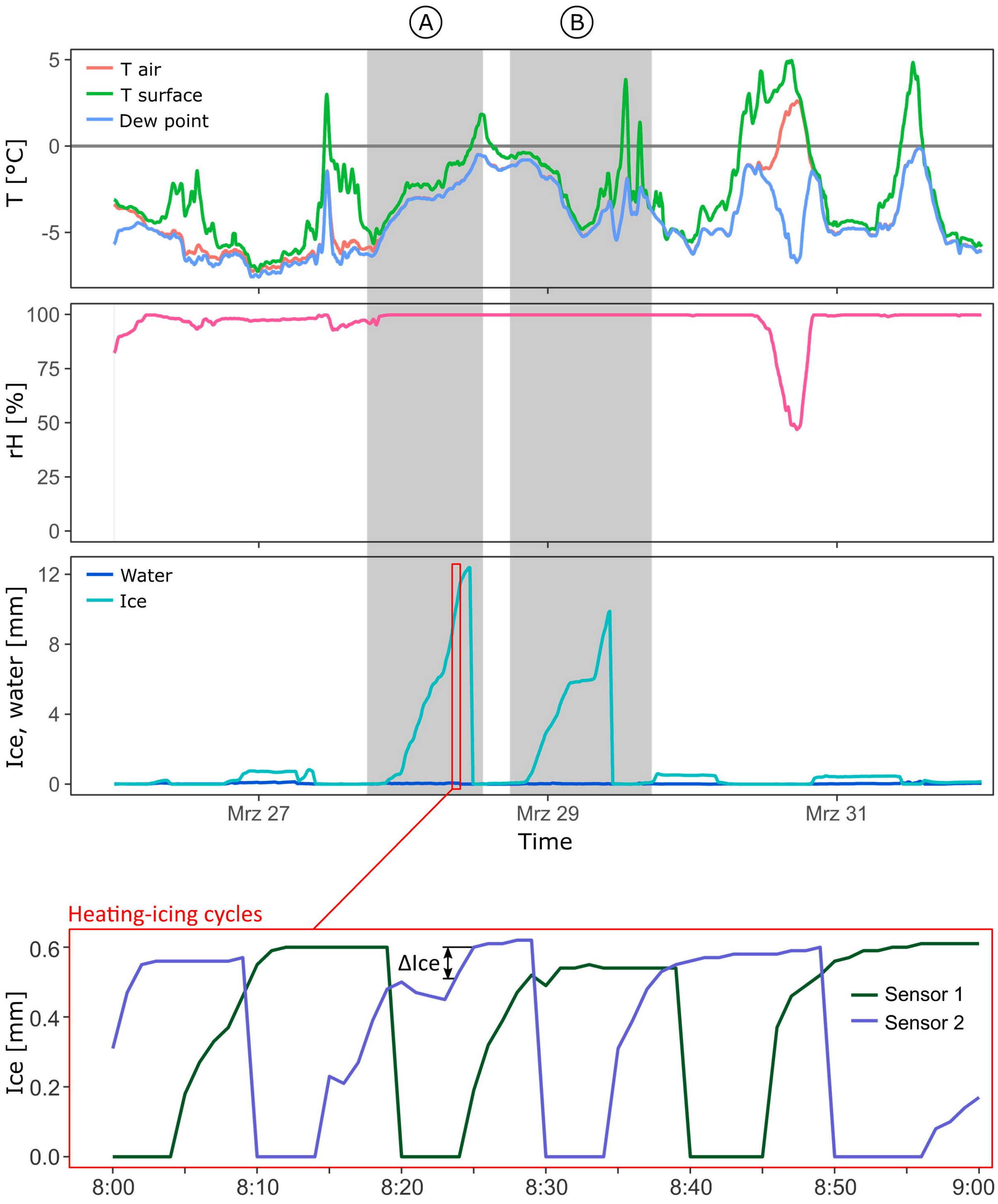


Figure 6 Icing-heating cycle of a Cube 1 sensor pair

In Figure 6 two pronounced icing events are shown. The ice layer on the sensor surface grows at different rates, depending on the ambient temperature. As soon as the sensor surface temperatures rise above 0°C again the ice on the Cube 1 sensors melts rapidly and thus terminates the icing events.

The close-up of Figure 6 also shows the intermittent heating-icing cycles of the two Cube 1 sensors used in the IDS-20a. Whenever one sensor is heated and dried, the other monitors ice accretion. The ice accumulation between two measurements, ΔIce, is summed up and recorded as the total ice thickness as shown in the Ice graph above.

5 Components

5.1 MAIN connector

MAIN (12 Pins)	Pin/Wire	Function	Description
Power supply	1	Vsupply	10…30 V
	12	GND	yellow-green
RS-485 interface	2	RS485 A	1 x RS-485 (1200…115200 Baud) ASCII – Protokoll Modbus
	3	RS485 B	
SDI-12 interface	4	SDI12	1 x SDI-12 (1200 Baud)
Test-INPUT (Simulation)	5	Test	Low Level: 0…0,6 V High Level: 2…30 V
Heating	6	$+24V_{ext}$	AC or DC
	7	$-24V_{ext}$	AC or DC
Relay OUTPUT	8	OUT COM	potential-free, max. 0.8A
	9	OUT Relay B	
	10	OUT Relay A	
	11	OUT function	

ATTENTION The relay outputs are referenced to GND on pin 12.

6 Specifications

IDS-sensors			
Sensor type	Cube sensor 5	Cube sensor 1	Rod sensor 80
Measuring range ice thickness	0.1…5 mm	0.01…1 mm	1…80 mm
Weight	0.7 kg	0.7 kg	2.3 kg
Length	560 mm	560 mm	580 mm

T/rH-sensor	
Dew point	-20…+20 °C
Frost point	-20…+20 °C
Air temperature	-40…+60 °C
Air humidity	0…100 %
Weight	0.715 kg
Size L x W x H	310 x 120 x 165

IDS-controller	
Power supply	Sensors 10…28 VDC Heating 24 VAC/DC integrated overvoltage protection
Power con- sumption	Active measurement 50 mA at 12 VDC Heating max. 7A at 24 VAC/DC
Output	RS-485 (Modbus) SDI-12 3x relay output, max. 0.8 A each
Operating tem- perature	-40…60 °C
Protection rating	IP 66
Lightning pro- tection	Integrated Lightning Protection against indirect Lightning; discharge capacity 0,6 kW Ppp
Size L x W x H	318 x 208 x 132 mm
Weight	3.6 kg

7 Installation

7.1 Site selection

The IDS-20d may be installed as a stand-alone system or mounted to facilities such as wind turbines, utility poles or antennas. To gain icing data that describe the icing on the monitored facility as accurate as possible the IDS-20d has to be installed at a representative position. This means that the ice-sensors should face the same environmental conditions as the monitored facility. Especially, the ice-sensors should not be mounted in the lee of an installation. It is also very important that the ice-sensors are influenced as little as possible by any installation or structure. Make sure that the sensors are not installed too close to your monitored facility.

The sensors and controller of the IDS-20d have very low power consumption and can be operated with an autonomous power supply, e.g. solar generator. However, if the IDS-20d is operated with sensor heating (up to 7 A at 24 VAC/DC) your measurement site needs to have access to mains power.

The IDS-20d must not be installed where passers-by could be hit by falling ice. If required, close off the measurement site and/or indicate the risk.

7.2 Things to consider for installation

7.2.1 Power supply

The IDS-20d consumes 50 mA @ 12 V during active measurements. Between measurements the IDS-20d automatically switches into standby-mode.

The Cube 5 sensor of the IDS-20d is heated if a defined ice-layer thickness is exceeded. This heating requires up to 7A @ 24V and can be provided by either a 24 VAC or 24 VDC power supply. The Rod T 80 senor has no heating.

7.2.2 Signal cables

Maximum cable length

Please consider the maximum cable lengths for the applied transmission protocol:

Protocol	Max. cable length
SDI-12	~60 m (depending on wire cross section and number of sensors)
RS-485	~300 m

Table 1 Maximum cable lengths

NOTE Cable lengths longer than 60 m require a heavier gauge wire if the power supply drops below 11 V.

7.2.3 Lightning protection

If the underground at the measurement site permits sufficient current dissipation it is strongly recommended to equip the sensor support or mast with properly dimensioned lightning protection. Consult an expert for advice.

The IDS-20d is protected against overvoltage. If a data logger is mounted to the mast, its ground lug must be properly connected to earth ground.

7.3 Required tools and equipment

Prepare the following tools and equipment to install the IDS-20d:

Qty	Tool
1	Flat spanner 13 mm
1	Wire cutter

7.4 Mounting

The IDS-20d is shipped with mounting accessories which combine the ice-sensors, T/rH-sensor and the controller to a single unit. Please follow the instructions below to mount your IDS-20d:

1. Mount the IDS-20d controller to the structure of your measurement site with the provided shackles. The housing of the IDS-20d controller provides brackets to mount a horizontal or vertical tube with a diameter up to 60 mm. Tighten the shackles around the tube and secure them with additional nuts.
2. Attach the supplied Ø 34 mm mounting tube to the IDS-20d controller as illustrated below. Tighten the shackles around the tube and secure them with additional nuts.

3. Mount the Cube 5 sensor on the 34-mm tube with the black dot on the sensor head facing north. Make sure that the sensor is mounted upright. Tighten the shackles around the tube and sensor shaft and secure them with additional nuts. If the sensor is not adjusted towards north, any offset can be corrected for in the Commander software.
4. Attach the Rod T 80 sensor on the 34-mm tube with the black dot on the sensor head facing north. Make sure the rods of the sensor point downwards. Again, tighten the shackles around the tube and secure them with additional nuts. If the sensor is not adjusted towards north, any offset can be corrected for in the Commander software.

ATTENTION
The rods of the Rod T 80 sensor must always point downwards. Otherwise, ice may accrete on the sensor housing and thus produce erroneous ice readings.
However, the Rod T 80 sensor may be mounted in a slanted position as shown in Figure 8. This might be appropriate when monitoring power lines. In this case the sensor may be aligned in the direction of the power cables.

5. Insert the T/rH-sensor into the radiation shield and secure it by tightening the plastic nut.
6. Attach the radiation shield in an upright position to the 34-mm tube. Tighten the shackles around the tube and secure them with additional nuts.
7. Connect the sensor cables to the quick-connectors of the IDS-20d controller:
   1. Cube 5 sensor to Sensor 1
   2. Rod T 80 sensor to Sensor 2
   3. T/rH-sensor to Temp. rel. H
8. Connect the MAIN sensor cable to the IDS-20d controller.
9. For the sensor heating and controller operation connect your power supply to the other end of the MAIN sensor cable as shown in Figure 10. Separate power supplies for controller and heating may be used. Make sure the power supply for the sensor heating provides sufficient power for defrosting (≤ 7A).
10. Connect your data acquisition device to the IDS-20d.
11. Optional: Connect the IDS-20d controller to the switch cabinet provided as an accessory by Sommer.

TIP Sommer provides a switch cabinet for the IDS-20d. This cabinet contains a power supply for sensor heating and controller operation, a data logger as well as a cellular modem for data transmission.

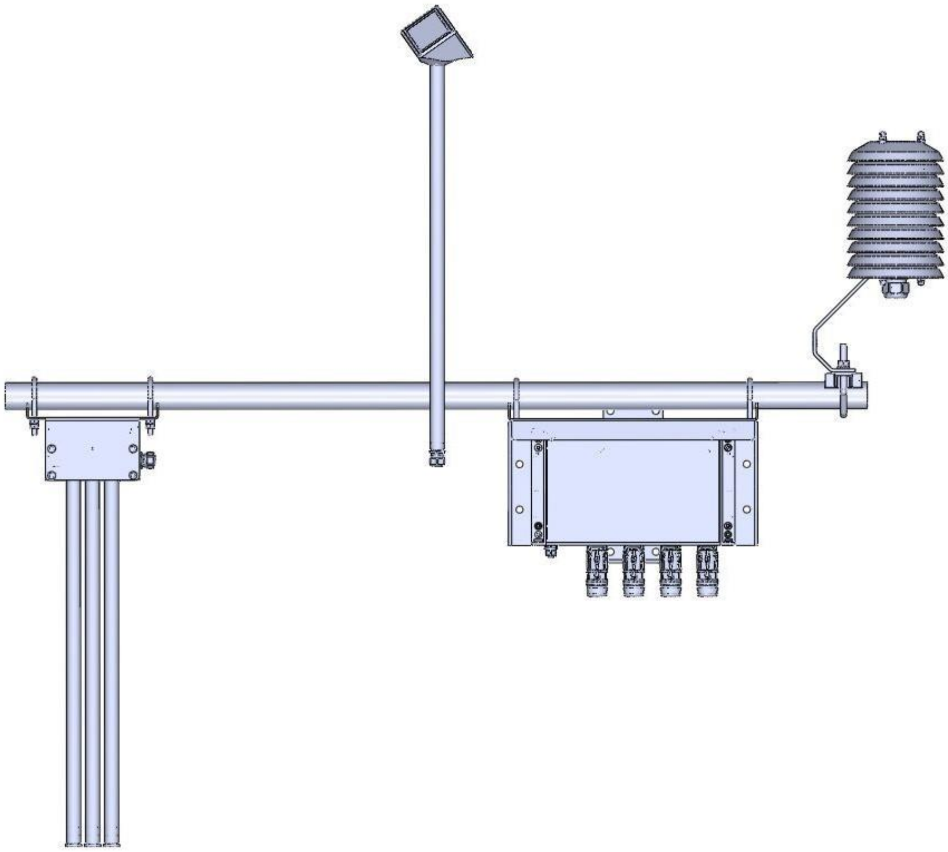


Figure 7 Mounting of sensor and controller

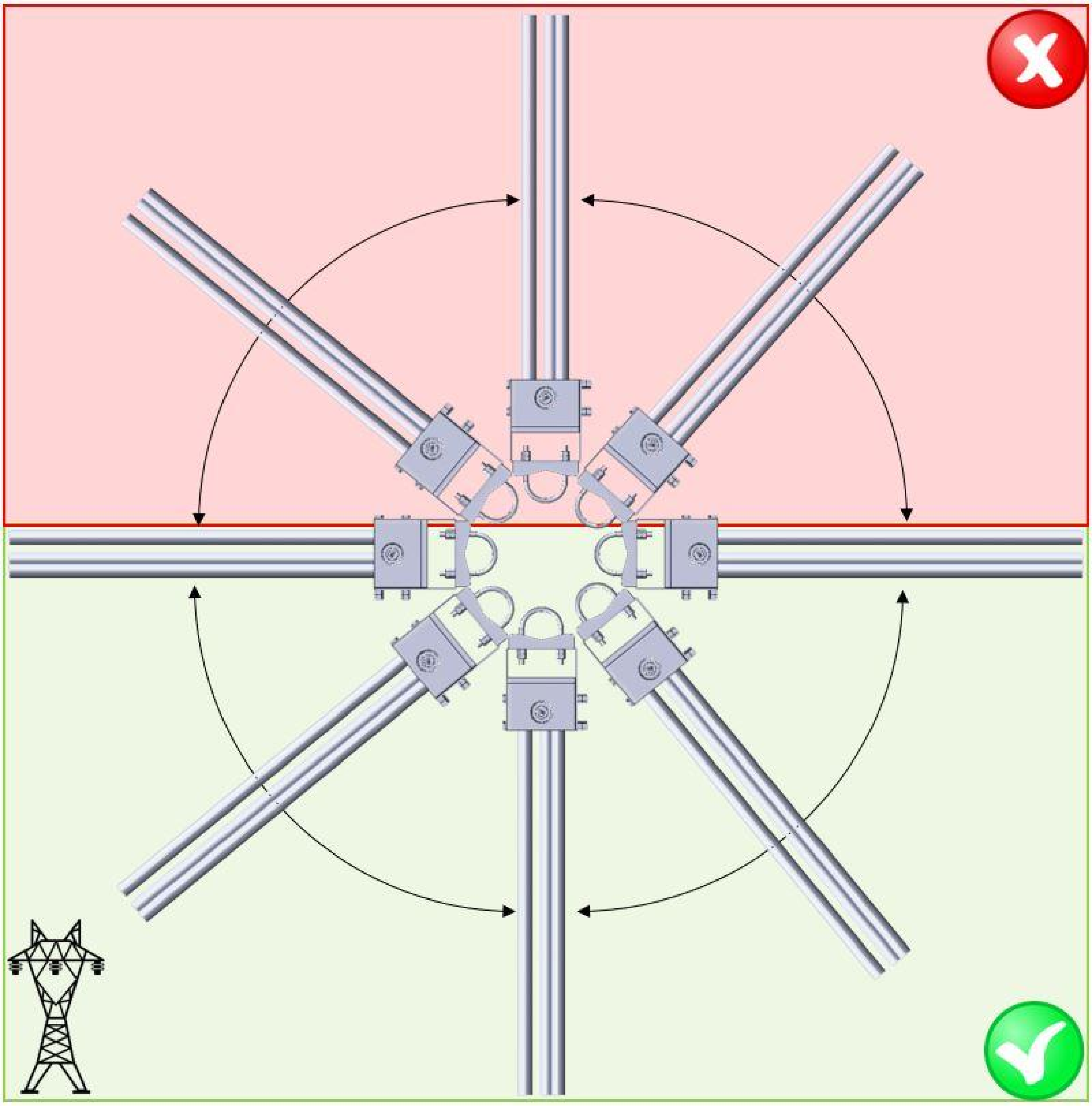
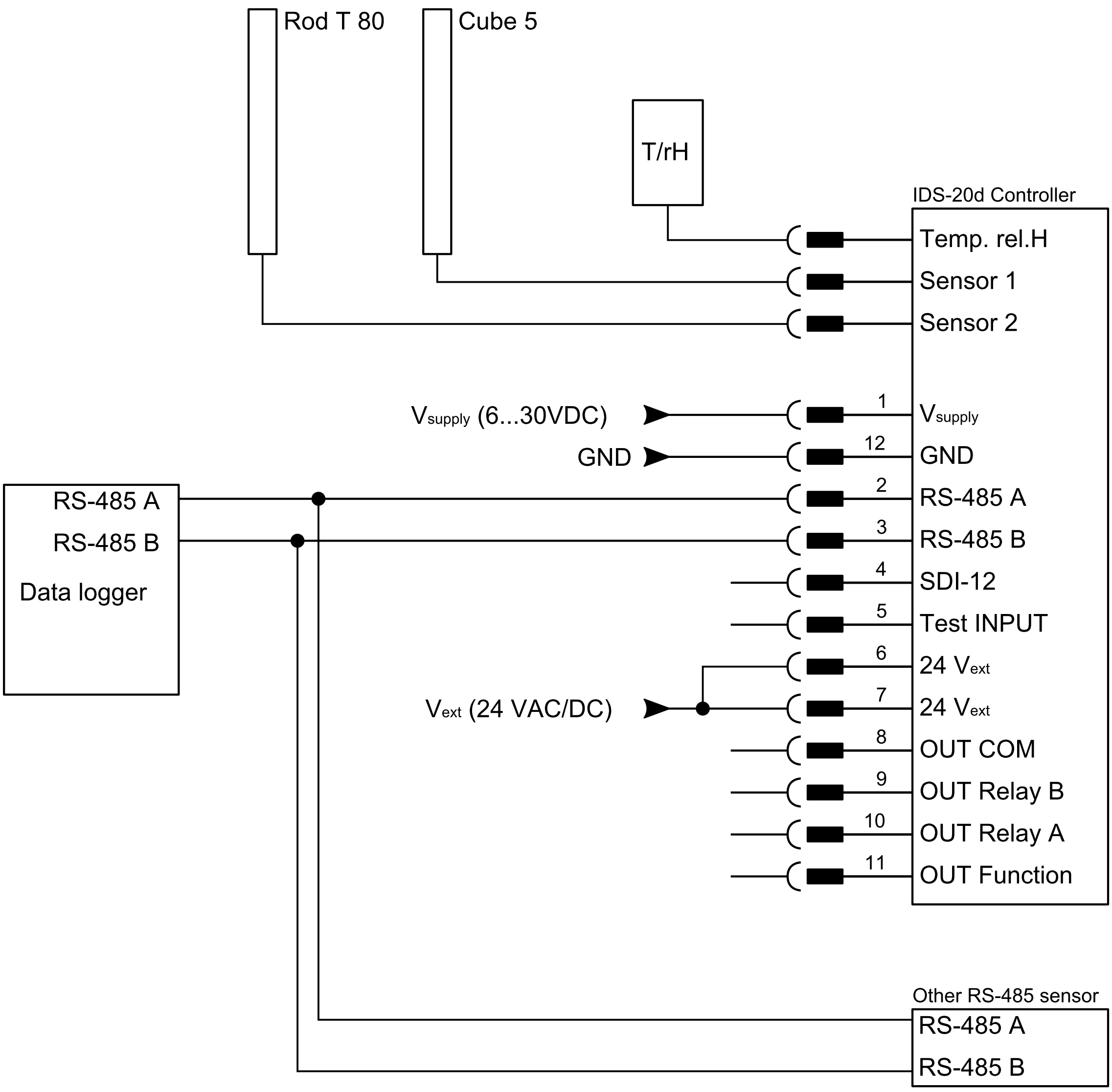


Figure 8 Positioning of Rod-80 sensor

7.5 Wiring

7.5.1 RS-485 wiring

Connect the IDS-20d to a data logger or RS-485 network according to the figure below.



7.5.2 SDI-12 wiring

Connect the IDS-20d to a data logger by SDI-12 according to the figure below.

SDI-12 uses a shared bus with a ground wire, a data wire (indicated as SDI-12) and an optional +12 V wire.

NOTE The connection with the 12 V power supply is optional and depends on the connected SDI-12 master device (typically a data logger).

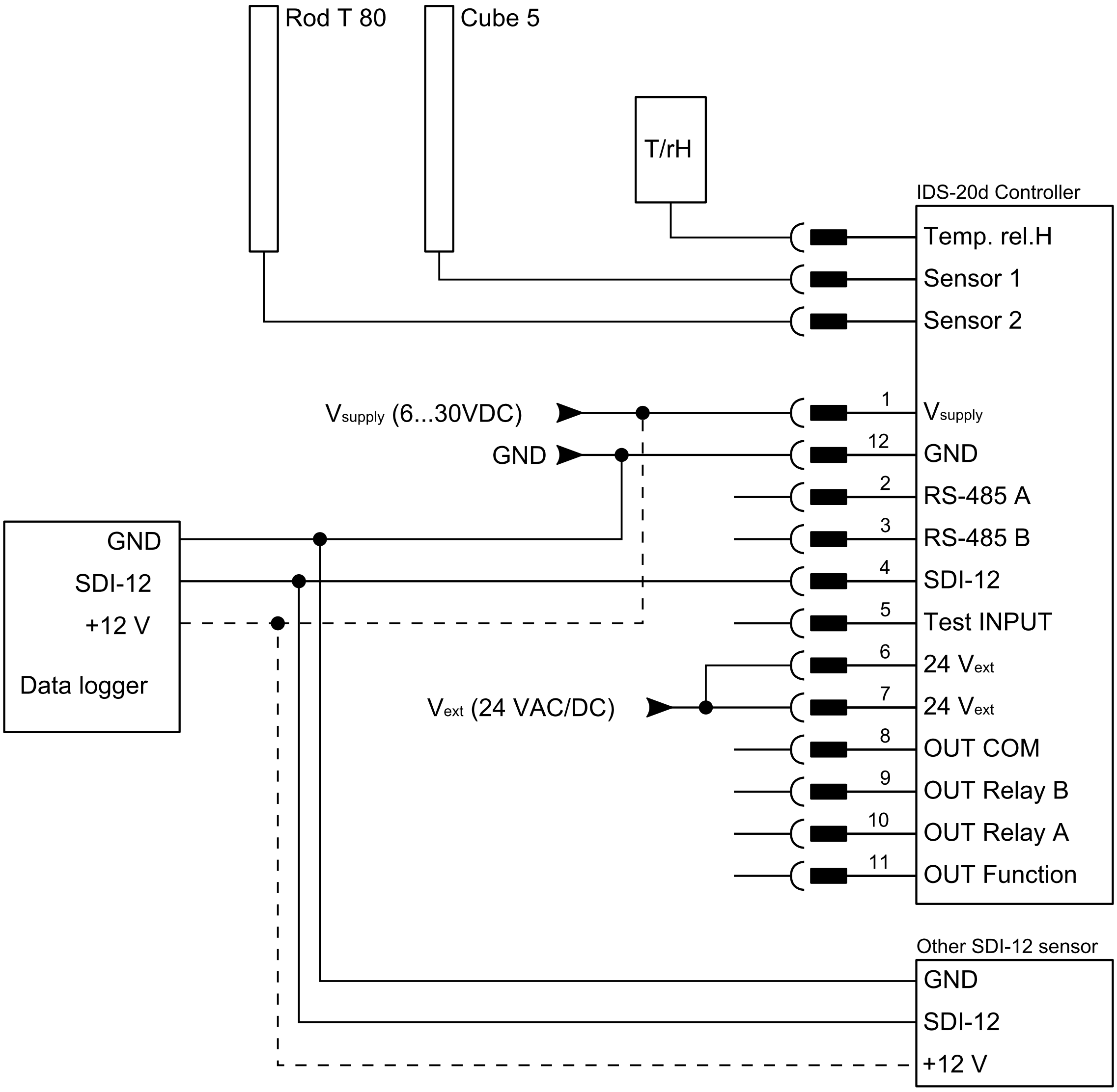


Figure 9 Wiring of the IDS-20d with a data logger via SDI-12

7.6 Start-up

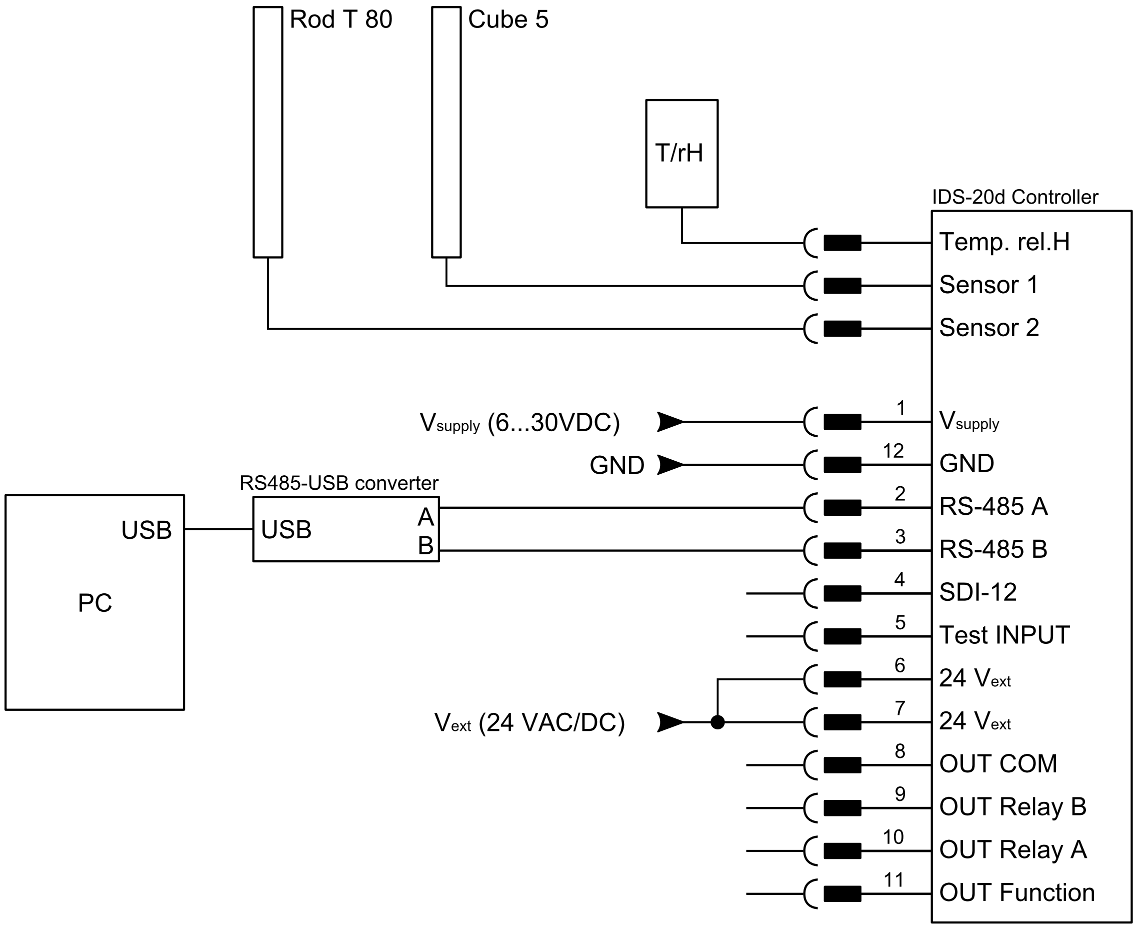
After successful testing, verify that the measurement data are recorded by your data acquisition system and check the data transmission to the remote server if applicable.

8 Operation

8.1 Connect device to PC

1. Install the Commander support software (see Installation of Commander).
2. Connect the yellow and gray wires of the sensor cable to the RS-485 to USB converter cable and plug it into your PC as illustrated in the figure below.
3. Connect a 9...28 VDC power supply to the IDS-20d as shown in the figure below.
4. Click on Communication assistant on the right-hand side of the Commander window and follow the instructions.
    a. As Type of connection select *Serial connection*
    b. As Device type select *Sensor (9600 Bd)*
    c. Select New connection and select the COM port

   During this procedure the communication assistant will search for connected devices. Upon successful completion, the new connection is added to the connections list (tab Connections (F8)).
5. In the Communication section at the right-hand side of the Commander window select Mode Connection and the previously created connection from the drop-down list.
6. Click Connect to establish a connection with the IDS-20d. If the connection was successful a green icon is displayed at the top-right corner of the Commander window.
7. Select the tab Parameters (F2) and click Download parameters from device on the left side of the Commander window. The complete parameter list is transferred from the sensor to your PC and displayed in the Parameter window.



To activate the communication between your device and the Commander software follow the steps described in Working with connections.

9 Maintenance

The IDS-20d generally does not require any special maintenance. However, the ice-monitoring system should be inspected regularly for any damage or soiling on the Cube 5 sensor and any dirt on the tip of the T/rH-sensor. If required, the sensor head and rods can be cleaned with water.

It is recommended to compare the temperature measurements of the ice-sensors and the T/rH-sensor regularly. Any offset can be corrected in the IDS-20d setup section Technics. If the temperature offset should be too large, a sensor recalibration is recommended.

10 Support software Commander

10.1 Software features

The Commander is a multipurpose software tool to configure and operate any Sommer Messtechnik device. It offers the following functions:

- Communication with Sommer Messtechnik sensors and data loggers via serial connection, modem, socket, IP-call and Bluetooth®
- Management of connections and stations
- Configurations of sensors and data loggers
- Live data monitoring and storage
- Data management including download from data loggers and transmission to MDS (Measurement Data server)
- Terminal window to check data transfer and to access device settings directly

10.2 System requirements

The Commander software supports 32- and 64-bit versions of Windows 7 SP1, Windows 8, Windows 8.1, Windows 10 and Windows 11.

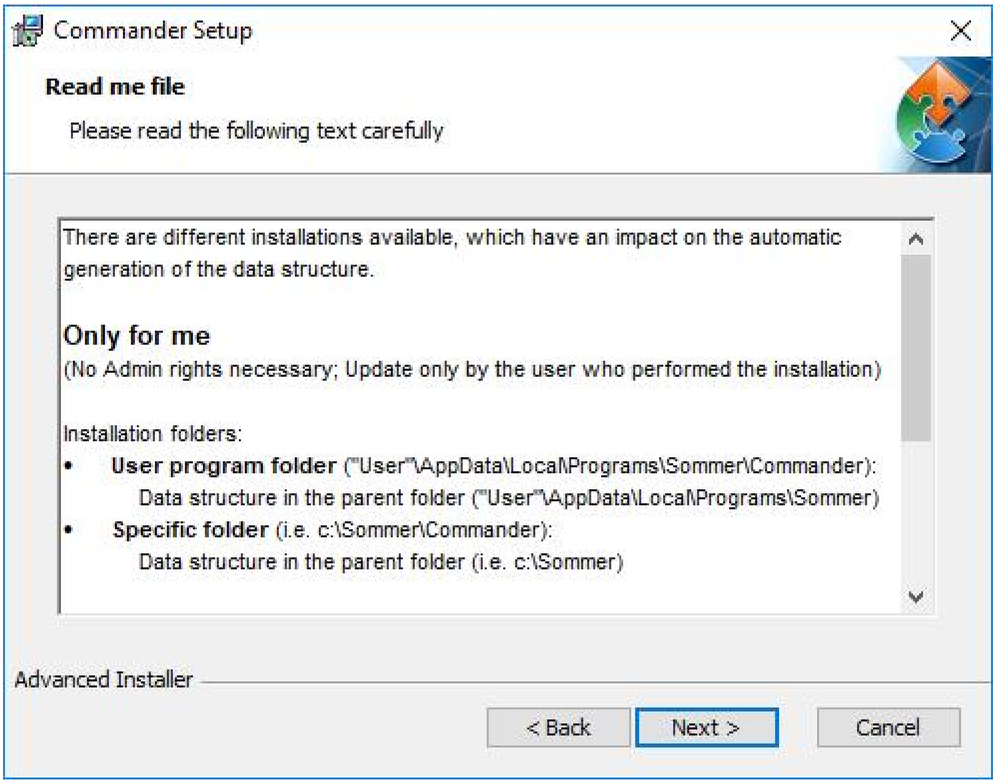
For correct operation Microsoft® .NET Framework 4.5 or later must be installed.

10.3 Installation of Commander

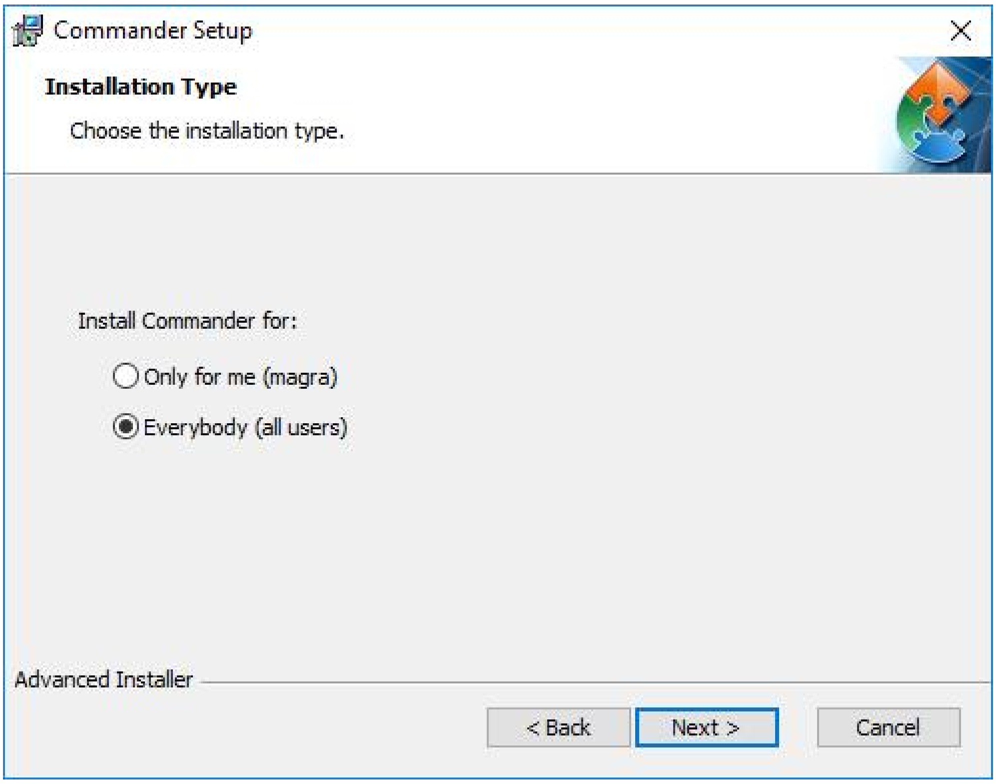
Follow the steps below to install the Commander software:

1. Plug the USB stick shipped with the device into your PC.
2. Double-click the commander.msi installer file on the USB drive.
3. Click Next on the pop-up window

4. Read the instructions and click Next



5. Select the installation type and click Next



NOTE

Two installation types are available. Depending on the selection, the access rights and the folder structure differ:

Only for me

No admin rights are required. Updates are only available to the user who installed the software.

Installation folders:

- User program folder:
  Users\User\AppData\Local\Programs\Sommer\Commander
  Data structure:
  Users\User\AppData\Local\Programs\Sommer
- Specific folder (default):
  C:\Sommer\Commander
  Data structure (default):
  C:\Sommer

Everybody

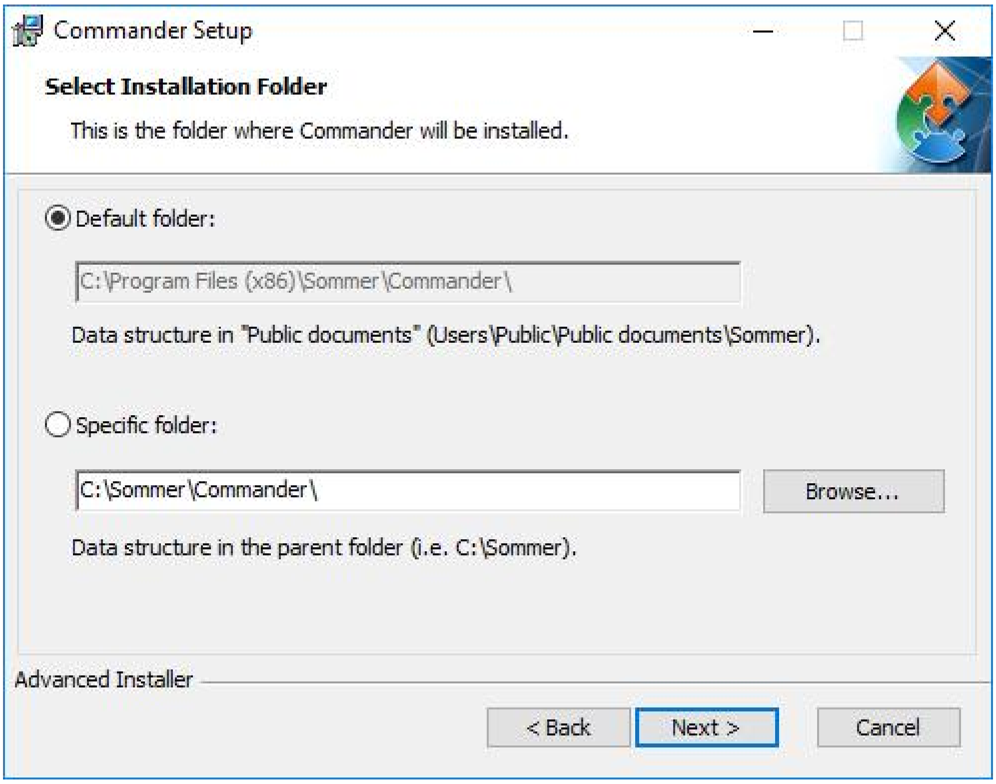
Admin rights are required. Updates may only be performed by system administrators.

Installation folders:

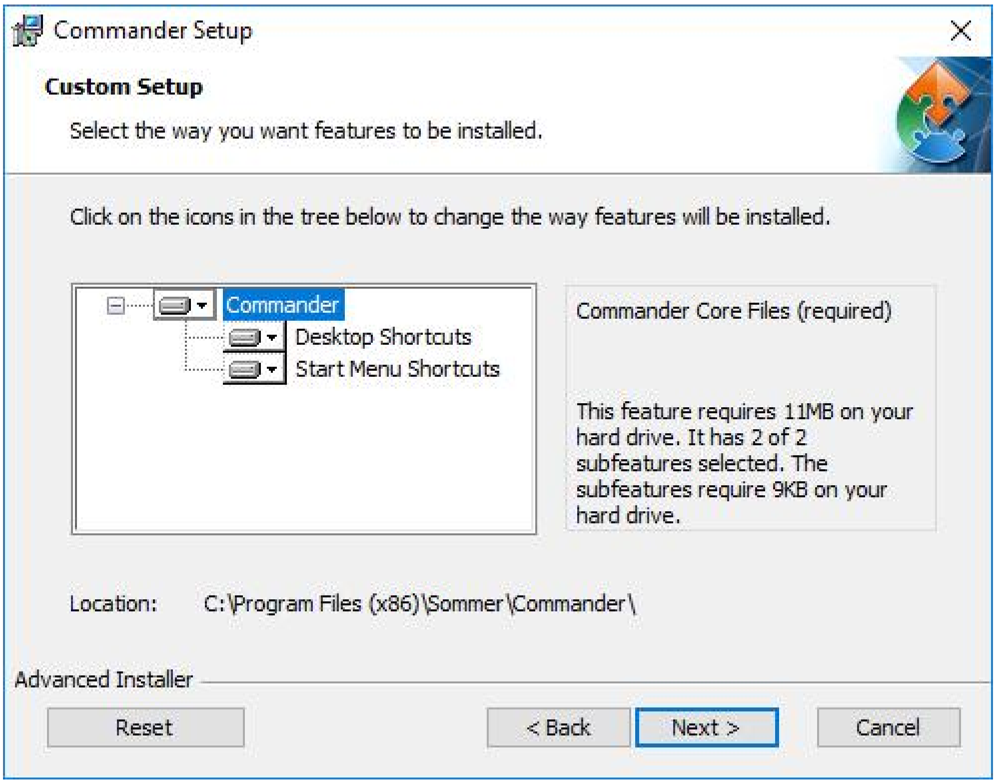
- Standard program folder:
  Program Files (x86)\Sommer\Commander

> Data structure:
> Users\Public\Public documents\Sommer
>
> - Specific folder (default):
>   C:\Sommer\Commander
>   Data structure (default):
>   C:\Sommer

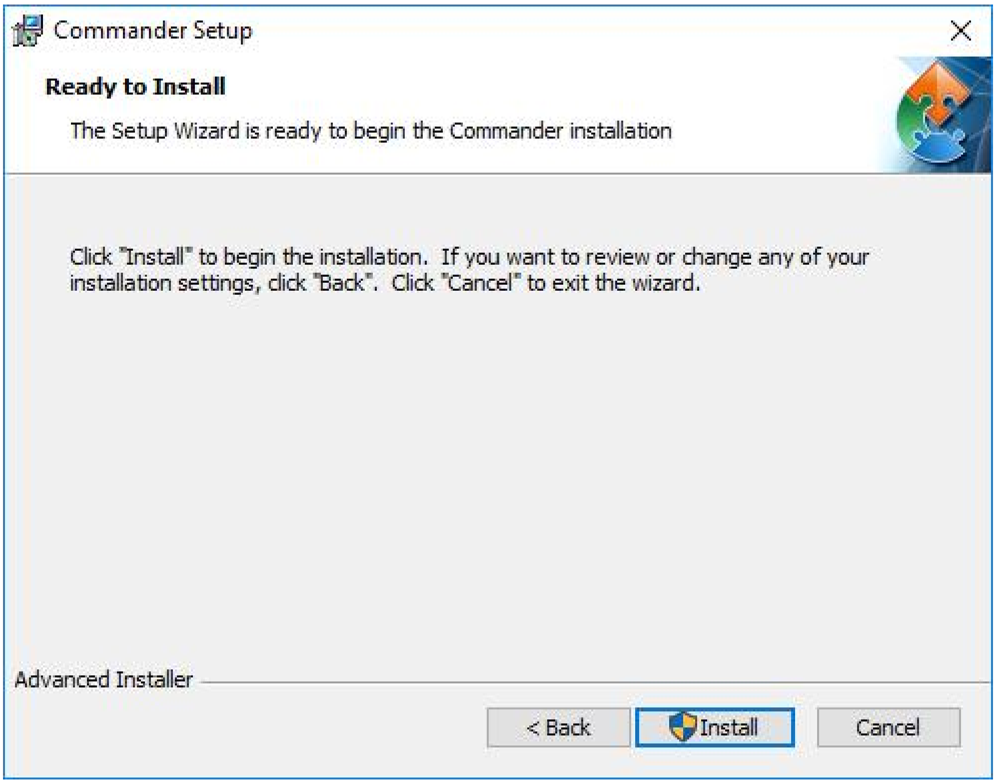
6. Select the installation directory and click Next.



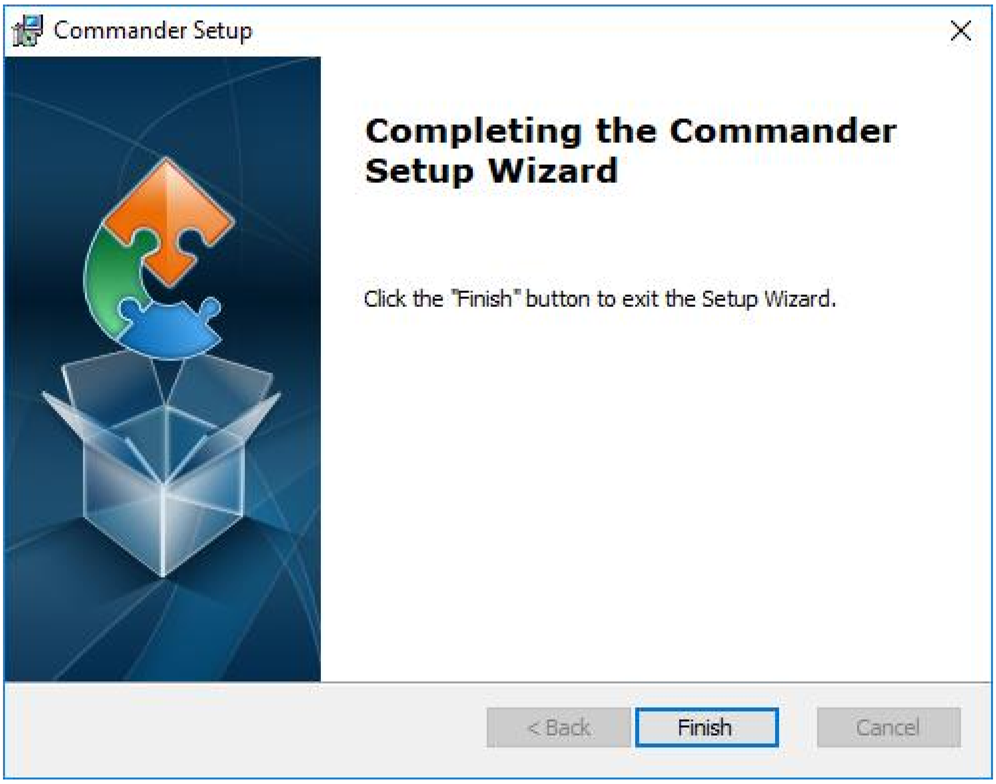
7. Select the features to be installed and click Next.



8. Click Install to start the installation.



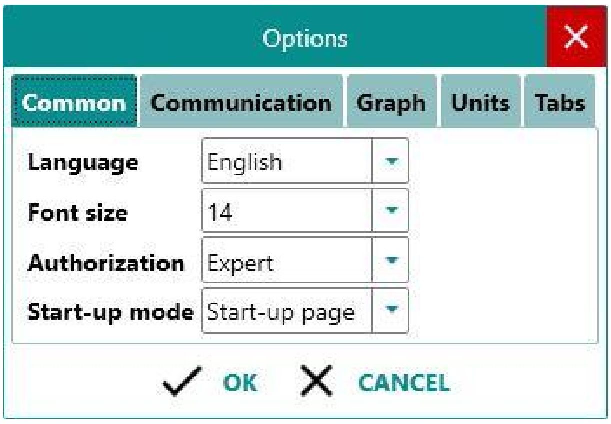
9. Click Finish to complete the installation.



10.4 Change authorization

To prevent unintended changes of parameters in the Technics menu authorization is generally set to *Normal*. Parameter modifications in Technics are enabled by switching the authorization level to *Expert* as described below:

1. On the upper tab bar click on Options and select Common.
2. In the Options window select authorization *Expert* and click OK.



10.5 Working with connections

10.5.1 Establish a connection with the Communication assistant

1. Install the Commander support software as described in Installation of Commander.
2. Connect the device to your PC.
3. Start the Commander software on your PC.
4. Click on Communication assistant on the right-hand side of the Commander window and follow the instructions. During this procedure the communication assistant will search for connected devices. Upon successful completion, the new connection is added to the connections list (tab Connections (F8)).
5. In the Communication section at the right-hand side of the Commander window select Mode Connection and the previously created connection from the drop-down list.
6. Click Connect to establish a connection with the IDS-20d. If the connection was successful a green icon is displayed at the top-right corner of the Commander window.

To view the settings of the connected device or to read the current measurements, follow the steps described in Download setup and Record measurements.

10.5.2 Establish a connection manually

1. Install the Commander support software as described in Installation of Commander.
2. Connect the device to your PC.
3. Start the Commander software on your PC.
4. Select the required connection in the Connections list of the Connections (F8) tab and click Connect. If the connection was successful a green icon is displayed at the top-right corner of the Commander window.
   If you don't have the required connection available in the Connections list, create a new connection as described in Create a new connection.

To view the settings of the connected device or to read the current measurements, follow the steps described in Download setup and Record measurements.

10.5.3 Create a new connection

1. Select the Connections (F8) tab in the Commander.
2. Click New connection.
3. In the section Connection settings enter a name of the new connection, e.g. *Serial-com1-9600*, and the connection type, e.g. *Serial connection*.

4. Enter the required information for the selected connection type.
   If your IDS-20d is wired to your PC with a RS-485 to USB converter cable, select the port where the device is connected and select a Baud rate of 9800.

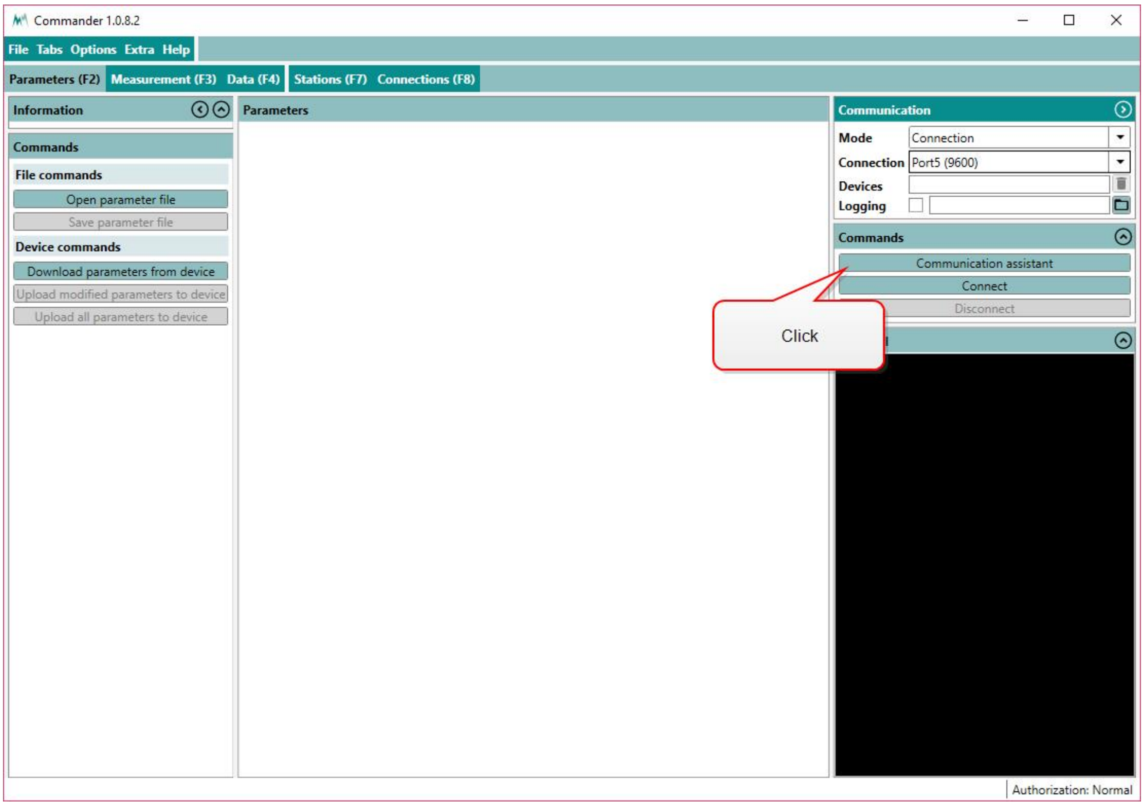
10.6 Working with stations

10.6.1 Create a station with the Communication assistant

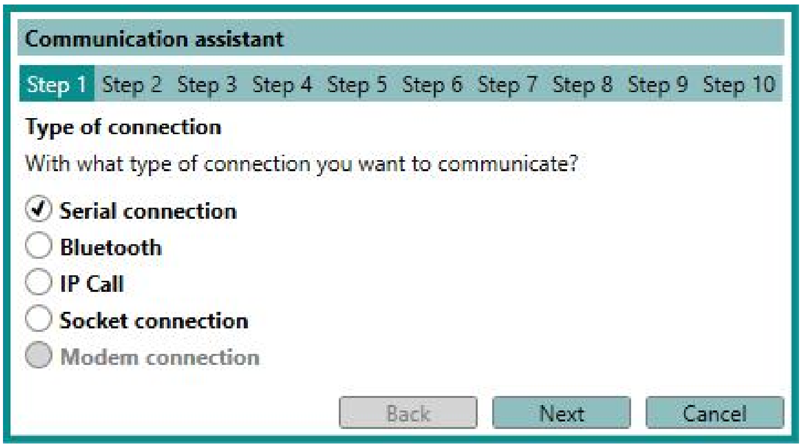
In order to manage several data loggers, to connect to a data logger via IP-call and to download data, stations can be created in the Commander software. To view a list of all stations select the tab Stations (F7).

Perform the following steps to create a new station with the Communication assistant:

1. Click on Communication assistant in the Commander-window

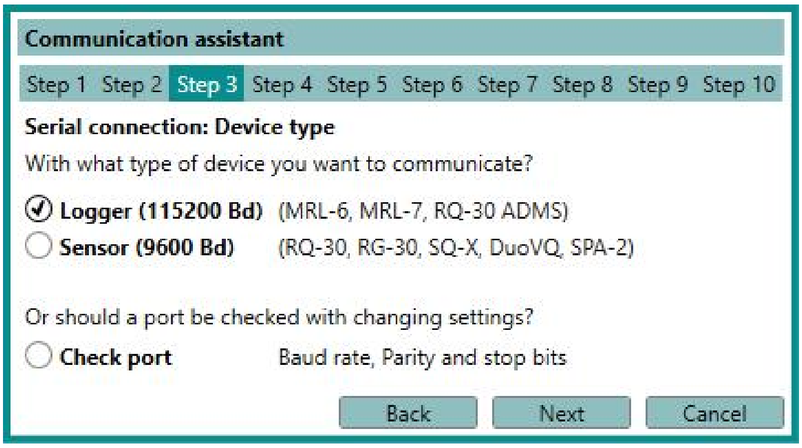


2. In the pop-up window choose the required connection and click Next.

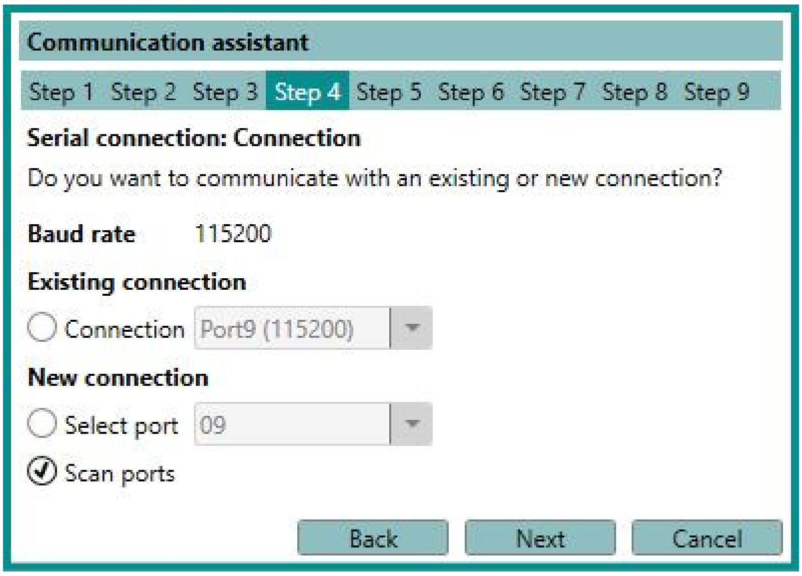


3. Verify that the IDS-20d is connected to your PC and a power supply. Click Next.

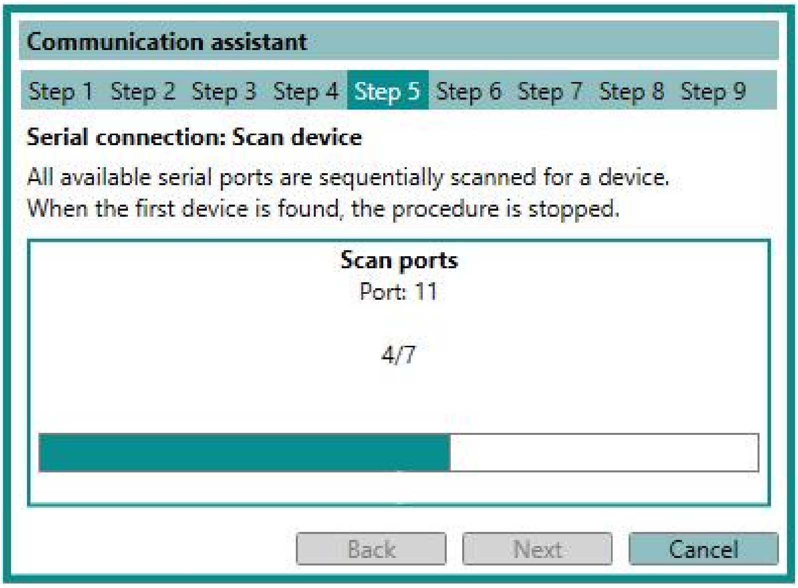
4. Select *Logger (115200 Bd)* and click Next.



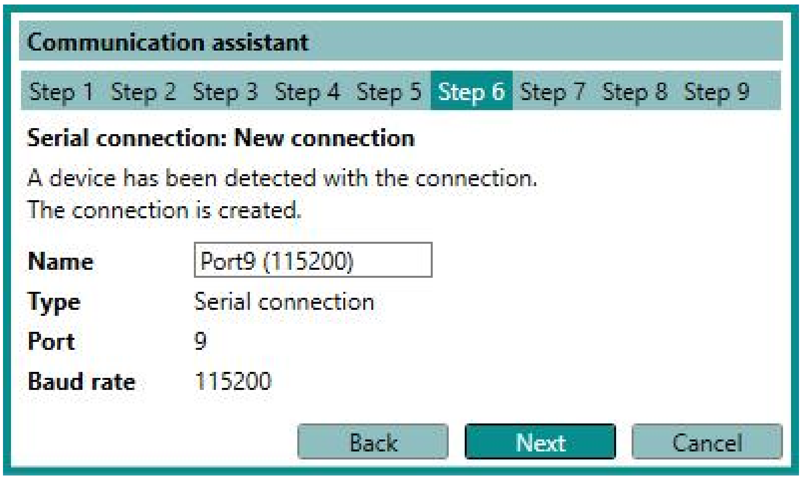
5. Select *Scan ports* and click Next.



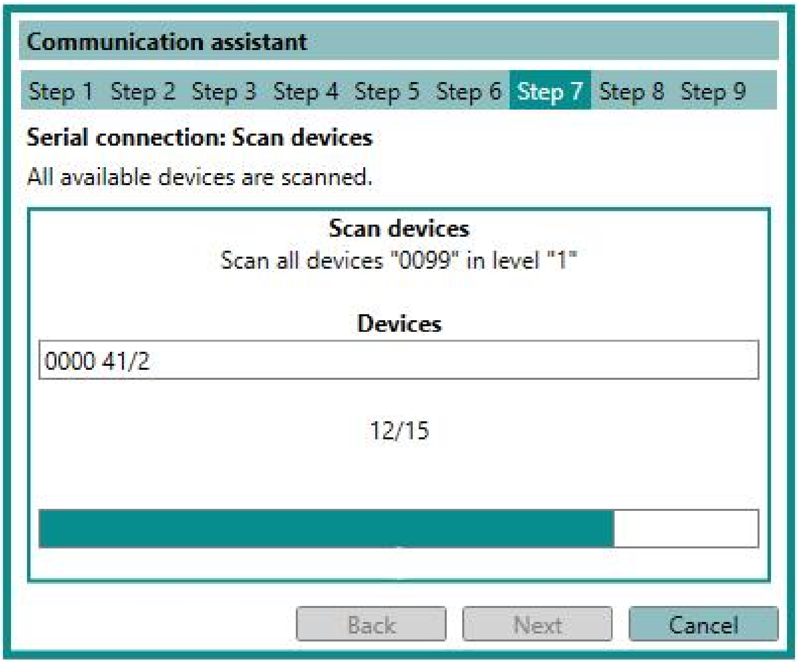
6. The Commander now scans all available ports.



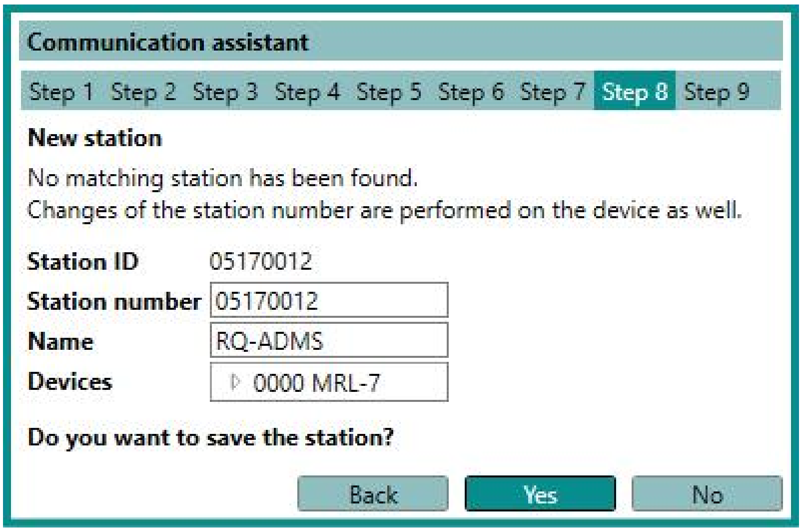
7. Adopt the *Name* provided by the communication assistant. Click Next.



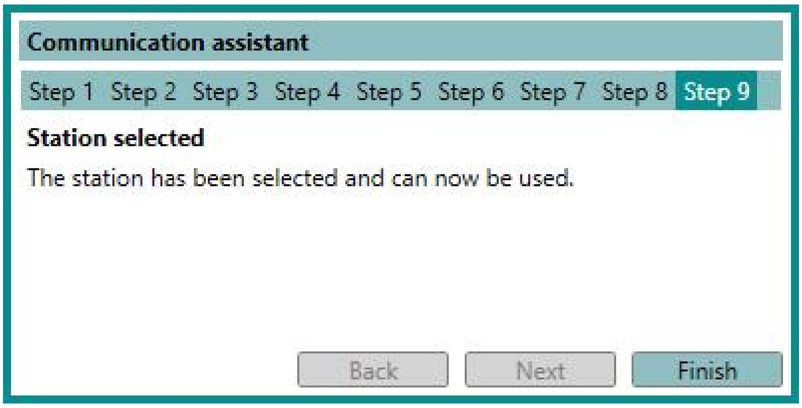
8. The Commander now scans the selected port for connected devices.



9. Adopt the *Name* of the new station or enter a new name. Click Next.



10. A new station has now been created. Click Finish.



11. The newly created station can now be selected in the Communication section of the Commander. Click Connect to activate the connection to your device.

10.6.2 Create a station manually

In order to manage several data loggers, to connect to a data logger via IP-call and to download data, stations can be created in the Commander software. To view a list of all stations select the tab Stations (F7).

Perform the following steps to create a new station:

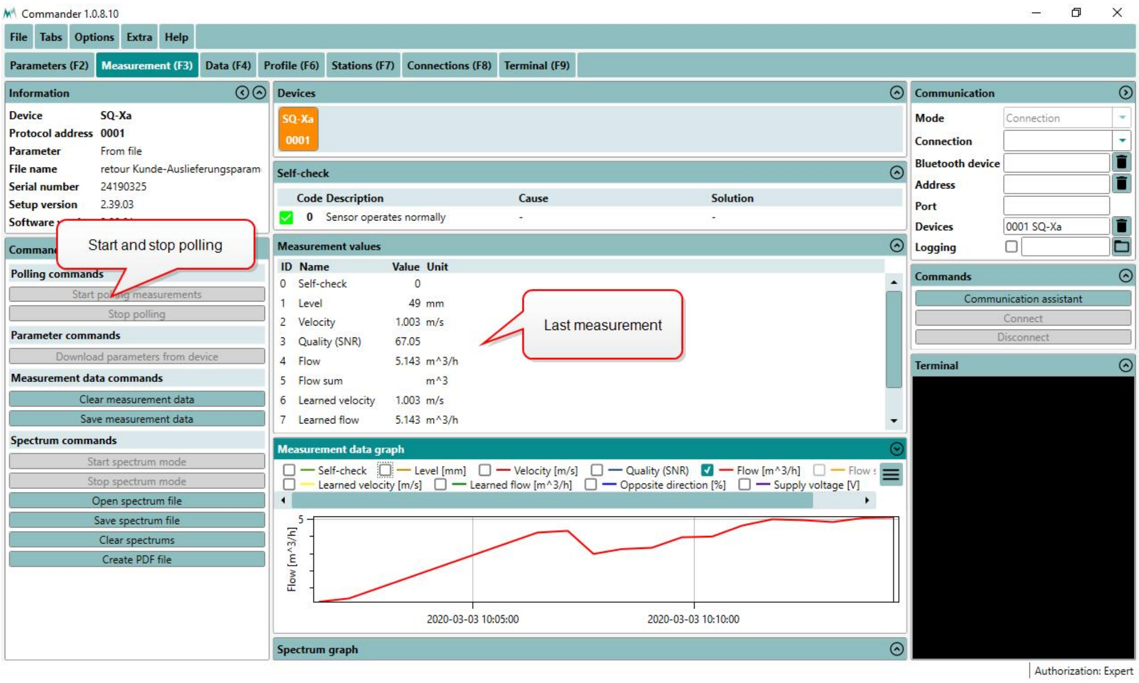
1. In the tab-menu Stations (F7) click New station.
2. Under Station settings enter the Station number and Sommer ID. By default both settings are set to the device's serial number (visible on the IDS-20d housing).
3. Select the Connections used for the station. Multiple selections are possible; the default connection can be selected by ticking the circular field.
4. Depending on the connection type, enter the additional information, e.g. Address for a Bluetooth connection or IMSI number for an IP call.

5. Enter the settings for Data management.When data are downloaded from a connected IDS-20d they are stored in an archive-file by default. Each archive-file contains the data of a year or month, as selected in Archive type. Selection *None* will save all data in one file.The default location for data files is C:\Users\Public\Documents\Sommer\Data\.
6. Save the newly created station with the button Save station.

10.7 Working with measurements

10.7.1 Poll continuous measurements

1. Establish a connection to your device as described in Working with connections.
2. Download the setup of your device as described in Download setup.
3. Select the Measurement (F3) tab.
4. In the Commandssection click Start polling measurement.
5. Select the option Polling with measurements. Now, the Commander will trigger measurements of the IDS-20d without any delays between measurements. The results are displayed Measurement values and plotted in the Measurement data graph.
6. To finish polling mode click Stop polling.



NOTE The polling mode stops automatically after 30 minutes.

10.7.2 Record measurements

1. Establish a connection to your device as described in Working with connections.
2. Download the setup of your device as described in Download setup.
3. Select the Measurement (F3) tab.
4. Make sure that Measurement output is set to *Measured values push* or *Storage values push*.
5. If the connection with your device is active, the data will now be displayed in the measurement table and updated at the interval specified in the setup. Also, the incoming data strings are displayed in the Terminal.
6. Click Save measurement data in the Commands section to save the recorded measurements. The data are saved as a *.csv file in the SommerXF format.

NOTE You can change the scope of the data output in the setup Information.

10.8 Working with data

10.8.1 View live data

Follow the steps below to view live data acquired from your device:

1. Establish a direct or remote connection with the IDS-20d using the Commander. Use an existing Commander-connection or -station if available.
2. In the Parameters (F2) tab download the parameters of the IDS-20d.
3. Now, there are two options to view the measurement data:
    1. If Measurement output is set to *Measured values push* or *Storage values push*, data are displayed in the Measurement (F3) tab in the specified measurement interval.
    2. Open the Measurement (F3) tab and click Start polling measurements. With this option measurements are triggered in the fastest possible sequence and the results are displayed instantly. This measurement mode can be stopped by clicking Stop polling, or it is finished automatically after 30 minutes.

10.9 Working with spectra

10.9.1 Record spectrum

1. Establish a connection to your device as described in Working with connections.
2. Download the setup of your device as described in Download setup.
3. Select the Measurement (F3) tab.
4. Click Start spectrum mode in the Commands section. Now the Commander collects the spectrum data and displays them in Spectrum graph.

> **NOTE** The collection of the spectrum data may require some time.

5. Click Save spectrum file in the Commands section to save the recorded spectra. The data are saved as a *.xlms file.

> **NOTE** The number of acquired spectra is displayed at the bottom of the Spectrum graph. You can navigate through the spectra by clicking the navigation buttons.

6. Click Stop spectrum mode to quit recording spectra.

10.9.2 Read spectrum file

1. Open the Commander.
2. Click Open spectrum file in the Commands section.
3. Select the desired spectrum file (*.xmls) and click Open. The spectra are now opened and displayed in the Spectrum graph.

> **NOTE** The number of acquired spectra is displayed at the bottom of the Spectrum graph. You can navigate through the spectra by clicking the navigation buttons.

10.10 Working with setups

10.10.1 Download setup

1. Establish a connection to your device as described in Working with connections.
2. Select the Parameters (F2) tab in the Commander software.
3. In the Commands section click Download parameters from device.
   The Commander now downloads the setup currently active on the IDS-20d. This may take some time if you are downloading the setup for the first time to your PC. Consecutive downloads of a setup with the same version number will be faster as the parameter structure is already available.

You can now save the setup file by clicking Save parameter file, or edit the settings as described in Edit setup.

> **TIP** Save the setup on your PC before you make any changes!

10.10.2 Open a setup file

1. Start the Commander on your PC and connect to your IDS-20d either directly with the USB to RS485 isolated converter cable or, if available, the optional Bluetooth connection.
2. Open the Parameters (F2) tab and click Open parameter file. Select the required file (extension .xmld or .xmla).
3. Verify the new settings and click Upload all parameters to device. After completion the new settings are active on your data logger.

10.10.3 Edit setup

1. Open the setup file as described in Open a setup file or download it from your device as described in Download setup.
2. Adapt the values of the settings in question and press Enter after each. After you have changed a value, its text box will turn red.

   > **NOTE** If you have entered a value outside the data range of the setting, it will be forced to the next valid value! The valid range of each setting is listed in the Parameter definitions.

3. After you have adapted all required settings save the setup file and/or upload the setup to your device by clicking Upload modified parameters to device.
   Once the setup has been saved or uploaded, the modified red text boxes will turn white again, indicating that the settings have been saved/applied.

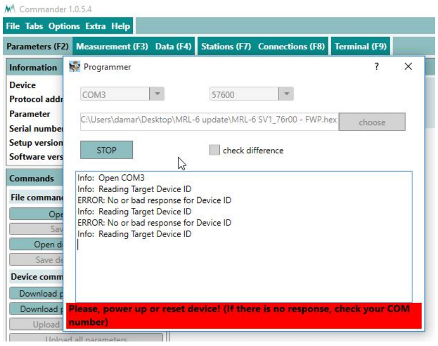
10.10.4 Upload new setup file

1. Establish a connection to your device as described in Working with connections.
2. Select the Parameters (F2) tab.
3. Download the setup currently on the IDS-20d as described in Download setup and save it by clicking Save parameter file. This step is recommended to have the latest setup available for documentation.
4. Click Open parameter file and select the required setup file (*.xlmd) on your PC.
5. Click Upload all parameters to device. This transfers the current setup to the IDS-20d.
6. To verify the correct upload click Dowanload parameters from device. This will display the present setup of the IDS-20d.

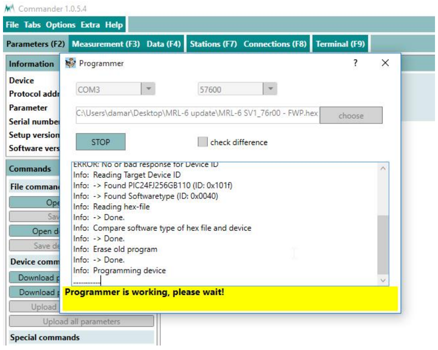
10.11 Update firmware

1. Connect the IDS-20d to your PC with the USB to RS485 isolated converter cable.
2. Make sure no connection is active in the Commander (no green icon at the top-right corner).
3. Click on the menu item Extra and select Start Programmer.
4. Select the firmware file (*.hex) provided by SOMMER Messtechnik. Make sure the file is stored on your PC and not on a USB or network drive.
5. Choose the COM-port the data logger is connected to and a Baud-rate of 57'600.
6. Perform the following three steps in short sequence:
   - Click Program
   - Unpower the data logger
   - Wait 3…5 seconds to enable full activation of the bootloader and a correct restart (capacitors must be discharged, and if the device had been in sleep mode, this can take some time)
   - Repower the data logger

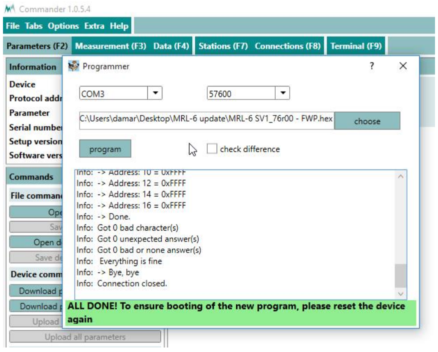
   The firmware currently present on the data logger is now erased and the new one copied to the data logger. During the update process the pop-up window may show the following messages:



The programmer is not ready; power needs to be on.



The programmer is active.



The firmware update has finished.

7. Close the programmer-window as soon as the firmware update has finished.
8. Switch off and repower the data logger again.
9. Open the Parameters (F2) tab.
10. Click Download parameters from device. The download of the new parameter list might take a few minutes as the parameter structure may need to be downloaded as well. After completion the new firmware and setup versions will be displayed in the Information section.

11 Configuration of the IDS-20d

11.1 Software tools

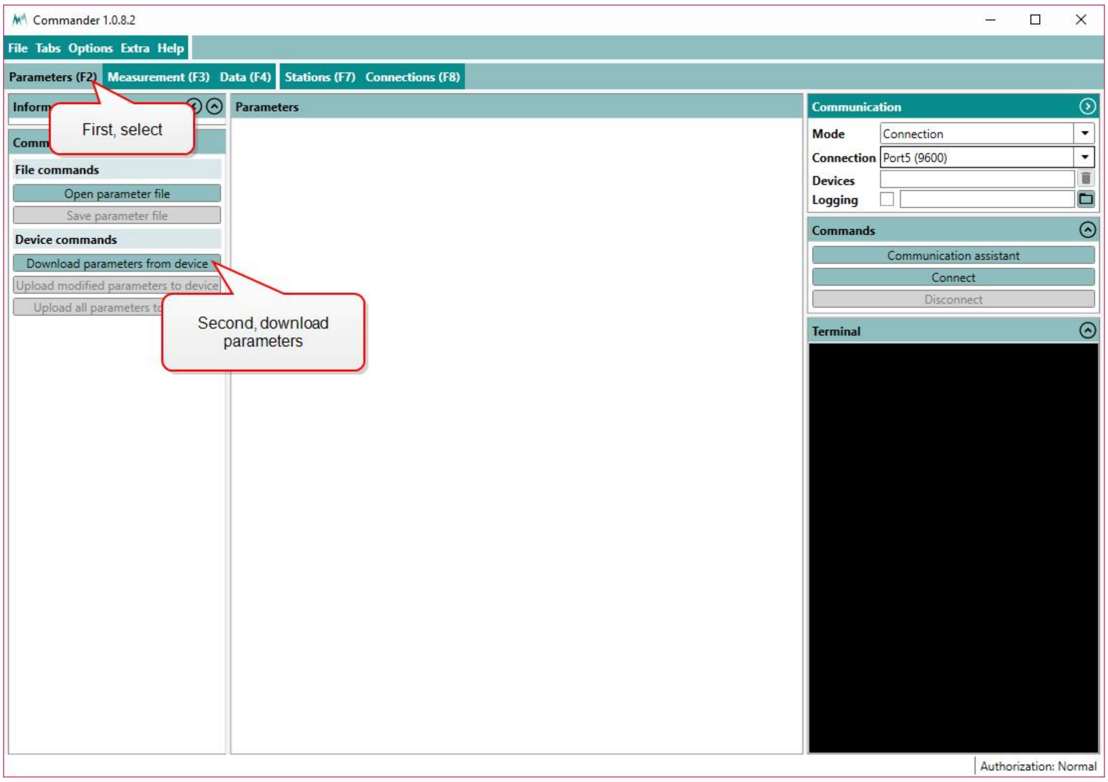
The IDS-20d can be configured with one of the following tools:

- Configuration with Commander support software
- Configuration with a terminal program

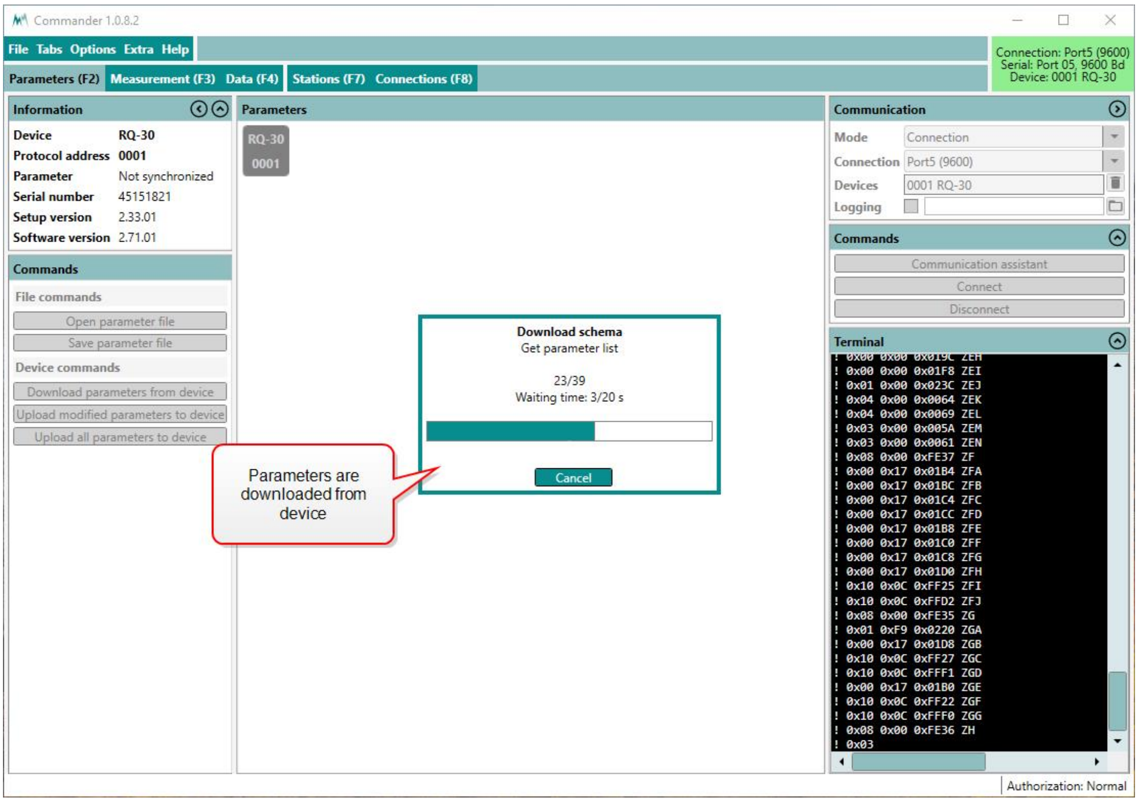
11.2 Configuration with Commander support software

Follow the steps below to modify the configuration parameters of the IDS-20d:

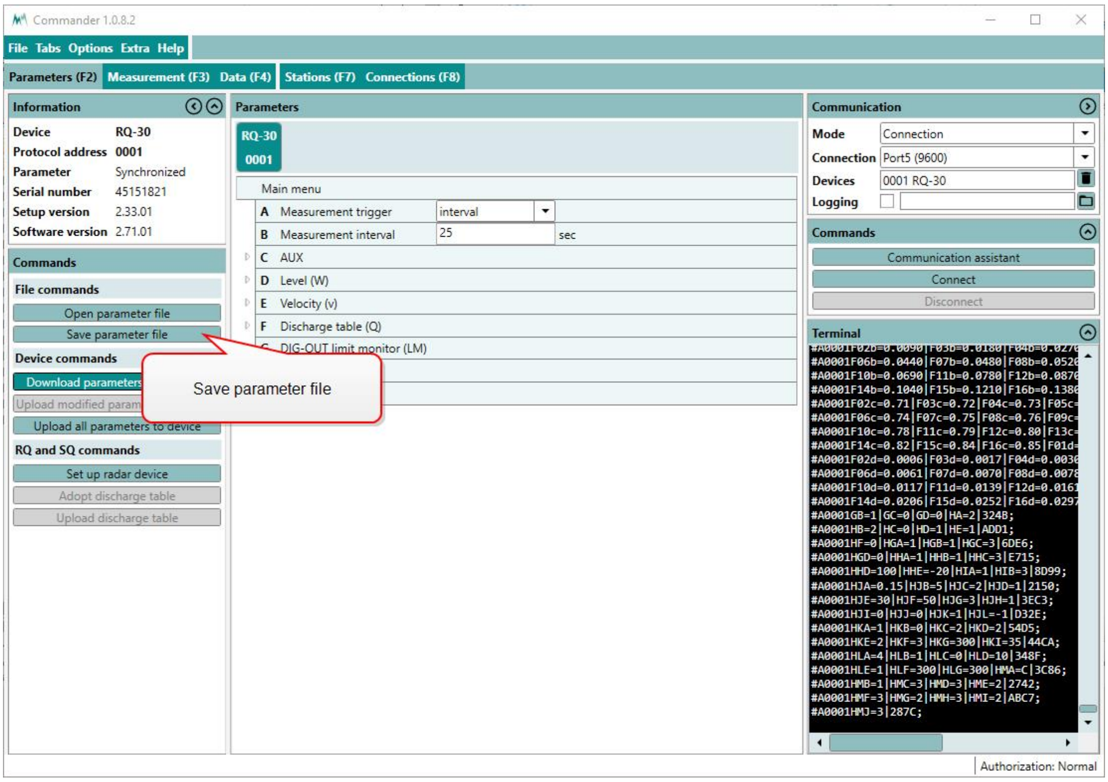
1. Establish a connection between your PC and the IDS-20d.
2. Select the tab Parameters (F2) and click Download parameters from device. The complete parameter list is transferred from the sensor to your PC and displayed in the Parameter window.



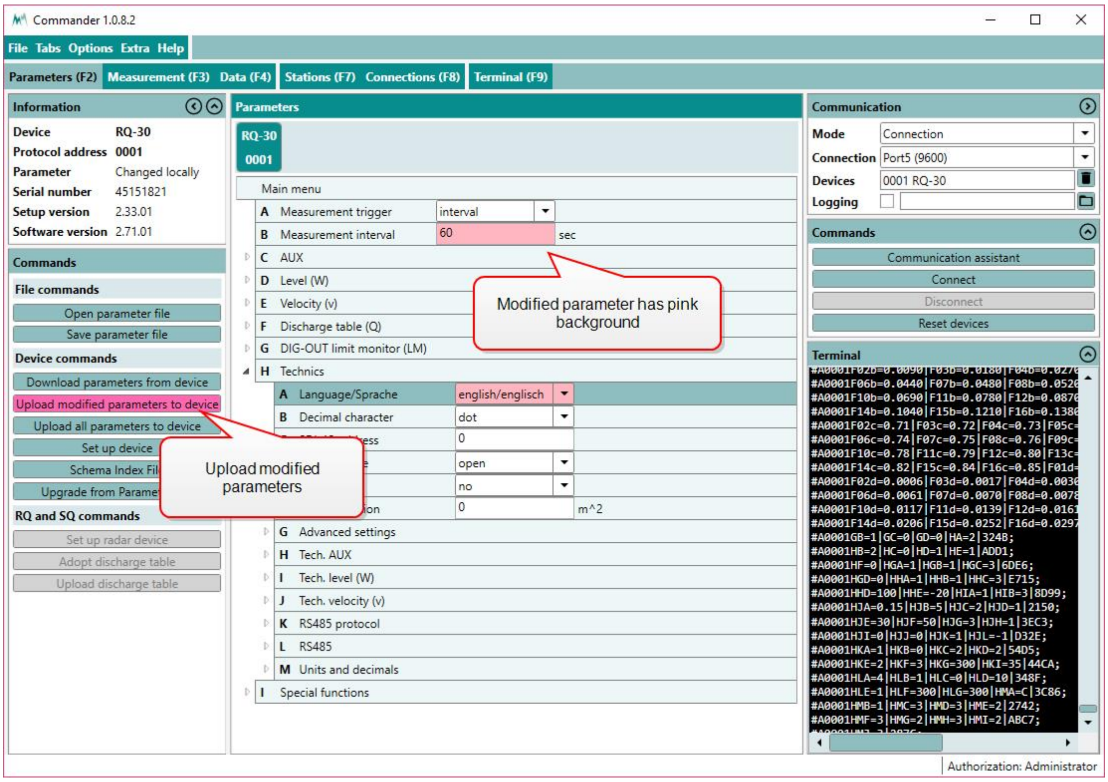
NOTE The first download of the parameter list may take a few minutes. After that the device is known to the PC and consecutive downloads are much faster.



3. Save the parameter file to your PC by clicking Save parameter file. This step is recommended to track any configuration changes.



4. Adapt the parameters required for your application. Changed values are displayed with a pink background.



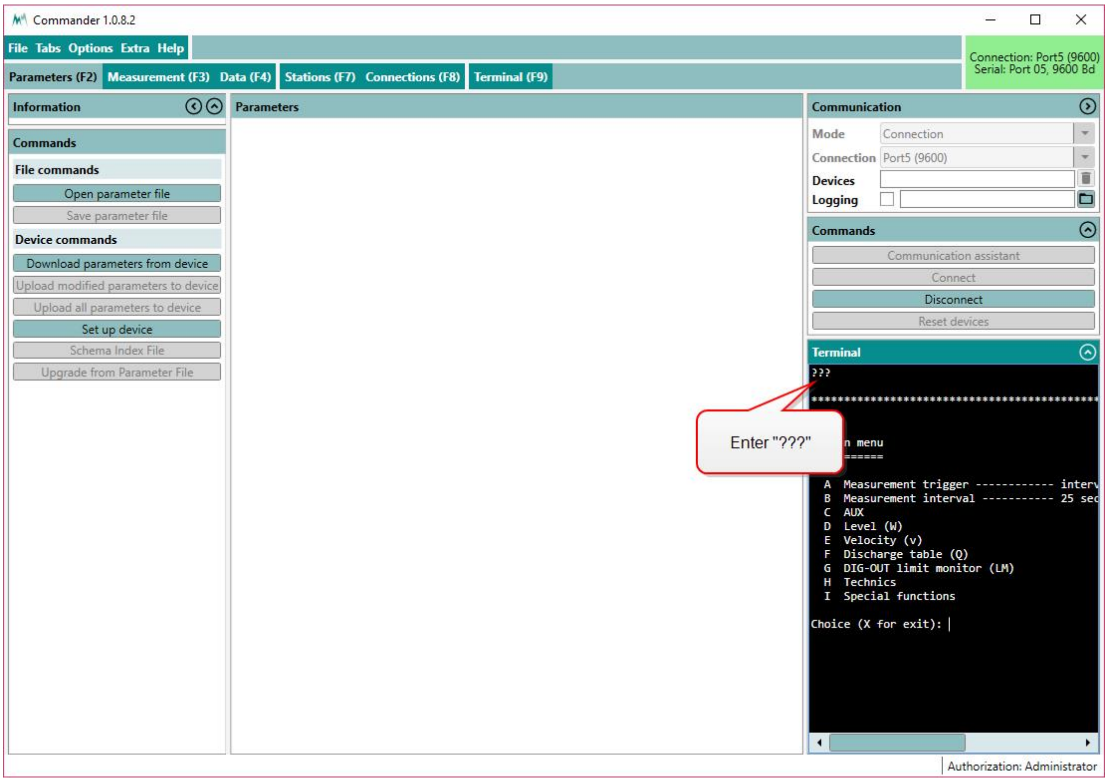
5. Send the modifications to the IDS-20d by clicking Upload modified parameters to device. Upon successful upload the pink backgrounds disappear again.

11.3 Configuration with a terminal program

The Commander software ships with an integrated terminal program. However, communication with the IDS-20d can be performed with any terminal program.

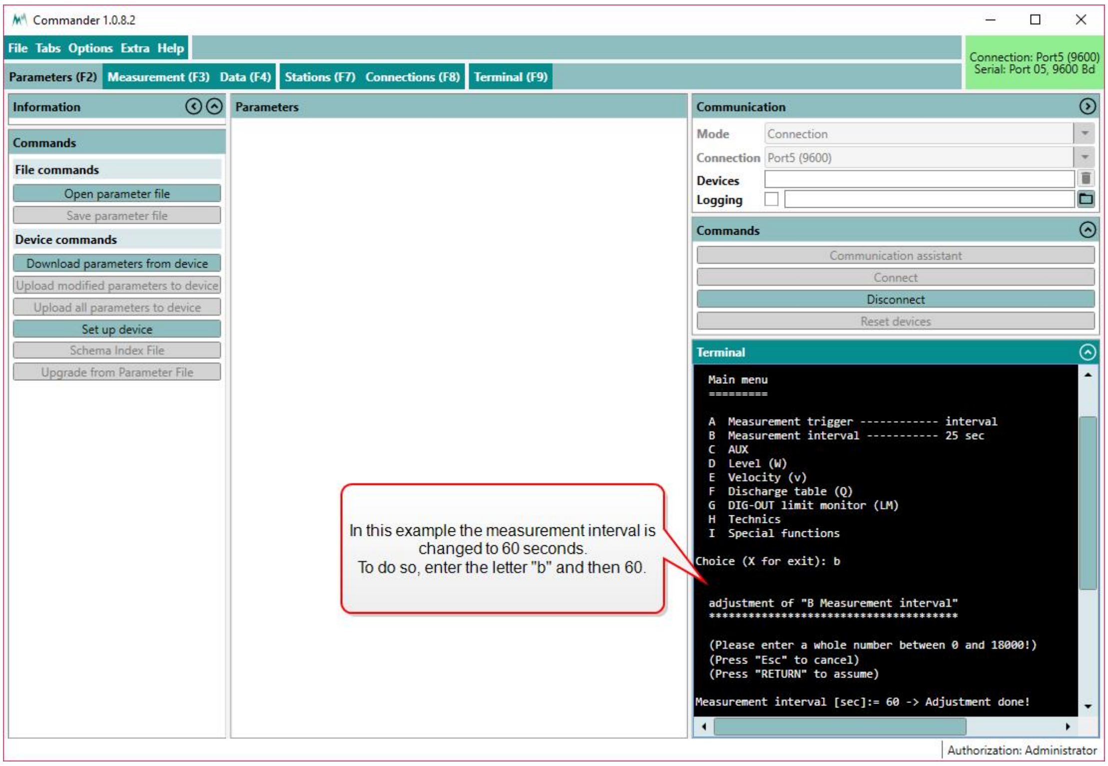
Follow the steps below to modify the configuration parameters of the IDS-20d:

1. Establish a connection between your PC and the IDS-20d.
2. In the terminal window enter three question marks (???) in quick succession. The main parameter menu is displayed in response.



NOTE As an unwanted switching into the menu mode must be avoided the timing of the three question marks ??? is very restrictive and must never be finished with Return/Enter. This is especially important for command line tools, which automatically send a closing "Carriage return”. Before and after sending ??? no communication must occur for 1 second.

3. Read or modify the required parameters: The menu items can be selected by entering the letter assigned to each item. Upon selection a submenu is opened or the selected parameter is displayed with its unit. Changes to values are confirmed with Return/Enter or discarded with Esc. Menus are closed with X or Esc. After closing the main menu with X the device performs an initialization.



11.4 General settings

When first setting-up a IDS-20d at a measurement site, the parameters described below may need to be adapted.

11.4.1 Language/Sprache

The menu language.

11.4.2 Decimal character

The character used as decimal separator in the values of the settings, in serial data strings and in .csv files.

11.4.3 Units and decimals

The units and number of decimal digits. These have to be set prior to all other settings as all values are saved internally in this format. They are set in the parameter menu Units and decimals.

ATTENTION If units or decimals are changed, related parameters may need to be adjusted.

11.4.4 Output protocol (OP)

The type of the serial output protocol. The following options are available:

ID	Option	Description
1	Sommer (SBP) (default)	Sommer protocol; data values are returned with an index starting at 1. Multiple strings may be returned.
2	Standard	Standard protocol; data values are returned without an index in one string.
3	MODBUS	Modbus protocol

11.4.5 Information

The main measurement values are always included in the data output string. Additionally, special and analysis values can be included.

ID	Option	Description
1	Main values	Only the main values are returned.
2	& Special values (default)	Main values and special values are returned.
3	& Analysis values	Main, special and analysis values are returned.

11.5 Sensor setup

11.5.1 Sensor type

The type of sensor used. One of Cube 1, Cub 5, Rod T 80 or Custom.

11.5.2 Sensor S1, orientation **and** Sensor S2, orientation

The orientation of the sensor relative to geographic north. Use the black mark on the cube sensor for northing.

11.5.3 Sensor S1, zero adjust **and** Sensor S2, zero adjust

After connection of the sensors to the IDS-20d controller it needs to be verified that the sensor cables do not introduce any interfering capacities. This can be tested with the functions Sensor S1, test and Sensor S2, test, which read the currently measured capacities of all sensor plates. Use the zero adjust functions to compensate for any capacities introduced by the sensor cables.

ATTENTION The zero adjust functions should only be applied during installation with dry sensor surfaces. Do not use this function during continuous operation as this may introduce a shift of icing measurements!

11.5.4 “OFF” turn off temperature

To reduce power consumption icing measurements are switched off if ambient temperatures exceed the specified limit.

NOTE
If the ambient temperature exceeds “OFF” turn off temperature, the IDS-20d returns the following values for ice and water variables:

Protocol	Returned value
RS-485	empty string
SDI-12	`00000000`
Modbus	10^6, 10^7, 10^8

11.6 Heater configuration

11.6.1 Ice, maximum

The maximum ice accumulation before the sensor starts heating.

11.6.2 Ice, minimum

Thickness of the accumulated ice layer at which heating stops. This limit is only active in combination with the Water, minimum setting.

11.6.3 Water, maximum

The maximum water accumulation before the sensor starts heating.

11.6.4 Water, minimum

Thickness of the accumulated water layer at which heating stops. This limit is only active in combination with the Ice, minimumsetting.

11.6.5 Maximum heating time

The maximum heating duration for one heating cycle. It prevents excess heating and damage of an ice-sensor. Generally, an ice-sensor is defrosted and dried in less than the default 600 sec. Except for extremely harsh environments it is recommended to use the default value.

11.6.6 Cool down duration

The time required to cool down the ice-sensor to ambient conditions.

11.6.7 Meas. duration icing rate

It is recommended to determine the icing-rate over a longer period than a single measurement interval. This period can be specified with the icing-rate measurement duration.

11.7 Icing verification

With the IDS-20d icing of a connected sensor is verified by the following variables. All three conditions must be satisfied for ice to accrete on a sensor.

11.7.1 Maximum temperature

The temperature below which icing may occur. This depends on the meteorological conditions at the measurement site, e.g. wind speed, humidity or precipitation and may reach a few degrees Celsius plus.

11.7.2 Minimum humidity

The relative humidity above which icing may occur. This value may be as low as 80%.

11.7.3 Maximum water

The thickness of the water layer on the sensor below which icing may occur.

The result of the icing verification is also returned with the analysis values (indices 26 and 40). See Measurement phases for details.

11.8 Relay switching

The IDS-20d provides two relay outputs which can be configured to switch according to different limit values of the connected sensors. The wiring of the relay outputs is illustrated in Figure 10.

11.8.1 Output value

The variable which controls relay A and/or B; either ice, water or ice and water. Different variables of the same sensor or the same variable of both sensors can be selected.

11.8.2 Sensor choice

One of the sensors for which the limit value is monitored.

11.8.3 Ice limit

The amount of ice accreted before the relay is switched.

11.8.4 Water limit

The amount of accumulated water before the relay is switched.

11.8.5 Ice rate limit

The rate at which ice accumulates before the relay is switched.

11.8.6 Functional switch at “OFF”

The IDS-20d contains an additional relay that responds to high ambient temperatures and the state of the device. To reduce power consumption icing measurements can be switched off if ambient temperatures are too high.

Generally, if an instrument failure occurs the relay opens. The relay can also be configured to open if the ambient temperature exceeds a certain limit.

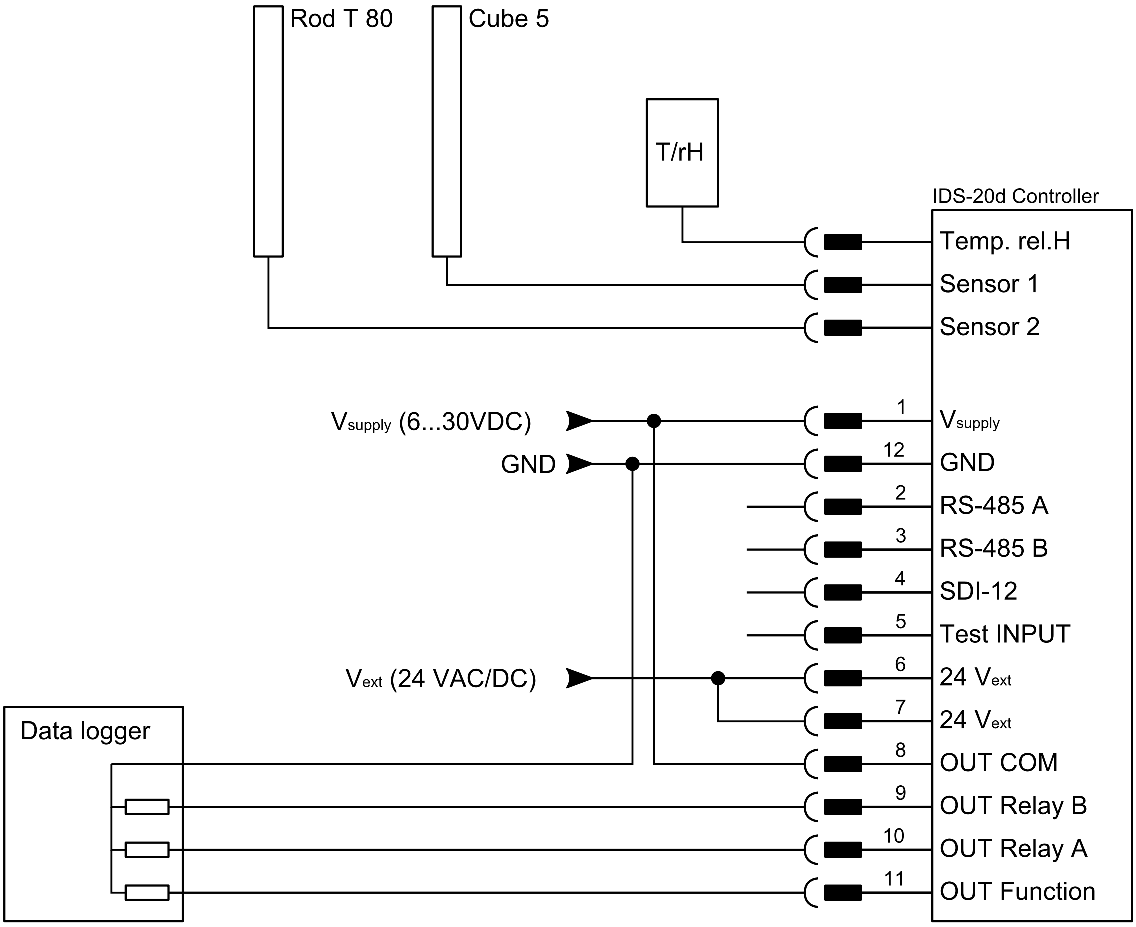


Figure 10 Wiring of relay outputs to a data logger

12 Communication

12.1 Communication protocols

The IDS-20d provides the following communication protocols:

- RS-485 (Sommer bus protocol)
- Modbus
- SDI-12

12.2 Data output

The measurement values returned by the IDS-20d are arranged in a fixed sequence and identified by an index. They are divided into three groups and can be selected in Information.

12.2.1 Main values

Index	Value	Unit	Description
01	Temperature	°C / F	Air temperature
02	Humidity	%	Humidity
03	Dew point	°C / F	Dew point
04	Relay A	0 / 1	State of relay A
05	Relay B	0 / 1	State of relay B
06	Relay function	0 / 1	State of measurement device
07	Sensor 1, Ice	mm	Current ice layer thickness on sensor 1
08	Sensor 1, Water	mm	Current water layer thickness on sensor 1
09	Sensor 1, Ice rate	mm/h	Current icing rate on sensor 1
10	Sensor 1, Temperature	°C / F	Surface temperature of sensor 1
11	Sensor 1, Direction	°	Icing direction of sensor 1

Index	Value	Unit	Description
12	Sensor 1, Direction value		Directional distinction of ice accretion; the higher the value the more pronounced icing is in a certain direction.
13	Sensor 2, Ice	mm	Current ice layer thickness on sensor 2
14	Sensor 2, Water	mm	Current water layer thickness on sensor 2
15	Sensor 2, Ice rate	mm/h	Current icing rate on sensor 2
16	Sensor 2, Temperature	°C / F	Surface temperature of sensor 2
17	Sensor 2, Direction	°	Icing direction of sensor 2
18	Sensor 2, Direction value		Directional distinction of ice accretion; the higher the value the more pronounced icing is in a certain direction.

Table 2 Main values

12.2.2 Special values

Index	Value	Unit	Description
19	Relay A, counter		Sum of trigger events of relay A
20	Relay A, time	h	Total time relay A is on
21	Relay B, counter		Sum of trigger events of relay B
22	Relay B, time	h	Total time relay B is on
23	Heating current	A	Heating current
24	Supply Voltage	V	Supply voltage
25	Exception code		for diagnostic use of Sommer Messtechnik only

Table 3 Special values

12.2.3 Analysis values

Index	Value	Unit	Description
26	Sensor 1, Measurement phase		Measurement phase of the sensor, see Measurement phases
27	Sensor 1, Ice raw	mm	Current ice layer thickness, not verified
28	Sensor 1, C P1 LF	pF	Capacity
29	Sensor 1, C P1 HF	pF	Capacity
30	Sensor 1, C P2 LF	pF	Capacity
31	Sensor 1, C P2 HF	pF	Capacity
32	Sensor 1, C P3 LF	pF	Capacity
33	Sensor 1, C P3 HF	pF	Capacity
34	Sensor 1, P P1 LF	°	Phase of the electrical signal
35	Sensor 1, P P1 HF	°	Phase of the electrical signal
36	Sensor 1, P P2 LF	°	Phase of the electrical signal
37	Sensor 1, P P2 HF	°	Phase of the electrical signal
38	Sensor 1, P P3 LF	°	Phase of the electrical signal
39	Sensor 1, P P3 HF	°	Phase of the electrical signal
40	Sensor 2, Measurement phase		Measurement phase of the sensor, see see Measurement phases
41	Sensor 2, Ice raw	mm	Current ice layer thickness, not verified

Index	Value	Unit	Description
42	Sensor 2, C P1 LF	pF	Capacity
43	Sensor 2, C P1 HF	pF	Capacity
44	Sensor 2, C P2 LF	pF	Capacity
45	Sensor 2, C P2 HF	pF	Capacity
46	Sensor 2, C P3 LF	pF	Capacity
47	Sensor 2, C P3 HF	pF	Capacity
48	Sensor 2, P P1 LF	°	Phase of the electrical signal
49	Sensor 2, P P1 HF	°	Phase of the electrical signal
50	Sensor 2, P P2 LF	°	Phase of the electrical signal
51	Sensor 2, P P2 HF	°	Phase of the electrical signal
52	Sensor 2, P P3 LF	°	Phase of the electrical signal
53	Sensor 2, P P3 HF	°	Phase of the electrical signal

Table 4 Analysis values

12.2.4 Exception values

Measurement data may be returned with the following exception values:

Value	Description
99999998	Initial value: No measurement has been performed yet.
99999997	Conversion error: Caused by a technical problem.
99999999	Positive overflow
−9999999	Negative overflow

Table 5 Exception values

12.3 RS-485

12.3.1 What is RS-485?

RS-485 is a serial communication method for computers and devices. It is currently a widely used communication interface in data acquisition and control applications where multiple nodes communicate with each other.[1]

12.3.2 What can I do with it?

RS-485 communication is primarily used to trigger measurements and read their results. It also permits to change parameters of the IDS-20d.

12.3.3 Configuration

The IDS-20d has serial RS-485 communication enabled by default. If the device is integrated into a RS-485 network or connected to a stand-alone data acquisition system, e.g. a data logger, the parameters listed in Output protocol may need to be adapted.

System key and device number

The system key and device number are used to identify a IDS-20d in a bus system. This is essential if multiple devices (IDS-20d and data loggers) are operated within the same system.

System key
: The system key separates different conceptual bus systems. This may be necessary if the remote radio coverage of two measurement systems overlap. In wired setups, the system key should be set to *00*.

Device number
: The device number is a unique number that identifies a device in a bus system.

> **ATTENTION** Do not use a device number twice in your bus system! Otherwise communication will fail!

[1] https://www.lammertbies.nl/comm/info/RS-485.html

Measurement output

The serial data output can be triggered in the following ways:

ID	Option	Description
1	Just per command	The output is only requested by commands via RS-485.
2	After measurement (default)	The serial data output is performed automatically right after each measurement.
3	Pos. TRIG slope	The output is triggered by a positive edge of a control signal applied to the trigger input.

NOTE If Measurement output is set to *pos. TRIG slope*, the data are returned with a delay of 200 ms after the trigger has been set. Make sure that your data acquisition system takes account of this lag to ensure that it receives the most recent data.

Operation modes

The selected combination of measurement trigger and output time determines the following operation modes:

	Mode		
Parameter	**Pushing**	**Polling**	**Apparent polling**
Measurement trigger	internal	TRIG input SDI-12/RS485	TRIG input SDI-12/RS485
OP, measurement output	after measurement	just per command	after measurement

Waking-up a connected data logger

The IDS-20d supports wake-up of a connected data logger that is in standby mode. Generally, this feature is only used in pushing mode and can be set under Wake-up sequence.

Sync sequence

The sync sequence is the string `UU~?~?` and is sent directly before a command. It is used to synchronize the receiving UART.

Prefix

The prefix is an arbitrary character; the IDS-20d uses a blank. This character is sent prior to any communication. Then the time of the Prefix holdback is waited and the command is sent afterwards. With this procedure the receiving device has time to wake-up.

Output protocols

For data output via RS-485 different protocols are available, which can be selected under Output protocol (OP).

12.3.4 Data output options

Data are returned in two different formats, selectable in Output protocol (OP):

- Sommer bus protocol (SBP)
- Standard protocol

12.3.5 Sommer bus protocol (SBP)

The data string of the Sommer protocol has the following format:

EXAMPLE `#M0001G01se01    1461|02    1539|03    25.25|04    0|3883;`

A data string contains max. 8 values and is max. 105 characters long.

Header

The header (`#M0001G00se`) identifies the data by system key, device number and string number.

Parameter	Format	Description
Start character	#	
Identifier	M	M identifies an output string
System key	dd	
Device number	dd	
Command ID	G	G defines an output string with string number
String number	dd	01 Main values 03 Special values 05 Analysis values 06 Analysis values
Command	se	se identifies automatically sent values

Table 6 Header of the Sommer protocol

Measurement value

A measurement value (02   1539|) has a length of 8 digits and is returned together with its index. If the measurement value is a floating point number, one digit is reserved for the decimal character. Values are returned right-aligned, so blanks may occur between index and value.

Parameter	Format	Description
Index	dd	2 numbers
Value	xxxxxxxx	8 character right-aligned
Separator	|	

Table 7 Values in Sommer protocol

End sequence

The data string is terminated with a CRC-16 in hex format (3883) followed by an end character and <CR><LF>. The CRC-16 is described in Sommer CRC-16.

Parameter	Format	Description
CRC-16	Hhhh	4-digit hex number
End character	;	
Control characters	<CR><LF>	Carriage return and Line feed

Table 8 End sequence of the Sommer protocol

Example Sommer protocol

Main values

Main values are returned as in the following example:

EXAMPLE

```
#M0001G01se01      27.8|02      35.8|03      11.2|04
0|05         0|06         1|9440;

#M0001G02se07       0.00|08       0.04|09       0.00|10
27.4|11          |12          |CA86;

#M0001G03se13       0.00|14      31.50|15       0.00|16
28.1|17          |18          |F592;
```

#M0001G01se	Header with system key 00, device number 01 and string number 01
01 27.8|	Temperature
02 35.8|	Humidity
03 11.2|	Dew point
04 0|	Relay A
05 0|	Relay B
06 1|	Relay function
9440;	Closing sequence

`#M0001G02se`	Header with system key 00, device number 01 and string number 02
`07       0.00|`	Sensor 1, Ice
`08       0.04|`	Sensor 1, Water
`09       0.00|`	Sensor 1, Ice rate
`10       27.4|`	Sensor 1, Temperature
`11           |`	Sensor 1, Direction
`12           |`	Sensor 1, Direction value
`CA86;`	Closing sequence
`#M0001G03se`	Header with system key 00, device number 01 and string number 03
`13       0.00|`	Sensor 2, Ice
`14      31.50|`	Sensor 2, Water
`15       0.00|`	Sensor 2, Ice rate
`16       28.1|`	Sensor 2, Temperature
`17           |`	Sensor 2, Direction
`18           |`	Sensor 2, Direction value
`F592;`	Closing sequence

Table 9 Main values in Sommer protocol

Special values

Special values are returned as in the following example:

EXAMPLE `#M0001G10se19      125|20     70.0|21      112|22      61.6|23      0.00|24    10.64|25      0.00|EA03;`

#M0001G10se	Header with system key 00, device number 01 and string number 10
19 125|	Relay A, counter
20 70.0|	Relay A, time
21 112|	Relay B, counter
22 61.6|	Relay B, time
23 0.00|	Heating current
24 10.64|	Supply Voltage
25 0.00|	Exception code
EA03;	Closing sequence

Table 10 Special values in Sommer protocol

Analyis values

Analysis values are returned as in the following example:

EXAMPLE

```
#M0001G20se26       1.06|27       0.00|28      29.94|29
30.05|30    30.03|31    30.15|32    30.24|828D;

#M0001G21se33     30.34|34    - 89.93|35    - 88.48|36    -
89.93|37   -88.43|38   -89.97|39   -88.65|D629;

#M0001G22se40       1.04|41       0.00|42      89.34|43
89.56|44    89.15|45    89.31|46    89.71|138B;

#M0001G23se47     89.94|48    - 89.93|49    - 89.66|50    -
89.91|51   -89.58|52   -89.92|53   -89.66|B46F;
```

#M0001G20se	Header with system key 00, device number 01 and string number 20
26 1.06|	Sensor 1, Measurement phase
27 0.00|	Sensor 1, Ice raw

`28    29.94|`	Sensor 1, C P1 LF
`29    30.05|`	Sensor 1, C P1 HF
`30    30.03|`	Sensor 1, C P2 LF
`31    30.15|`	Sensor 1, C P2 HF
`32    30.24|`	Sensor 1, C P3 LF
`828D;`	Closing sequence
`#M0001G21se`	Header with system key 00, device number 01 and string number 21
`33    30.34|`	Sensor 1, C P3 HF
`34   -89.93|`	Sensor 1, P P1 LF
`35   -88.48|`	Sensor 1, P P1 HF
`36   -89.93|`	Sensor 1, P P2 LF
`37   -88.43|`	Sensor 1, P P2 HF
`38   -89.97|`	Sensor 1, P P3 LF
`39   -88.65|`	Sensor 1, P P3 HF
`D629;`	Closing sequence
`#M0001G22se`	Header with system key 00, device number 01 and string number 22
`40     1.04|`	Sensor 2, Measurement phase
`41     0.00|`	Sensor 2, Ice raw
`42    89.34|`	Sensor 2, C P1 LF
`43    89.56|`	Sensor 2, C P1 HF
`44    89.15|`	Sensor 2, C P2 LF
`45    89.31|`	Sensor 2, C P2 HF
`46    89.71|`	Sensor 2, C P3 LF
`138B;`	Closing sequence

#M0001G23se	Header with system key 00, device number 01 and string number 23
47 89.94|	Sensor 2, C P3 HF
48 -89.93|	Sensor 2, P P1 LF
49 -89.66|	Sensor 2, P P1 HF
50 -89.91|	Sensor 2, P P2 LF
51 -89.58|	Sensor 2, P P2 HF
52 -89.92|	Sensor 2, P P3 LF
53 -89.66|	Sensor 2, P P3 HF
B46F;	Closing sequence

Table 11 Analysis values in Sommer protocol

12.3.6 Standard protocol

The data string of the Standard protocol has the following format:

EXAMPLE `M_0001      1461      1359       25.38          0`

Header

The header (M_0001) identifies the data by system key and device number.

Parameter	Format	Description
Identifier	X_	M_ Measurement values S_ Special values V_ Analysis values
System key	Dd	
Device number	Dd	

Table 12 Header of the Standard protocol

Measurement values

Measurement values are returned in sequence and are separated by a blank. A measurement value has a length of 8 digits. If the measurement value is a decimal number, one digit is reserved for the decimal character. Values are returned right-aligned, so additional blanks may be returned between values.

Parameter	Format	Description
Separator	`[blank]`	blank
Value	`xxxxxxxx`	8 character right-aligned

Table 13 Values in Standard protocol

NOTE With the standard protocol the data strings can be very long. In contrast, the strings of the Sommer protocol are max. 105 characters long.

End sequence

The data string is terminated with `<CR><LF>`.

Example Standard protocol

Main values

Main values are returned as in the following example:

EXAMPLE
```
M_0001      28.1      34.9      11.2           0
0          1      0.00      0.03      0.00      27.9
0.00      31.50      0.00      28.4
```

M_0001	Header with identifier for measurement values
28.1	Temperature
34.9	Humidity
11.2	Dew point
0	Relay A
0	Relay B
1	Relay function
0.00	Sensor 1, Ice
0.03	Sensor 1, Water
0.00	Sensor 1, Ice rate
27.9	Sensor 1, Temperature
0.00	Sensor 1, Direction
31.5	Sensor 1, Direction value
0	Sensor 2, Ice
0.0	Sensor 2, Water
0	Sensor 2, Ice rate
28.4	Sensor 2, Temperature

Table 14 Main values in Standard protocol

Special values

Special values are returned as in the following example:

EXAMPLE `S_0001 125 70.0 112 61.6 -0.01 11.30 0.32`

S_0001	Header with identifier for measurement values
125	Relay A, counter
70.0	Relay A, time
112	Relay B, counter
61.6	Relay B, time
-0.01	Heating current
11.30	Supply Voltage
0.32	Exception code

Table 15 Special values in Standard protocol

Analyis values

Analysis values are returned as in the following example:

EXAMPLE
```
V_0001    1.06     0.00     29.93    30.05
30.03    30.14    30.23    30.34   -89.93   -88.47   -
89.92   -88.43   -89.97   -88.65     1.04     0.00
89.32    89.55    89.14    89.32    89.71    89.94   -
89.93   -89.66   -89.91   -89.58   -89.92   -89.65
```

V_0001	Header with identifier for analysis values
1.06	Sensor 1, Measurement phase
0	Sensor 1, Ice raw
29.93	Sensor 1, C P1 LF
30.05	Sensor 1, C P1 HF
30.03	Sensor 1, C P2 LF
30.14	Sensor 1, C P2 HF
30.23	Sensor 1, C P3 LF

30.34	Sensor 1, C P3 HF
-89.93	Sensor 1, P P1 LF
-88.47	Sensor 1, P P1 HF
-89.92	Sensor 1, P P2 LF
-88.43	Sensor 1, P P2 HF
-89.97	Sensor 1, P P3 LF
-88.65	Sensor 1, P P3 HF
1.04	Sensor 2, Measurement phase
0	Sensor 2, Ice raw
89.32	Sensor 2, C P1 LF
89.55	Sensor 2, C P1 HF
89.14	Sensor 2, C P2 LF
89.32	Sensor 2, C P2 HF
89.71	Sensor 2, C P3 LF
89.94	Sensor 2, C P3 HF
-89.93	Sensor 2, P P1 LF
-89.66	Sensor 2, P P1 HF
-89.91	Sensor 2, P P2 LF
-89.58	Sensor 2, P P2 HF
-89.92	Sensor 2, P P3 LF
-89.65	Sensor 2, P P3 HF

Table 16 Analysis values in Standard protocol

12.3.7 RS-485 commands

Command structure

The structure of serial commands and answers is described in the following table:

Parameter	Format	Description
Start character	#	
Identifier	X	W Write: IDS-20d returns a confirmation on receipt. This command type demands a closing sequence with a valid CRC-16. S Silent: IDS-20d does not acknowledge the receipt of the command. This command type demands no closing sequence and therefore no CRC-16. R Read: IDS-20d returns the requested measurement value or parameter. This command type demands a closing sequence with a valid CRC-16. T Temporary: Write a volatile, temporary setting and receive a confirmation. A Answer: Answer of device to read or write command.
System key	dd	
Device number	dd	
Command	xxx	See table in section Commands.
Separator	|	
CRC-16	hhhh	4-digit hex number
End character	;	

Table 17 Structure of Sommer bus commands and answers

Commands

The following commands can be used with the IDS-20d:

Command	Description
$mt	Trigger a measurement
$pt	Return measurement values
XX	Read a parameter with identifier XX
XX=xxxx	Write a parameter with identifier XX and the value xxx

Table 18 List of Sommer bus commands

Trigger a measurement

The command $mt triggers a complete measurement sequence as in the following example:

EXAMPLE #W0001$mt|BE85;   Answer: #A0001ok$mt|4FA9;

Read a parameter value

Read measurement interval (in the example below the menu item B):

EXAMPLE #R0001B|228E;   Answer: #A0001B=300|F8B3;

Request a complete data string

The command $pt requests a data string as in the following example:

EXAMPLE

Option 1

#W0001$pt|7D19;   Answer: #A0001ok$pt|8C35;

Option 2

#S0001$pt| Answer: none

The data string is returned as soon as the IDS-20d has processed the command. If a wrong command is entered, the device returns #A0001na$pt|3D40;.

Request a single measurement value

The reading command `R` together with the index of the requested measurement returns a single measurement value. In the following example the measurement value with index `01` (in this example a water level) is requested:

> **EXAMPLE**
> `#R0001_010cv|EA62;`
>
> Answer: `#A0001ok_010cv1461     |07EB;`

12.3.8 Sommer CRC-16

The CRC-16 (cyclic redundancy check) used in data transmission of Sommer devices is based on the ZMODEM protocol. When data are exchanged between two devices the receiving device calculates the CRC-value. This value is compared to the CRC value sent by the other device to check if the data were transmitted correctly. Please refer to technical literature or contact Sommer for calculation of CRC-16 values.

You can here calculate the CRC of a command online .

If you need to compute CRCs automatically, you can implement the following procedure in your data logger or controller software.

The CRC-16 is calculated character by character. The start value for the initial CRC-16 calculation is always 0.

The following procedure returns the CRC-16 of a single character:

`byte1 = CRC-16 right shift by 8 bits`	upper byte disappears
`uint1 = c`	new character, upper byte = 0
`uint2 = CRC-16 left shift by 8 bits`	lower byte = 0
`uint3 = crc16tab[byte1]`	Table value from the CRC-16 table
`Crc16 = uint3 (excl. or) uint2 (excl. or) uint1`	

Computation CRC-16 in C/C++

```
crc16 = crc16tab[(unsigned char)(crc16>>8)] ^ (crc16<<8) ^ (unsigned int)(c);
```

The `crc16tab` array is listed in CRC-16 array.

EXAMPLE

Command to request measurement data `#W0001$pt|7D19;`

The first character is `#`, the last `|`. The CRC-16 of the command is `7D19` and its end character is `;`.

The CRC-16 is calculated sequentially with the start value `0` for the initial CRC-16 calculation:

Position	String	CRC-16
Start		0000
0	#	0023
1	#W	2357
2	#W0	4331
3	#W00	4997
4	#W000	4EDD
5	#W0001	743B
6	#W0001$	0537
7	#W0001$p	67D5
8	#W0001$pt	C935
9	#W0001$pt|	7D19

12.4 SDI-12

12.4.1 What is SDI-12?

SDI-12 (Serial Data Interface at 1200 Baud) is a serial data communication standard for interfacing multiple sensors with a single data recorder. For a detailed description on SDI-12 communication please refer to www.sdi-12.org.

12.4.2 What can I do with it?

The IDS-20d listens to standard SDI-12 commands as listed in the SDI-12 specifications of version 1.3, e.g., to trigger a measurement or retrieve measurement results. Additionally, a set of extended SDI-12 commands is implemented in all SOMMER sensors for instrument configuration.

12.4.3 Configuration

The IDS-20d has SDI-12 communication enabled by default. When setting up a SDI-12 network take the following considerations into account:

- Each device in the SDI-12 network must have a unique address, e.g. data logger address *0*, IDS-20d address *1*.
- The IDS-20d operates in pushing mode and data are retrieved by `R!` commands.
- When multiple sensors are connected to the same network, data acquisition should be done in sequence, i.e., data should have been received from the first sensor before triggering the measurement of the second sensor.
- Most data loggers control the timing of messages (marking and spacing) automatically. If this is not the case, please refer to www.sdi-12.org.

12.4.4 Data structure

The answer from the SDI-12 device is a string containing the sensor address, the requested data and a terminating carriage return/line feed.

In a string containing measurement data, the measurements are returned in the same order as listed by the index in Data output.

EXAMPLE

`0+2591+706+25.53+62<CR><LF>`

Value	Content
0	Sensor address
2591	Measurement with index 01
706	Measurement with index 02
25.53	Measurement with index 03
62	Measurement with index 04

If a device returns more than 9 measurement values, or if the values are returned in groups (see also Request results) the measurement index increments in the next group.

EXAMPLE

`0D0!` Answer: `0+2591+706+25.53+62<CR><LF>`

`0D0!` Answer: `0+56.2+125+12.32<CR><LF>`

Value	Content
0	Sensor address
2591	Measurement with index 01
706	Measurement with index 02
25.53	Measurement with index 03
62	Measurement with index 04
0	Sensor address
56.2	Measurement with index 05
125	Measurement with index 06
12.32	Measurement with index 07

12.4.5 SDI-12 commands

The following tasks can be performed with standard and extended SDI-12 commands.

Extended SDI-12 commands are non-standard commands implemented by SOMMER to enable device configuration via SDI-12.

NOTE After any changes, the settings have to be adopted with the command `aXW_ts|!`, with `a` the sensor address.

Command structure

A standard SDI-12 command starts with the sensor address and ends with an exclamation mark, e.g., `0M!` to trigger a measurement.

Configuration commands contain additional information; see the sections below for details.

Identify device

The identification of a SDI-12 device is requested with the command `aI!`, with `a` the sensor address.

EXAMPLE

`0I!` Answer `013Sommer  USH   140r90 USH-9    <CR><LF>`

The answer contains the following information:

0	SDI-12 address
1	SDI-12 version prior to the point
3	SDI-12 version after the point
Sommer	Description of the company (6 characters and 2 blanks)
USH	Description of the firmware (5 characters and 2 blanks)
140r90	Firmware version (6 characters and 2 blanks)
IDS-20d	Device designation (max. 13 characters)

Acquire measurements

To acquire a measurement from a sensor, two individual SDI-12 commands – trigger a measurement and request measurement values – need to be sent.

EXAMPLE

0M! Answer: 00084<CR><LF> and 0<CR><LF> after 8 seconds

0D0! Answer: 0+2591+706+25.53+0<CR><LF>

The first values in the response to the aDn! command is the sensor address.

Trigger measurement

The command aM! with sensor address a triggers a measurement as in the example below.

The response states the measurement duration and the number of measurement values (see example below). After completion of the measurement, the device will return an additional a<CR><LF>, with a the sensor address.

EXAMPLE

0M! Answer: 00084<CR><LF> and 0<CR><LF> after 8 seconds

The answer contains the following information:

0 SDI-12 address

008	Duration of the measurement in seconds
4	Number of measurement values

Request results

After each measurement, results are requested with the command aDn!, with a the sensor address and n the index of the returned data string.

EXAMPLE 0D0! Answer: 0+2591+706+25.53+0<CR><LF>

The leading 0 of the response is the sensor address.

Generally, the command aD0! is sufficient to request up to 9 measurement values. If more than 9 values need to be read, or if the values are returned in groups, the commands aD1!, aD2!,… may need to be issued after aD0!. For example, if a measurement returns 8 values in two groups of 4, the commands aD0! and aD1! need to be issued to receive all values.

Acquire continuous measurements

If the SDI-12 device is operating in continuous measurement mode (not polled by SDI-12), the command aR0! will request and return the current reading of the sensor. The values within the data string follow the order listed in the measurement table. The first values in the response to the aRn! command is the sensor address.

EXAMPLE

0R0! Answer: 0+2591+706+25.53+0<CR><LF>

If more than 9 values need to be read, or if the values are returned in groups, the commands aR1!, aR2!,… may need to be issued after aR0!. For example, if a measurement returns 8 values in two groups of 4, the commands aR0! and aR1! need to be issued to receive all values.

Configure parameter

The configuration parameters of a SOMMER sensor are read with the command aXRpp! and written with the command aXWpp=vvv!, with a the sensor address, pp the parameter identifier and vvv the value of the parameter.

Read and write a parameter

EXAMPLE

Reading of measurement interval (in this example menu item B)

`0XRB|!` Answer: `0B=300|<CR><LF>`

Setting of measurement interval to 60 s (in this example menu item B)

`0XWB=60|!` Answer: `0B=60|<CR><LF>`

Read and write a selector-parameter

Changing the measurement trigger (in the following example menu item A) from *interval* to *SDI-12/RS485*:

EXAMPLE

`0XRA|!` Answer: `0A=1|<CR><LF>`

`0XWA=3|!` Answer: `0A=3|<CR><LF>`

Read and write a parameters of a table

Some SOMMER sensors are equipped with multiple transducers and their settings are listed in a table (see example below). A value within such a table is addressed by its row-index (01, 02 …) and column-index (A, B …). A corresponding SDI-command has the following format:

EXAMPLE

In this example of a snow scale the value in row 01 and column B of the parameter D-D-E is changed to -1.4.

`0XWDDE01B=-1.4|!` Answer: `0DDE01b=-1.4|<CR><LF>`

	Identifier	offset zero kg	gain	zero default kg	gain default
01	Load Cell 1	-1.4	0,997787	0,000	0,997787
02	Load Cell 2	0,000	0,997787	0,000	0,997787
03	Load Cell 3	0,000	0,997787	0,000	0,997787
04	Load Cell 4	0,000	0,997787	0,000	0,997787

Adopt settings

Some settings need to be adopted with the command `aXW_ts|!`, with `a` the sensor address. It is recommended to issue `aXW_ts|!` after each configuration change.

12.5 Modbus

12.5.1 What is Modbus?

Modbus is a serial communication protocol used for transmitting information over serial lines between electronic devices. The device requesting the information is called the Modbus Master and the devices supplying information are Modbus Slaves. In a standard Modbus network, there is one Master and up to 247 Slaves, each with a unique Slave Address from 1 to 247. The Master can also write information to Slaves.

Modbus has become a standard communication protocol in industry, and is now the most commonly available means of connecting industrial electronic devices. It is often used to connect a supervisory computer with a remote terminal unit (RTU) in supervisory control and data acquisition (SCADA) systems. Versions of the Modbus protocol exist for serial lines (Modbus RTU and Modbus ASCII) and for Ethernet (Modbus TCP).[1]

12.5.2 What can I do with it?

Modbus-communication with IDS-20d allows reading of measurement values and device information by a Modbus master. Additionally, the basic RS-485 port settings can be written to the IDS-20d.

12.5.3 Wiring

For Modbus communication the IDS-20d is wired according to the table below.

Modbus	Connector MAIN	Connection wire	Description
Common	Pin 1	White	GND
D1 - B/B	Pin 4	Yellow	RS-485 A
D0 - A/A	Pin 5	Grey	RS-485 B

[1]http://www.simplymodbus.ca/FAQ.htm

Table 19 Modbus wiring

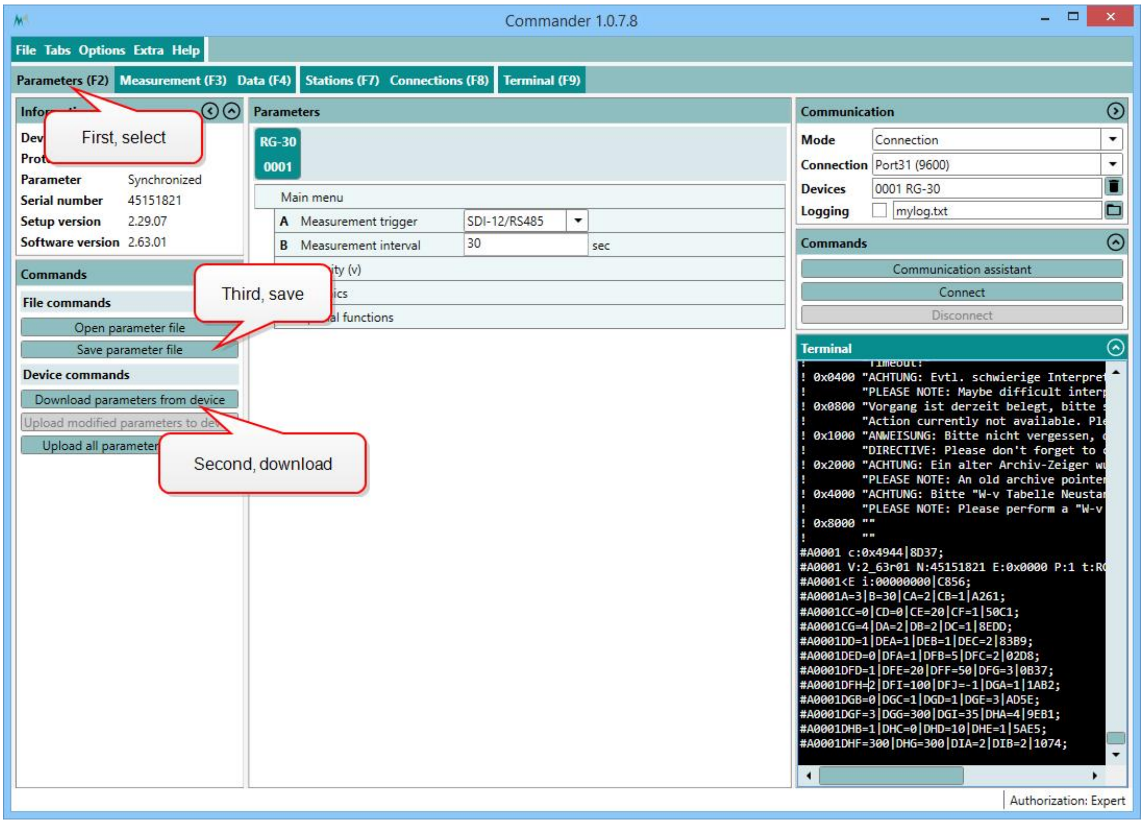
> **NOTE**
> Please note that different signal notations are in use for RS-485 connections:
>
> TX+/RX+ or D+ or D1 as alternative for B
>
> TX−/RX− or D− or D0 as alternative for A

> **NOTE** If the IDS-20d is operated with multiple Modbus devices within the same network, termination resistors may be required. Please contact Sommer Messtechnik for details.

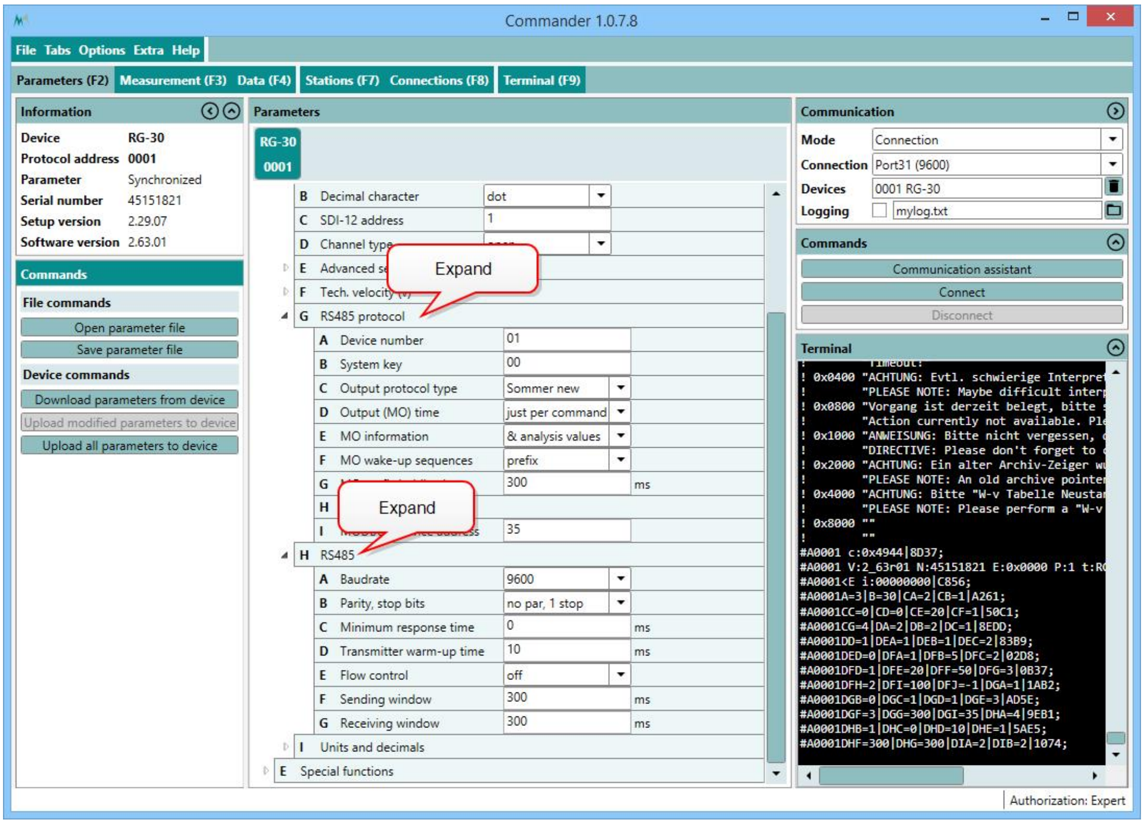
12.5.4 Modbus configuration

Follow the instructions below to change the communication of a Sommer-device (in this example a RG-30) to Modbus:

1. Connect the USB to RS-485 converter to the data cable of the Sommer-device and a USB port on your PC.
2. Connect the sensor to a power supply with the specified rating.
3. Start the Commander software on your PC.
4. Establish a connection to the Sommer-device.
5. Download the sensor's parameters in the Parameters (F2) tab and save the parameter list on your PC.



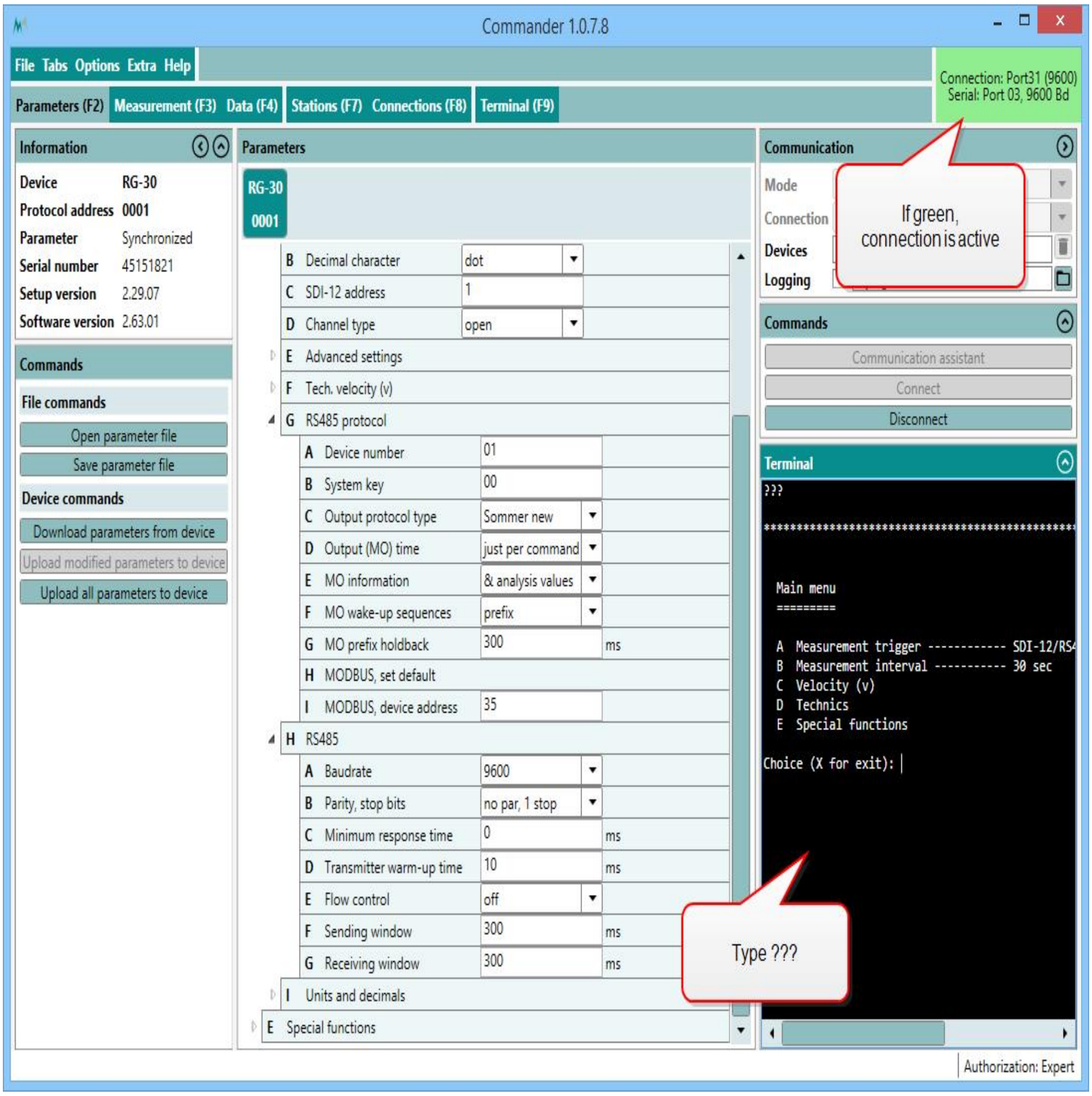
6. In the parameter list navigate to Technics and open the menus RS-485 protocol and RS485 and take a screenshot of the associated parameters. This and the previous step are helpful if you need to switch back to the standard communication mode at a later time.



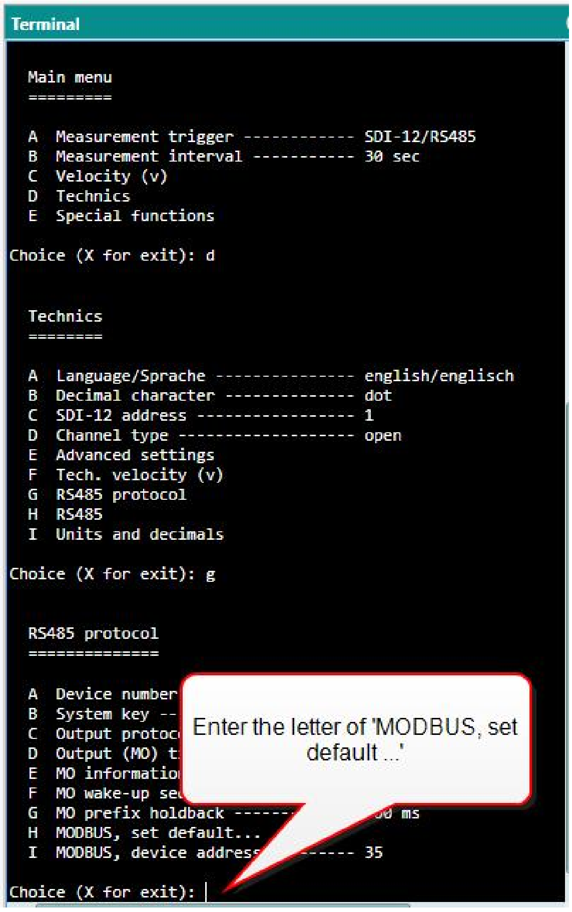
7. Set Measurement trigger to one of the following options:
   A. *Interval*, if measurements are triggered internally by the device.
   B. *SDI-12/RS-485*, if measurements are triggered by SDI-12.
   C. *TRIG input*, if measurements are triggered by a trigger input.
   D. *all allowed*, if measurements are triggered by one of the previous options.

> **NOTE** Modbus cannot trigger measurements! Make sure to use the trigger option suitable for your application!

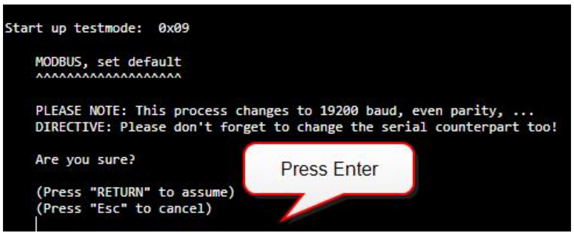
8. Verify that the connection to the Sommer-device is active and click into the Terminal window. Type `???` to enter the sensor-menu.



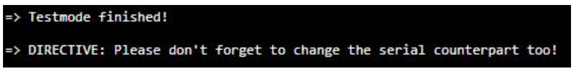
9. Navigate to *RS485 protocol* and select *MODBUS, set default...* Please note, that the index-letters might be different for your Sommer-device!



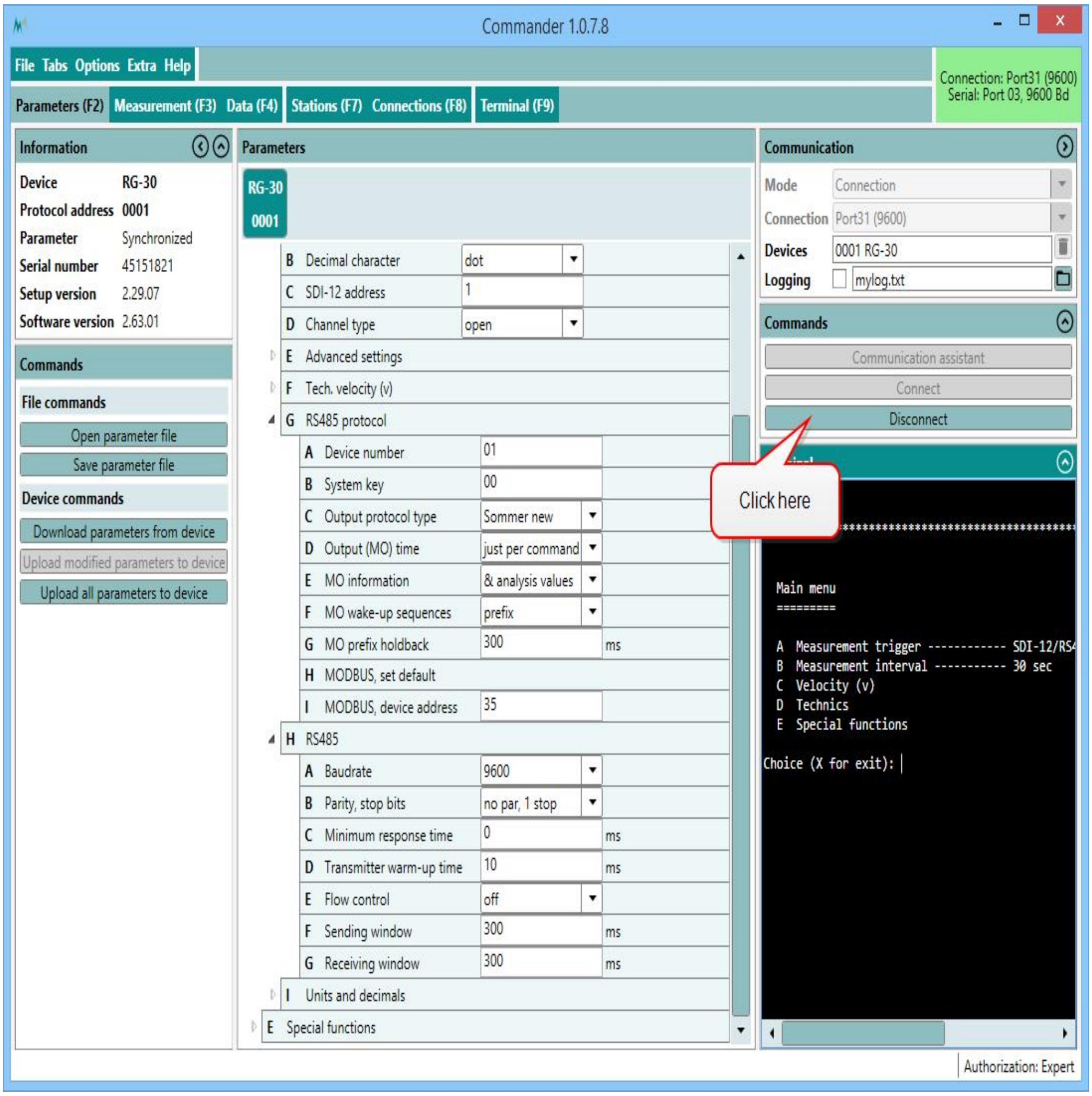
10. Acknowledge the safety-note.



11. After completion the following message will be displayed:



12. Enter X until you get back to the main menu. The Sommer-device is now restarted and available for Modbus-communication. As the connection-parameters have been changed to Modbus, the connection to the sensor is lost. Press Disconnect for completion.



NOTE

By switching communication to Modbus with MODBUS, set default the following parameters are changed:

Parameter	Modbus setting
OP, measurement output	just per command
Output protocol (OP)	Modbus
MODBUS, device address	35
Sleep mode	Modbus, slow
Parity, stop bits	even par, 1 stop
Baud rate	19200
Flow control	off
Transmitter warm-up time	10 ms

Parameter	Modbus setting
Minimum response time	30 ms

TIP To change a parameter in the Technics menu you need to change your Commander-authorization to Expert. See Change authorization for instructions.

12.5.5 Modbus commands and registers

Read input registers

Input registers contain measurement values. The content of these registers is updated after each measurement.

	Index	Register address	Variable	Unit / value	Bytes	Format
Test value		0	Hardcoded test value	2.7519...	4	float
Main	01	2	Temperature	°C / F	4	float
Main	02	4	Humidity	%	4	float
Main	03	6	Dew point	°C / F	4	float
Main	04	8	Relay A	0 / 1	4	float
Main	05	10	Relay B	0 / 1	4	float
Main	06	12	Relay function	0 / 1	4	float
Main	07	14	Sensor 1, Ice	mm	4	float
Main	08	16	Sensor 1, Water	mm	4	float
Main	09	18	Sensor 1, Ice rate	mm/h	4	float
Main	10	20	Sensor 1, Temperature	°C / F	4	float
Main	11	22	Sensor 1, Direction	°	4	float
Main	12	24	Sensor 1, Direction value	-	4	float

	Index	Register address	Variable	Unit / value	Bytes	Format
Main	13	26	Sensor 2, Ice	mm	4	float
Main	14	28	Sensor 2, Water	mm	4	float
Main	15	30	Sensor 2, Ice rate	mm/h	4	float
Main	16	32	Sensor 2, Temperature	°C / F	4	float
Main	17	34	Sensor 2, Direction	°	4	float
Main	18	36	Sensor 2, Direction value	-	4	float
Special	19	38	Relay A, counter	-	4	float
Special	20	40	Relay A, time	h	4	float
Special	21	42	Relay B, counter	-	4	float
Special	22	44	Relay B, time	h	4	float
Special	23	46	Heating current	A	4	float
Special	24	48	Supply Voltage	V	4	float
Special	25	50	Exception code	-	4	float
Analysis	26	52	Sensor 1, Meas-urement phase	-	4	float
Analysis	27	54	Sensor 1, Ice raw	mm	4	float
Analysis	28	56	Sensor 1, C P1 LF	pF	4	float
Analysis	29	58	Sensor 1, C P1 HF	pF	4	float
Analysis	30	60	Sensor 1, C P2 LF	pF	4	float
Analysis	31	62	Sensor 1, C P2 HF	pF	4	float
Analysis	32	64	Sensor 1, C P3 LF	pF	4	float
Analysis	33	66	Sensor 1, C P3 HF	pF	4	float
Analysis	34	68	Sensor 1, P P1 LF	°	4	float
Analysis	35	70	Sensor 1, P P1 HF	°	4	float

	Index	Register address	Variable	Unit / value	Bytes	Format
Analysis	36	72	Sensor 1, P P2 LF	°	4	float
Analysis	37	74	Sensor 1, P P2 HF	°	4	float
Analysis	38	76	Sensor 1, P P3 LF	°	4	float
Analysis	39	78	Sensor 1, P P3 HF	°	4	float
Analysis	40	80	Sensor 2, Measurement phase	-	4	float
Analysis	41	82	Sensor 2, Ice raw	mm	4	float
Analysis	42	84	Sensor 2, C P1 LF	pF	4	float
Analysis	43	86	Sensor 2, C P1 HF	pF	4	float
Analysis	44	88	Sensor 2, C P2 LF	pF	4	float
Analysis	45	90	Sensor 2, C P2 HF	pF	4	float
Analysis	46	92	Sensor 2, C P3 LF	pF	4	float
Analysis	47	94	Sensor 2, C P3 HF	pF	4	float
Analysis	48	96	Sensor 2, P P1 LF	°	4	float
Analysis	49	98	Sensor 2, P P1 HF	°	4	float
Analysis	50	100	Sensor 2, P P2 LF	°	4	float
Analysis	51	102	Sensor 2, P P2 HF	°	4	float
Analysis	52	104	Sensor 2, P P3 LF	°	4	float
Analysis	53	106	Sensor 2, P P3 HF	°	4	float
Device info	-	65533	Device type and configuration	320X	2	unsigned int
	-	65534	Software version	XYYZZ	2	unsigned int
	-	65535	Modbus implementation version	10100	2	unsigned int

Table 20 Input registers

> **NOTE** The 4-byte float values have the format *ABCD*, big-endian (*A* is the most significant byte).

Read and write holding registers

Holding resisters are mainly used to configure the Modbus adapter communication. Configuration settings are read with function 03 (read holding registers) and written with function 06 (write single registers).

> **NOTE** Restart the Modbus adapter after changing the configuration!

	Register address	Variable	Range	Bytes	Format
Config values	0	Modbus default[1]	0 - 1...read 1...write	2	unsigned int
	1	Modbus device address	1 to 247		
	2	RS-485 baud rate	1...1200 baud 2...2400 baud 3...4800 baud 4...9600 baud 5...19200 baud 6...38400 baud 7...57600 baud 8...115200 baud		
	3	RS-485 parity/ stop bits	1...no parity, 1 stop bit 2...no parity, 2 stop bits 3...even parity, 1 stop bit 4...odd parity, 1 stop bit		

Table 21 Holding registers

Report slave ID

The Modbus function 17 (report slave ID, read only) can be used to read basic information of the IDS-20d. The following example shows the response of function 17 of a RG-30 sensor, which is received in

[1]Writing "1" sets the Modbus default settings.

hex-format:

EXAMPLE 23 11 26 53 FF 27 74 20 53 6F 6D 6D 65 72 20 20 52 47 2D 33 30 20 20 20 32 5F 37 31 72 30 31 20 34 35 31 35 31 38 32 31 00 BB D4

			Example	
	Content	**Length (Bytes)**	**HEX-value**	**Decimal, ASCII**
PDU* response	Slave address	1	23	35
	Function code	1	11	17
	Number of bytes (excl. slave-address, function code, NUL and CRC)	1	26	38
	Slave ID	1	53	"S"
	Run status (0=inactive; FF=active)	1	FF	255
	Modbus implementation version	2	27 74	10100
	Separator	1	20	" "
	Vendor string	7	53 6F 6D 6D 65 72 20	"Sommer "
	Separator	1	20	" "
	Device configuration	7	52 47 2D 33 30 20 20	"RG-30 "
	Separator	1	20	" "
	Software version	7	32 5F 37 31 72 30 31	2_71r01
	Separator	1	20	" "
	Serial number	8	34 35 31 35 31 38 32 31	45151821
	NUL	1	00	
	CRC	2	BB D4	

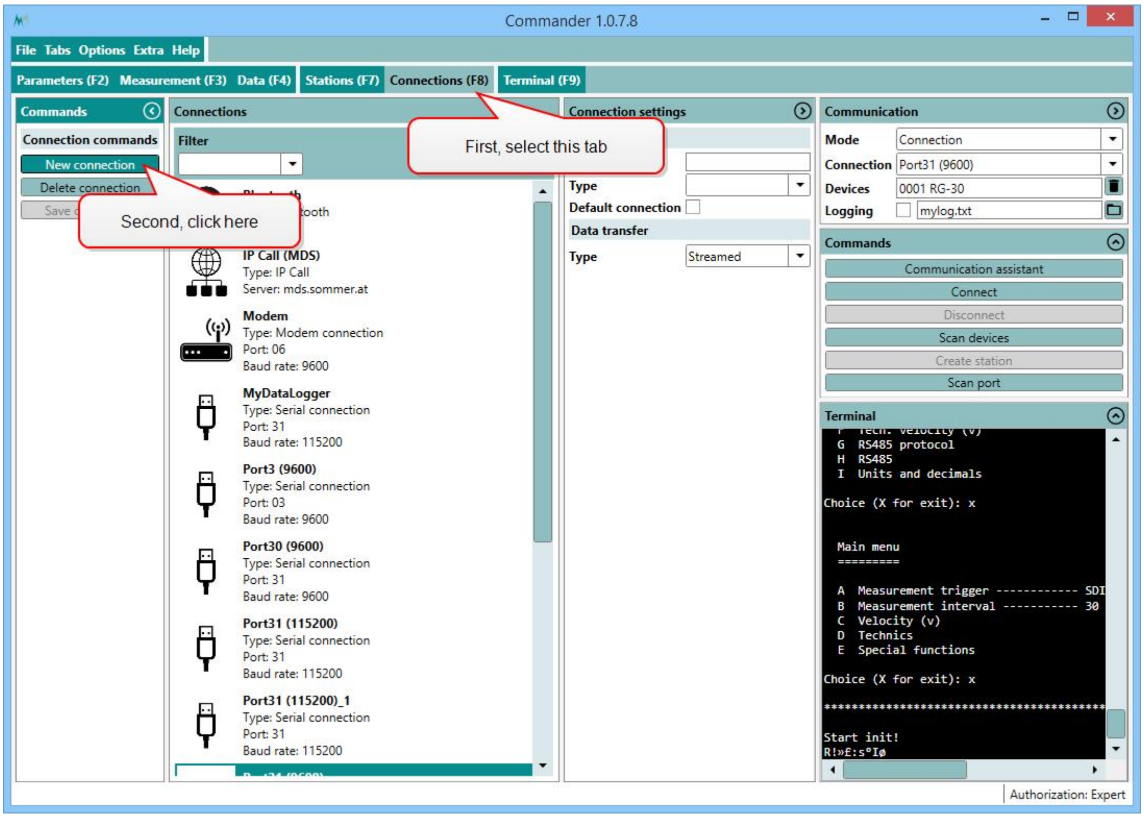
*Protocol Data Unit

Table 22 Slave ID

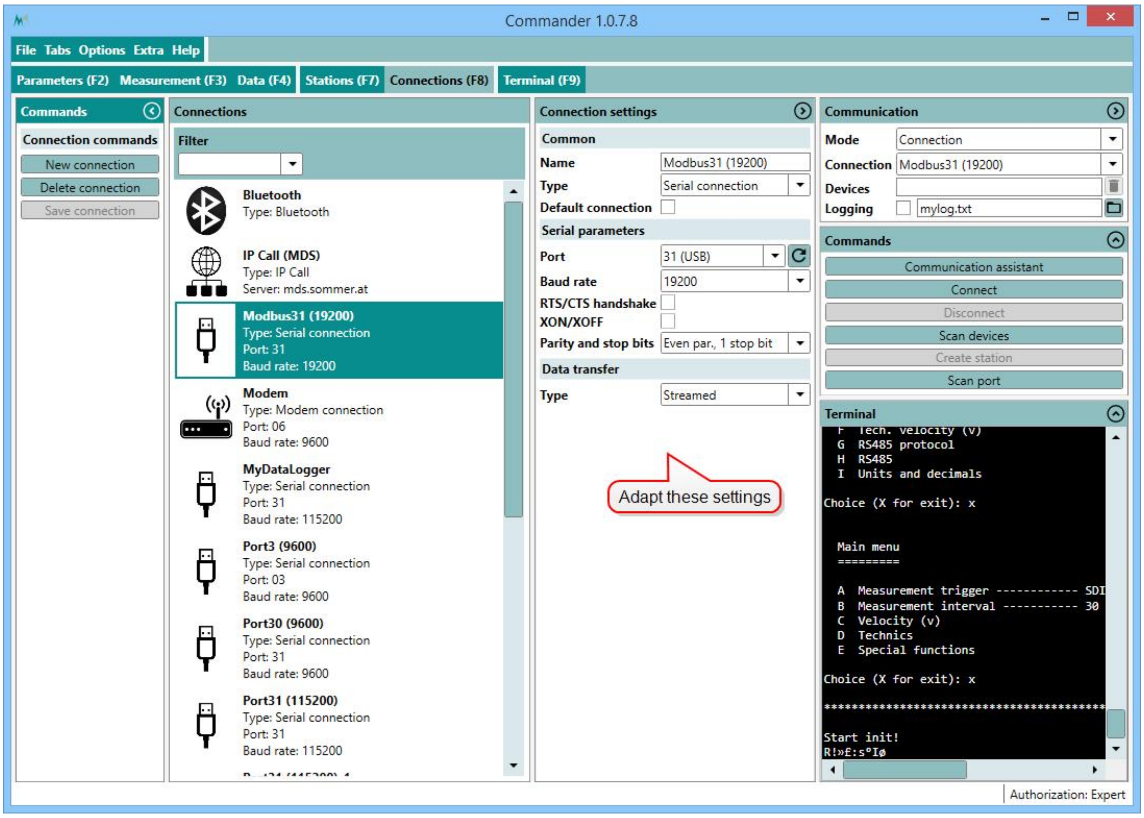
12.5.6 Reactivate Sommer protocol

Follow the instructions below to change the data output back to Sommer-protocol:

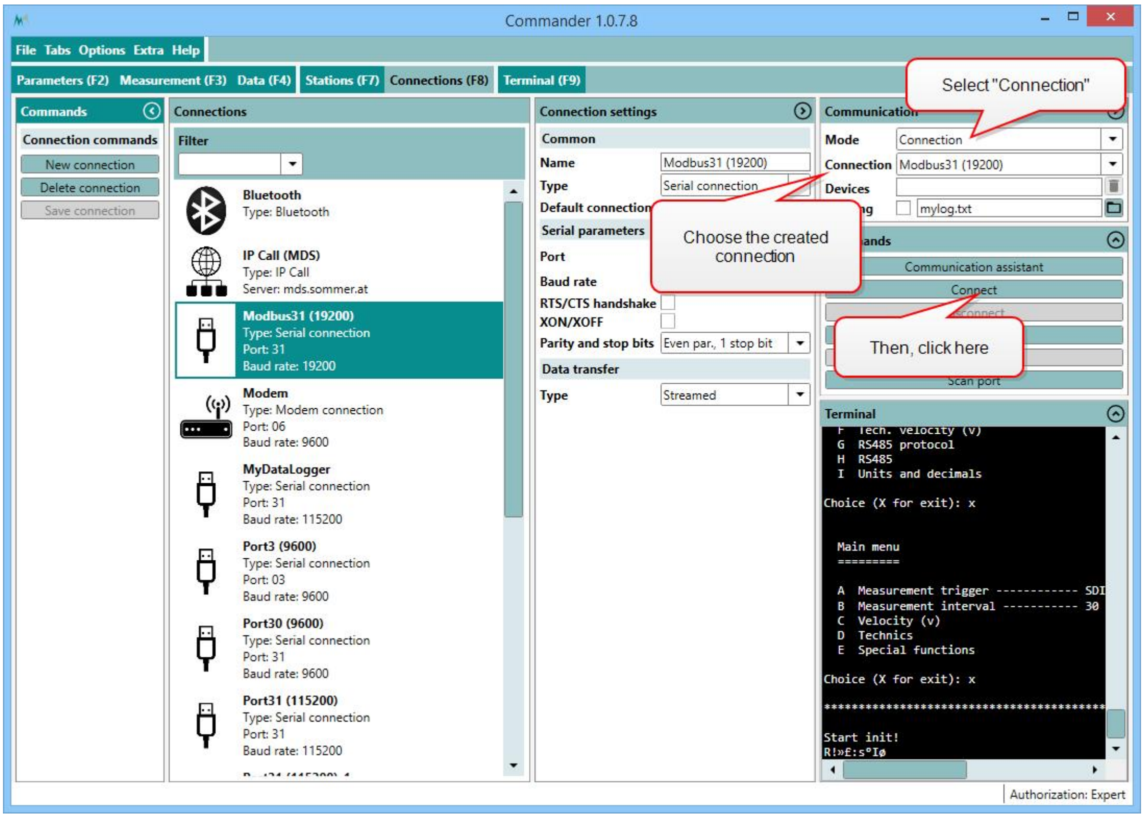
1. Open the Connections (F8) tab and click New connection.



2. Enter the Name of the new connection. We recommend to use a meaningful name for later recognition, e.g. Modbus31 (19200) to indicate port 31 and Baud-rate 19200. Select the Type Serial connection and choose the Port your sensor is connected to, set the Baud-rate to *19200* and the Parity/stop bits to *Even par., 1 stop bit*.



3. Click Save connection.
4. In the Communication window select Mode Connection and choose the Connection you have created. Then click Connect.

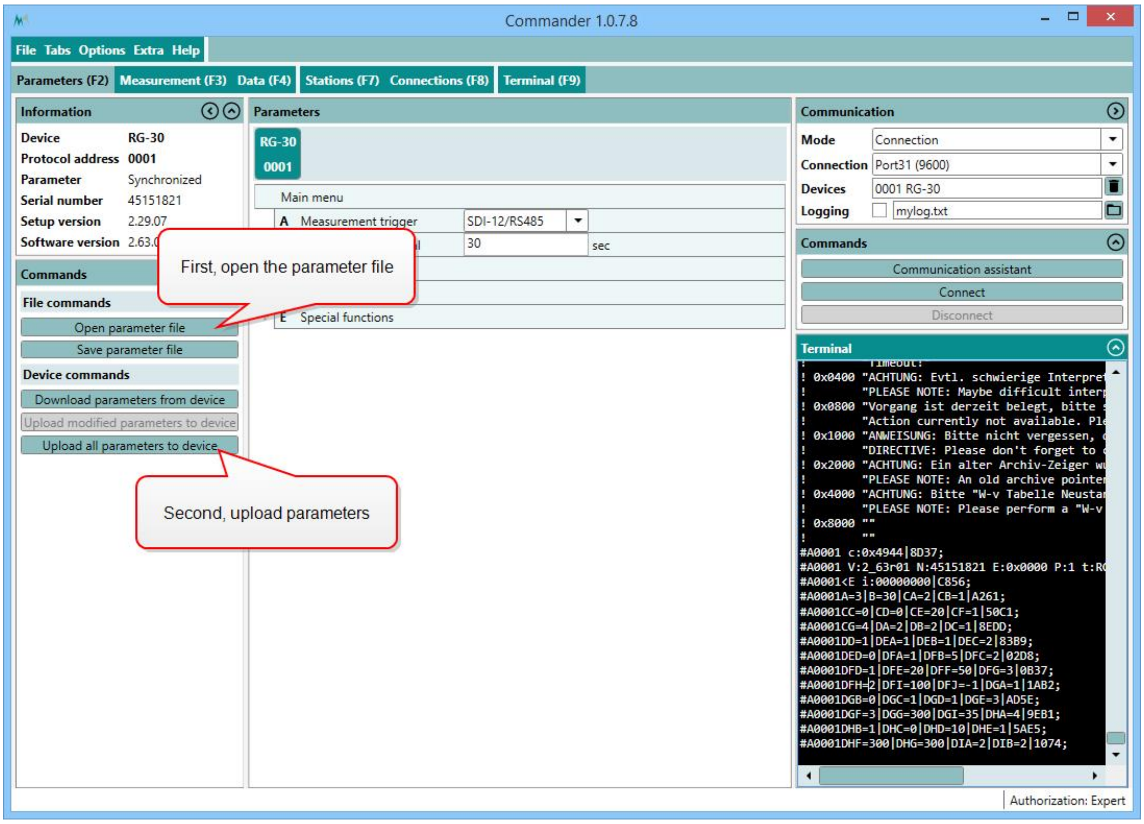


5. Download the parameters and save the parameter file as described in Modbus configuration.

> **TIP** Save the parameter file for future use and to document configuration changes!

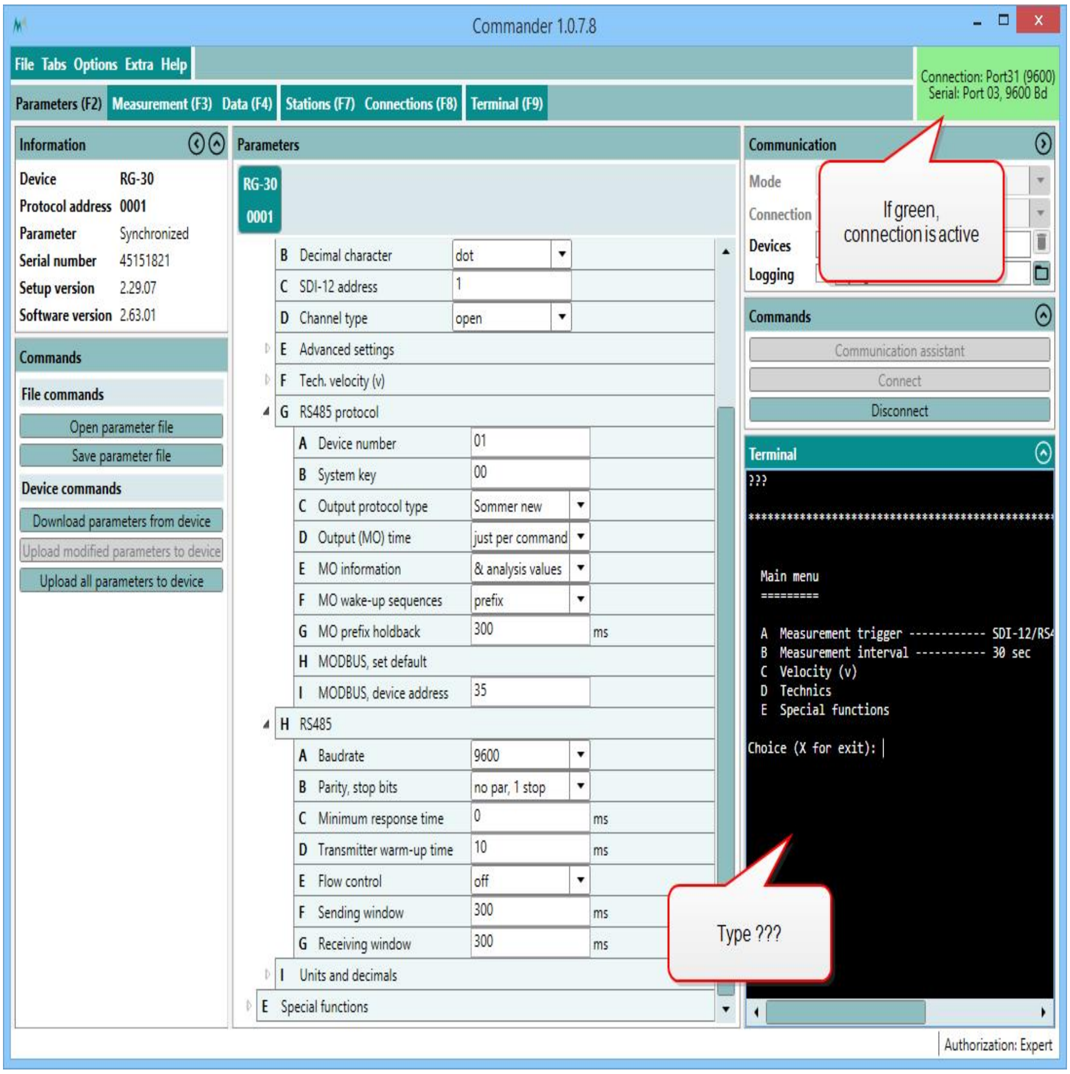
6. Now, two options are available to revert communication back to the Sommer-protocol:

A. If a parameter file is available that has the Sommer-protocol enabled, the file can be loaded by clicking Open parameter file, selecting the respective file and uploading the parameters to the device by clicking Upload all parameters to device.

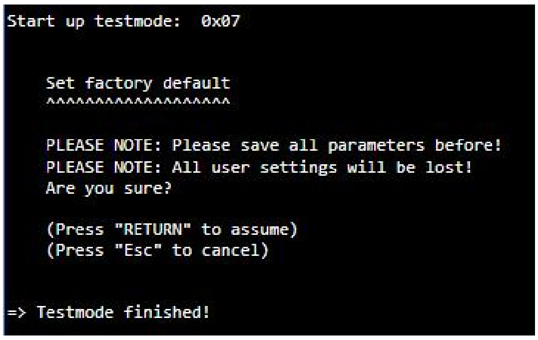


B. If no parameter file is available, the device has to be reset to its default configuration:

1. Click into the Terminal window and type `???` to enter the sensor-menu.



2. Navigate to Special functions and select Set factory default...
3. Acknowledge the safety-note.



4. Enter `X` until you get back to the main menu. The Sommer-sensor is now restarted and available in its initial configuration. As the connection-parameters have been changed to the default settings, the connection to the sensor is lost. Press Disconnect for

completion.

7. Establish the original connection to the Sommer-sensor as described in Modbus configuration.
8. Download the sensor's parameters in the Parameters (F2) tab, adapt the required parameters, or upload your originally saved parameter file to the IDS-20d.

12.5.7 PLC integration

The IDS-20d can be integrated into a PLC system as a slave device. It supports the PROFIBUS, PROFINET, EtherCAT and CANopen protocols. This requires an additional serial converter, e.g. Anybus Communicator.

13 Parameter definitions

A Relay A

A-A Output value

Specifies the variable which controls the relay.

Option	Description
Off	Relay does not switch
Ice (default)	Relay is turned on if Output value exceeds specified value
Ice and ice rate	Relay is turned on if Output value and Output value exceed specified values
Water	Relay is turned on if Output value exceed specified value

A-B Sensor choice

The sensor for which the limit value is monitored.

A-C Turn off delay

The time relay is kept energized after the monitored variable falls below the limit value again.

Unit	sec	seconds

Value range	0...65535	600 (default)

A-D Ice limit

The amount of ice accreted before the relay is switched.

Unit	mm	
Value range	0.0...9999999.9	0.5 (default)

A-E Water limit

The amount of accumulated water before the relay is switched.

Unit	mm	
Value range	0.0...9999999.9	1.999 (default)

A-F Ice rate limit

The rate at which ice accumulates before the relay is switched.

Unit	mm/h	
Value range	0...99999999	100 (default)

A-G Test output

Function to test the relay manually.

B Relay B

B-A Output value

Specifies the variable which controls the relay.

Option	Description
Off	Relay does not switch
Ice (default)	Relay is turned on if Output value exceeds specified value
Ice and ice rate	Relay is turned on if Output value and Output value exceed specified values
Water	Relay is turned on if Output value exceed specified value

B-B Sensor choice

The sensor for which the limit value is monitored.

B-C Turn off delay

The time relay is kept energized after the monitored variable falls below the limit value again.

Unit	sec	seconds
Value range	0...65535	600 (default)

B-D Ice limit

The amount of ice accreted before the relay is switched.

Unit	mm	
Value range	0.0...9999999.9	0.5 (default)

B-E Water limit

The amount of accumulated water before the relay is switched.

Unit	mm	
Value range	0.0...9999999.9	1.999 (default)

B-F Ice rate limit

The rate at which ice accumulates before the relay is switched.

Unit	mm/h	
Value range	0...99999999	100 (default)

B-G Test output

Function to test the relay manually.

C Sensor tests

C-A Sensor S1, test heating

Function to test the sensor heating. Heats the sensor for the selected duration.

C-B Sensor S1, test

Function to test the ice-sensor. Returns the currently measured capacity values. Used to verify that the sensor reads zero when dry.

C-C Sensor S2, test heating

Function to test the sensor heating. Heats the sensor for the selected duration.

C-D Sensor S2, test

Function to test the ice-sensor. Returns the currently measured capacity values. Used to verify that the sensor reads zero when dry.

D Technics

D-A SDI-12 address

`generic-sdi-12-address`

The address is a unique identifier of the sensor within a SDI-12 bus system.

Value range	Default	Units
0…9, a…z, A…Z	0	-

D-B Measurement Interval

`generic-measurement-interval`

The interval at which measurements are acquired.

Value range	Default	Units
20…18'000	60	s

D-C Units and decimals

D-C-A Temperature, unit

`generic-units-temperature`

The following units of the air temperature can be selected:

ID	Option	Description
1	°C (default)	Degrees Celsius
2	°F	Fahrenheit

D-C-B Temperature, decimals

`generic-decimals-temperature`

The number of decimal places for the measured air temperature.

Value range	Default	Units
0…6	2	-

D-D SBP device addressing

D-D-A Device number

`generic-rs-485-protocol-device-number`

The device number is used for the unique identification of the device in a bus system.

Value range	Default	Units
0…98	1 (default)	-

D-D-B System key

`generic-rs-485-protocol-system-key`

The system key defines the bus system of the device. Thus, different conceptual bus systems can be separated. Interfering bus systems occur if the remote radio coverage of two measurement systems overlap. In general, the system key should be set to 00.

Value range	Default	Units
0...99	0	-

D-E RS-485 (COM)

D-E-A Output protocol

D-E-A-A Protocol type

`generic-rs-485-protocol-type`

The type of the serial output protocol. The following options are available:

ID	Option	Description
1	Sommer (default)	Sommer bus protocol (SBP); data values are returned with an index starting at 1. Multiple strings may be returned.
2	Standard	Standard protocol; data values are returned without an index in one string.
3	MODBUS	Modbus protocol

NOTE For MODBUS applications run MODBUS, set default to get the appropriate communication settings.

D-E-A-B Measurement output

`generic-rs-485-protocol-measurement-output`

Specifies the timing of the serial data output.

ID	Option	Description
1	Just per command	The output is only requested by commands via RS-485.
2	After measurement (default)	The serial data output is performed automatically right after each measurement.
3	Pos. TRIG slope	The output is triggered by a positive edge of a control signal applied to the trigger input.

D-E-A-C Information

`generic-rs-485-protocol-information`

The main measurement values are always included in the data output string. Additionally, special and analysis values can be included.

ID	Option	Description
1	Main values	Only the main values are returned.
2	& Special values (default)	Main values and special values are returned.
3	& Analysis values	Main, special and analysis values are returned.

D-E-A-D Wake-up sequence

`generic-rs-485-protocol-wake-up-sequence`

Serial data can be transmitted to a recording device automatically without a request. However, many devices demand a wake-up sequence before they can receive and process data. The IDS-20d has the option to send a sync sequence and a prefix before data are transmitted. The following options are available:

ID	Option	Description
1	Off	No wake-up sequence
2	Sync	The sync sequence UU~?~? is sent before the output string.
3	Prefix (default)	A blank with a time delay is sent before the output string.
4	Prefix & Sync	A blank with a time delay and the sync sequence UU~?~? is sent before the output string.

D-E-A-E Prefix holdback

`generic-rs-485-protocol-prefix-holdback`

The hold-back time defines the time delay between the prefix and the data string.

Value range	Default	Units
0...5'000	300	ms

D-E-A-F MODBUS, set default

`generic-rs-485-protocol-modbus-set-default`

Sets all parameters required for Modbus communication automatically. The following settings are adapted:

Parameter	Modbus setting
OP, measurement output	just per command
Output protocol (OP)	Modbus
MODBUS, device address	35
Sleep mode	Modbus, slow
Parity, stop bits	even par, 1 stop
Baud rate	19200
Flow control	off
Transmitter warm-up time	10 ms
Minimum response time	30 ms

D-E-A-G MODBUS, device address

`generic-rs-485-protocol-modbus-device-address`

Unique device address for the Modbus protocol.

Value range	Default	Units
1...247	35	-

D-E-B Port

D-E-B-A Baud rate

`generic-rs-485-port-baud-rate`

The following transmission rates in bps (baud) can be selected:

ID	Option	Description
1	1'200	-
2	2'400	-
3	4'800	-
4	9'600 (default for sensors and data logger inputs)	-
5	19'200 (default if used with radio communication)	-
6	38'400	-
7	57'600	-
8	115'200 (default for data loggers)	-

D-E-B-B Parity, stop bits

`generic-rs-485-port-parity-stop-bits`

The following combinations of parity and stop bits can be selected:

ID	Option	Description
1	No par, 1 stop (default)	No parity and 1 stop bit
2	No par, 2 stop	No parity and 2 stop bits
3	Even par, 1 stop	Even parity and 1 stop bit
4	Odd par, 1 stop	Odd parity and 1 stop bit

D-E-B-C Minimum response time

`generic-rs-485-port-minimum-response-time`

This setting avoids failures of half-duplex interfaces. For this purpose the response to a command is delayed by the selected time. Additionally, the response is also kept temporally compact.

Value range	Default	Units
0...2'000	10	ms

D-E-B-D Transmitter warm-up time

`generic-rs-485-port-transmitter-warm-up-time`

The transmitter warm-up time defines the time before data is sent.

Value range	Default	Units
0...2'000	10	ms

D-E-B-E Flow control

`generic-rs-485-port-flow-control`

Flow control for the defined application.

ID	Option	Description
1	Off	no flow control
2	XOFF-XON blocking (default)	XOFF-XON flow control, especially adapted for half-duplex systems
4	DFM-RC	Flowcontrol for Sommer Messtechnik DFM point-to-point radios.
5	DFM-TM	Flowcontrol for Sommer Messtechnik DFM tiny-mesh radios.

D-E-B-F Sending window

`generic-rs-485-port-sending-window`

If XON-XOFF flow control is activated data are transmitted in blocks with the defined length.

Value range	Default	Units
200...5'000	300	ms

D-E-B-G Receiving window

`generic-rs-485-port-receiving-window`

If XON-XOFF flow control is activated transmission of blocks is delayed by the specified time.

Value range	Default	Units
200...5'000	300	ms

D-F Sensor S1

D-F-A Sensor type

One of the following sensor types can be selected:

Option	Description
Cube 5 (default)	Cube 5 sensor
Rod T 80	Rod sensor 80
Custom	Reserved for custom or new sensor types

D-F-B Sensor S1, orientation

The orientation of the sensor relative to geographic north. Use the black mark on the cube sensor for northing.

Unit	°	
Value range	-180...359	0 (default)

D-F-C Icing verification

D-F-C-A Maximum temperature

Temperature below which icing may occur.

Unit	°C	
Value range	-99999.9...999999.9	0.5 (default)

D-F-C-B Minimum humidity

Relative humidity above which icing may occur.

Unit	-	
Value range	0.0...9999999.9	80 (default)

D-F-C-C Maximum water

Thickness of water layer below which icing may occur.

Unit	mm	
Value range	0.0...9999999.9	0.5 (default)

D-F-C-D Switch on delay

Time delay between verification of icing and actual output of icing in data string. Specifying a delay might be advisable under threshold conditions.

Unit	sec	
Value range	0...7200	0 (default)

D-F-C-E Temperature sensor choice

The temperature sensor used for icing verification. Select one of the following options:

Option	Description
sensor temperature (default)	The surface temperature of the IDS-20d sensor
air temperature	The air temperature of the external T/rH-sensor

D-F-D Limits and timer

D-F-D-A Min. sup. voltage for heating

Minimum supply voltage for sensor heating.

Unit	V	
Value range	0.00...999999.99	10 (default)

D-F-D-B Ice, maximum

Maximum ice accumulation before sensor starts heating.

Unit	mm	
Value range	0...9999999.9	1 (default)

D-F-D-C Ice, minimum

Thickness of ice layer at which heating stops. This limit is only active in combination with Water, minimum.

Unit	mm	
Value range	0...9999999.9	0.1 (default)

D-F-D-D Water, maximum

Maximum water accumulation before sensor starts heating.

Unit	mm	
Value range	1.0...9999999.9	2 (default)

D-F-D-E Water, minimum

Thickness of water layer at which heating stops. This limit is only active in combination with Ice, minimum.

Unit	mm	
Value range	0.0...9999999.9	0.1 (default)

D-F-D-F Ice rate, heating

A switch to activate a sensor heating if the icing-rate drops below a specified limit. Generally, this option is used to detect individual icing-events.

If ice accumulates on the sensor above a limit value specified in Ice limit, relay A and/or B close; see Figure 11 for an illustration. Ice accretion may continue above this limit value, but may eventually cease, i.e. the icing rate levels off. Any further accumulation on the existing ice layer can be detected with reduced sensitivity only. Thus, it would be advantageous to continue ice-monitoring with a dry sensor surface. The "ice rate, heating" setting enables this option: If the icing rate falls below the value specified in Ice rate, minimum over the time set in Ice rate, holdtime a sensor heating is triggered. Consequently, relay A and/or B open, the sensor is defrosted and the IDS-20d is ready to detect a new icing event.

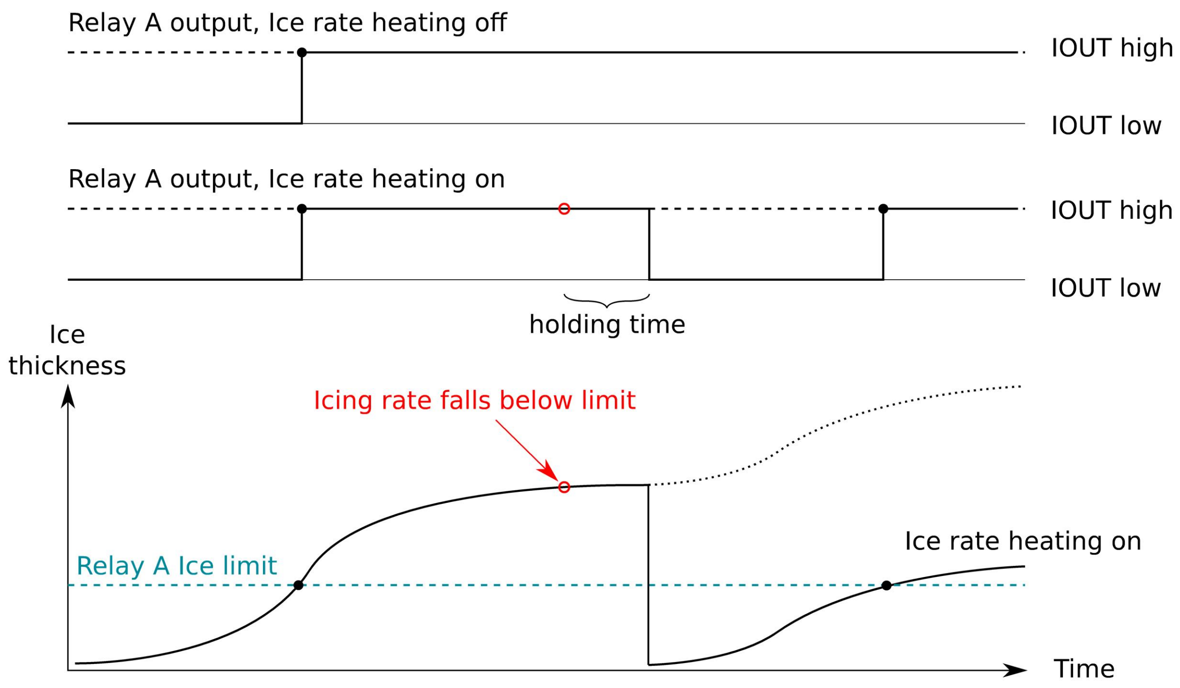


Figure 11 Behavior of Ice rate heating option

Option	Description
off	Sensor heating triggered by reduced icing rate is inactive.
on (default)	Sensor heating triggered by reduced icing rate active.

D-F-D-G Ice rate, minimum

Minimum icing rate below which a sensor heating is triggered. See Ice rate, heating for details.

Unit	mm/h	
Value range	-999999.9...9999999.9	0.5 (default)

D-F-D-H Ice rate, holdtime

Time before a sensor heating is triggered due to a low icing rate. See Ice rate, heating for details.

Unit	sec	
Value range	0...7200	600 (default)

D-F-D-I Maximum heating time

Maximum heating duration for one heating cycle.

Unit	sec	
Value range	0…7200	600 (default)

D-F-D-J Subsequent heating, head

The time the sensor head is continued to be heated after a regular heating cycle.

Unit	sec	
Value range	0…1800	0 (default)

D-F-D-K Subsequent heating, shaft

The time the sensor shaft is continued to be heated after a regular heating cycle.

Unit	sec	
Value range	0…1800	120 (default)

D-F-D-L Cool down duration

Time for sensor to cool down to ambient conditions.

Unit	sec	
Value range	0…1800	180 (default)

D-F-D-M Duration frost suppression

Frost generally builds up to thin ice layers well below the Ice, minimum limit and the relay Duration frost suppression before accretion levels off. To detect individual frost events a sensor heating can be triggered after a specified time with no further ice accumulation. The sensor surface is then dry again to sense the next frost-event. Figure 12 illustrates such a situation:

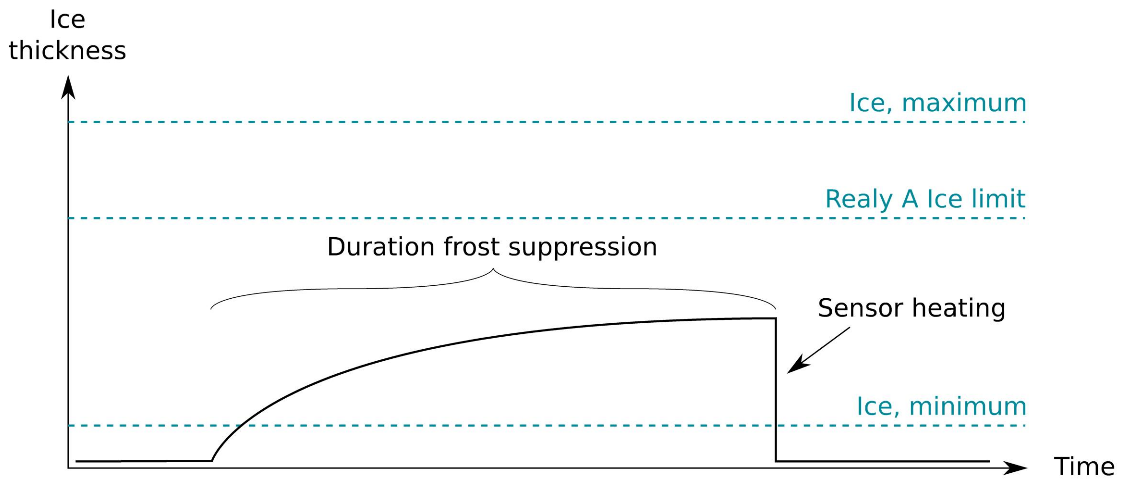


Figure 12 Duration frost suppression

ATTENTION If Duration frost suppression is set to *0* frost suppression is inactive.

Unit	sec	
Value range	-86400...86400	0 (default)

D-F-D-N Meas. duration icing rate

Measurement time used to determine icing rate.

Unit	sec	
Value range	0...1800	360 (default)

D-F-E Sensor S1 temperature

D-F-E-A Temperature offset

Offset of the temperature of the T/rH-sensor. An offset might be required if the sensor needs to be matched to an external reference.

Unit	°C	
Value range	-9999.99...99999.99	0 (default)

D-F-E-B Adjust temperature

Function to adjust the temperature measurement of the T/rH-sensor. Applying this function will update the setting Temperature offset.

D-F-E-C Test temperature

Function to test the temperature measurement of the T/rH-sensor.

D-F-F Sensor S1, test heating

Function to test the sensor heating. Heats the sensor for the selected duration.

D-F-G Sensor S1, zero adjust

Function to reset the capacity measurements of the sensor plates. Only used during installation to compensate for any capacities introduced by the sensor cable.

D-F-H Sensor S1, test

Function to test the ice-sensor. Returns the currently measured capacity values. Used to verify that the sensor reads zero when dry.

D-G Sensor S2

D-G-A Sensor type

One of the following sensor types can be selected:

Option	Description
Cube 5 (default)	Cube 5 sensor
Rod T 80	Rod sensor 80
Custom	Reserved for custom or new sensor types

D-G-B Sensor S2, orientation

The orientation of the sensor relative to geographic north. Use the black mark on the cube sensor for northing.

Unit	°	
Value range	-180...359	0 (default)

D-G-C Icing verification

D-G-C-A Maximum temperature

Temperature below which icing may occur.

Unit	°C	
Value range	-99999.9...999999.9	0.5 (default)

D-G-C-B Minimum humidity

Relative humidity above which icing may occur.

Unit	-	
Value range	0.0...9999999.9	80 (default)

D-G-C-C Maximum water

Thickness of water layer below which icing may occur.

Unit	mm	
Value range	0.0...9999999.9	0.5 (default)

D-G-C-D Switch on delay

Time delay between verification of icing and actual output of icing in data string. Specifying a delay might be advisable under threshold conditions.

Unit	sec	
Value range	0...7200	0 (default)

D-G-C-E Temperature sensor choice

The temperature sensor used for icing verification. Select one of the following options:

Option	Description
sensor temperature (default)	The surface temperature of the IDS-20d sensor
air temperature	The air temperature of the external T/rH-sensor

D-G-D Limits and timer

D-G-D-A Min. sup. voltage for heating

Minimum supply voltage for sensor heating.

Unit	V	
Value range	0.00...999999.99	10 (default)

D-G-D-B Ice, maximum

Maximum ice accumulation before sensor starts heating.

Unit	mm	
Value range	0...9999999.9	1 (default)

D-G-D-C Ice, minimum

Thickness of ice layer at which heating stops. This limit is only active in combination with Water, minimum.

Unit	mm	
Value range	0...9999999.9	0.1 (default)

D-G-D-D Water, maximum

Maximum water accumulation before sensor starts heating.

Unit	mm	
Value range	1.0...9999999.9	2 (default)

D-G-D-E Water, minimum

Thickness of water layer at which heating stops. This limit is only active in combination with Ice, minimum.

Unit	mm	
Value range	0.0...9999999.9	0.1 (default)

D-G-D-F Ice rate, heating

A switch to activate a sensor heating if the icing-rate drops below a specified limit. Generally, this option is used to detect individual icing-events.

If ice accumulates on the sensor above a limit value specified in Ice limit, relay A and/or B close; see Figure 13 for an illustration. Ice accretion may continue above this limit value, but may eventually cease, i.e. the icing rate levels off. Any further accumulation on the existing ice layer can be detected with reduced sensitivity only. Thus, it would be advantageous to continue ice-monitoring with a dry sensor surface. The "ice rate, heating" setting enables this option: If the icing rate falls below the value specified in Ice rate, minimum over the time set in Ice rate, holdtime a sensor heating is triggered. Consequently, relay A and/or B open, the sensor is defrosted and the IDS-20d is ready to detect a new icing event.

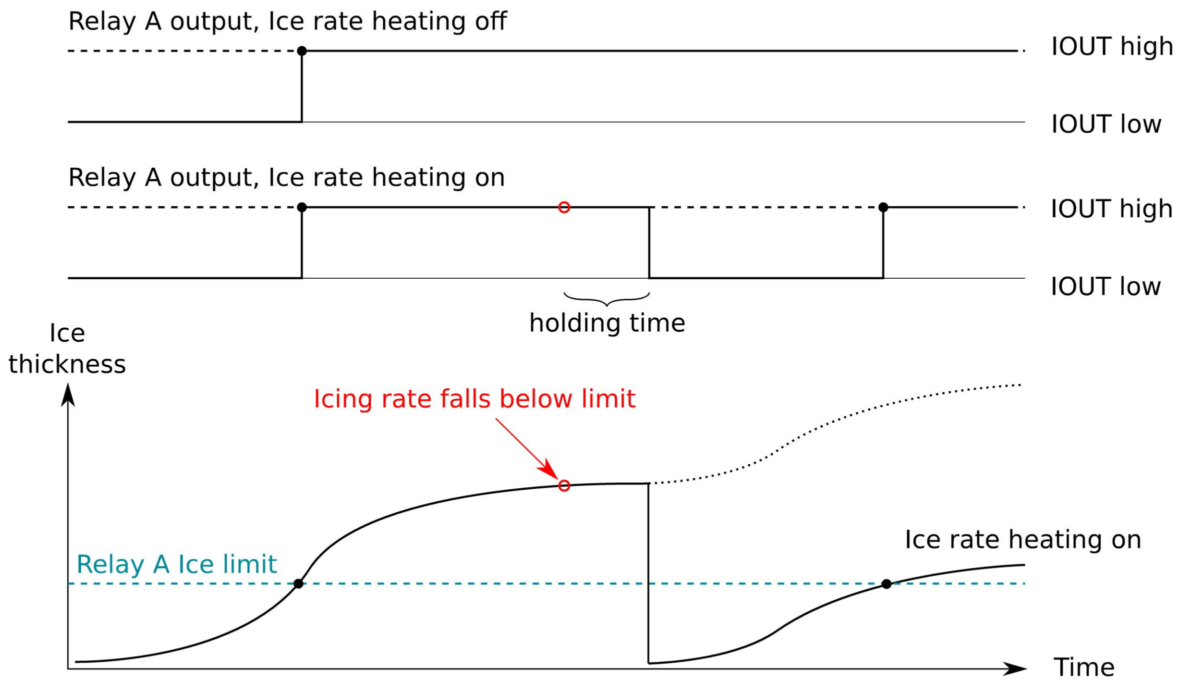


Figure 13 Behavior of Ice rate heating option

Option	Description
off	Sensor heating triggered by reduced icing rate is inactive.
on (default)	Sensor heating triggered by reduced icing rate active.

D-G-D-G Ice rate, minimum

Minimum icing rate below which a sensor heating is triggered. See Ice rate, heating for details.

Unit	mm/h	
Value range	-999999.9...9999999.9	0.5 (default)

D-G-D-H Ice rate, holdtime

Time before a sensor heating is triggered due to a low icing rate. See Ice rate, heating for details.

Unit	sec	
Value range	0...7200	600 (default)

D-G-D-I Maximum heating time

Maximum heating duration for one heating cycle.

Unit	sec	
Value range	0...7200	600 (default)

D-G-D-J Subsequent heating, head

The time the sensor head is continued to be heated after a regular heating cycle.

Unit	sec	
Value range	0...1800	0 (default)

D-G-D-K Subsequent heating, shaft

The time the sensor shaft is continued to be heated after a regular heating cycle.

Unit	sec	
Value range	0...1800	120 (default)

D-G-D-L Cool down duration

Time for sensor to cool down to ambient conditions.

Unit	sec	
Value range	0...1800	180 (default)

D-G-D-M Duration frost suppression

Frost generally builds up to thin ice layers well below the Ice, minimum limit and the relay Duration frost suppression before accretion levels off. To detect individual frost events a sensor heating can be triggered after a specified time with no further ice accumulation. The sensor surface is then dry again to sense the next frost-event. Figure 14 illustrates such a situation:

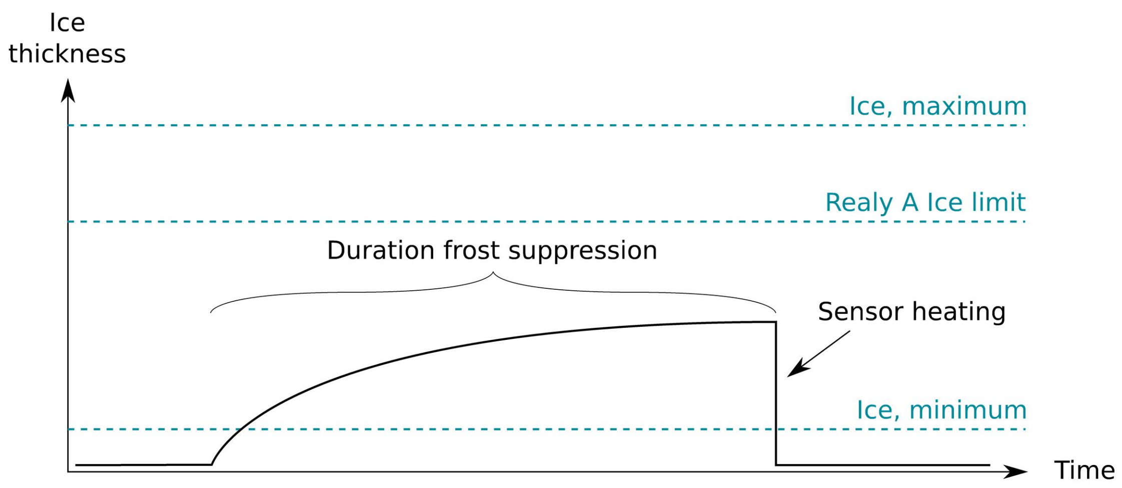


Figure 14 Duration frost suppression

> **ATTENTION** If Duration frost suppression is set to *0* frost suppression is inactive.

Unit	sec	
Value range	-86400...86400	0 (default)

D-G-D-N Meas. duration icing rate

Measurement time used to determine icing rate.

Unit	sec	
Value range	0...1800	360 (default)

D-G-E Sensor S2 temperature

D-G-E-A Temperature offset

Offset of the temperature of the T/rH-sensor. An offset might be required if the sensor needs to be matched to an external reference.

Unit	°C	
Value range	-9999.99...99999.99	0 (default)

D-G-E-B Adjust temperature

Function to adjust the temperature measurement of the T/rH-sensor. Applying this function will update the setting Temperature offset.

D-G-E-C Test temperature

Function to test the temperature measurement of the T/rH-sensor.

D-G-F Sensor S2, test heating

Function to test the sensor heating. Heats the sensor for the selected duration.

D-G-G Sensor S2, zero adjust

Function to reset the capacity measurements of the sensor plates. Only used during installation to compensate for any capacities introduced by the sensor cable.

D-G-H Sensor S2, test

Function to test the ice-sensor. Returns the currently measured capacity values. Used to verify that the sensor reads zero when dry.

D-H Temperature and humidity (TH)

D-H-A Humidity offset

Offset of the humidity of the T/rH-sensor. An offset might be required if the sensor needs to be matched to an external reference.

Unit	°C	
Value range	-999999.9...9999999.9	0.0 (default)

D-H-B Adjust humidity

Function to adjust the humidity measurement of the T/rH-sensor. Applying this function will update the setting Humidity offset.

D-H-C Test humidity

Function to test the humidity measurement of the T/rH-sensor.

D-H-D Temperature offset

Offset of the temperature of the T/rH-sensor. An offset might be required if the sensor needs to be matched to an external reference.

Unit	°C	
Value range	-9999.99...99999.99	0 (default)

D-H-E Adjust temperature

Function to adjust the temperature measurement of the T/rH-sensor. Applying this function will update the setting Temperature offset.

D-H-F Test temperature

Function to test the temperature measurement of the T/rH-sensor.

D-I Advanced settings

D-I-A Sleep mode

`generic-sleep-mode`

Defines the behavior of the IDS-20d between two measurements, provided the measurement interval is longer than the time of the measurement itself. The following options are available:

ID	Option	Description
1	MODBUS, fast	For MODBUS applications. The IDS-20d stays in normal mode. This option permits high data transmission rates, but increases power consumption.
2	MODBUS, slow	For MODBUS applications. The IDS-20d goes into idle mode and can be woken up by a command via the RS-485 interface with a low baud rate. This option reduces power consumption at lower data transmission rates.
3	Standard (default)	The IDS-20d goes into sleep mode and can be woken up by a command via the RS-485 interface only with a time delay. Option with the lowest power consumption.

D-I-B SDI12 ‘M’-response

`generic-sdi-12-m-response`

Defines how an SDI-12 M-command received by the IDS-20d is answered if the requested number of measurement values exceeds 9. The following options are available:

ID	Parameter	Description
1	expand address	This option should only be used with SDI-12 standard V1.0. The measurement values can be requested with the commands `aD0!`, `aD1!`,…, with `a` the sensor address. Max. 9 values are returned for each command.
2	just expand output	The `M`-request received by the IDS-20d is answered according to SDI-12 standard V1.3, which supports transmitting more than 9 measurement values per answer.
3	as at ‘C’ request	The M-request received by the IDS-20d is answered as if several `C`-requests were sent.
4	M1, M2, M3 split (default)	The M-request received by the IDS-20d is answered as if several `Mk`-commands were sent, with k depending on the number of measurement values to be transmitted (`M1` returns the first 9 measurement values, `M2` the second nine values, etc).

D-I-C “OFF” turn off temperature

The ambient temperature above which the IDS-20d stops performing measurements.

Unit	°C	
Value range	-99999.9...999999.9	10 (default)

NOTE

If the ambient temperature exceeds “OFF” turn off temperature, the IDS-20d returns the following values for ice and water variables:

Protocol	Returned value
RS-485	empty string
SDI-12	`00000000`
Modbus	10^6, 10^7, 10^8

D-I-D Functional switch monitoring

Sets the activity of the “OUT function” output. The following options are available:

Option	Description
just while awake	The “OUT function” output is only active while the device is active.
always active (default)	The “OUT function” output is always active.

ATTENTION If Functional switch monitoring is set to *just while awake*, Sleep mode must be set to *standard*!

D-I-E Functional switch at “OFF”

The status of the “OUT Function” relay of the IDS-20d. This status depends on the instrument status and the “OFF” turn off temperature (above this temperature the IDS-20d does not perform icing-measurements). The OUT Function output is an "active high" output, i.e. as long as the instruments operates normally, the output is high. The following options are available:

<table>
<tr><th>Option</th><th>Description</th></tr>
<tr><td>regular condition (default)</td><td>If the ambient temperature is above the limit value the output is set to high (1) and the relay is closed.
<table><tr><th>Instrument status</th><th>T above limit</th><th>OUT Function status</th></tr><tr><td>OK</td><td>No</td><td>1</td></tr><tr><td>OK</td><td>Yes</td><td>1</td></tr><tr><td>Error</td><td>No</td><td>0</td></tr><tr><td>Error</td><td>Yes</td><td>0</td></tr></table></td></tr>
<tr><td>error condition</td><td>If the ambient temperature is above the limit value the output is set to low (0) and the relay is opened. Thus, ambient temperatures that are too high are handled like any other error (output is set to low [0]).
If the ambient temperature is below the limit value and the instrument operates normally the output is set to high (1).
<table><tr><th>Instrument status</th><th>T above limit</th><th>OUT Function status</th></tr><tr><td>OK</td><td>No</td><td>1</td></tr><tr><td>OK</td><td>Yes</td><td>0</td></tr><tr><td>Error</td><td>No</td><td>0</td></tr><tr><td>Error</td><td>Yes</td><td>0</td></tr></table></td></tr>
</table>

An instrument error occurs if the power supply of the instrument is insufficient, the software detects a fatal error, a software procedure is slow or blocked or if the software runs in the bootloader.

D-I-F Sommer ID

`generic-sommer-id`

The Sommer ID is used to define stations within the Commander software. The ID is preset in the device and corresponds to its serial number.SOMMER suggests not to change the ID, except if a IDS-20d device is replaced. In such a case it can be practical to change the ID of the new device to the ID of the replaced device to guarantee data consistency.

D-J Measurement table

Lists all measured variables with their units (see Data output).

Index	Value	Unit	Description
01	Temperature	°C / F	Air temperature
02	Humidity	%	Humidity
03	Dew point	°C / F	Dew point
04	Relay A	0 / 1	State of relay A
05	Relay B	0 / 1	State of relay B
06	Relay function	0 / 1	State of measurement device
07	Sensor 1, Ice	mm	Current ice layer thickness on sensor 1
08	Sensor 1, Water	mm	Current water layer thickness on sensor 1
09	Sensor 1, Ice rate	mm/h	Current icing rate on sensor 1
10	Sensor 1, Temperature	°C / F	Surface temperature of sensor 1
11	Sensor 1, Direction	°	Icing direction of sensor 1
12	Sensor 1, Direction value		Directional distinction of ice accretion; the higher the value the more pronounced icing is in a certain direction.
13	Sensor 2, Ice	mm	Current ice layer thickness on sensor 2
14	Sensor 2, Water	mm	Current water layer thickness on sensor 2
15	Sensor 2, Ice rate	mm/h	Current icing rate on sensor 2
16	Sensor 2, Temperature	°C / F	Surface temperature of sensor 2
17	Sensor 2, Direction	°	Icing direction of sensor 2
18	Sensor 2, Direction value		Directional distinction of ice accretion; the higher the value the more pronounced icing is in a certain direction.

E Region format

E-A Language/Sprache

`generic-language`

The menu language.

ID	Option	Description
1	German/Deutsch	German language
2	English/Englisch (default)	English language

E-B Decimal character

`generic-decimals-character`

The character used as decimal separator in the values of the settings, in serial data strings and in .csv files.

ID	Option	Description
1	Comma	-
2	Dot (default)	-

F Special functions

F-A Relay, reset counters

Resets the relay counters.

F-B Relay, simulate outputs

Only available in terminal mode. This function is primarily used for remote system testing and can be triggered by the test input on pin 5 (see for details). It offers two options:

1. If option *1* is selected or the trigger signal on pin 5 is set high the following tasks are performed in sequence:
    a. Relay A is closed and the sensor heating (head and shaft) is turned on for 60 sec (if sensor 1 is active)
    b. Relay B is closed and the sensor heating (head and shaft) is turned on for 60 sec (if sensor 2 is active)
2. If option *2* is selected or the trigger signal on pin 5 is set high for more than 10 sec the tasks in option *1* are performed and the relay counters are reset.

F-C Device status

`generic-special-functions-device-status`

Displays information about the device and the software version.

F-D View setup

`generic-special-functions-view-setup`

All parameters of the IDS-20d are listed in the terminal window.

F-E Set factory default

`generic-special-functions-set-factory-default`

All parameters are reset to factory defaults. Only available in terminal-mode.

F-F Temp. load factory default

`generic-special-functions-temp-load-factory-default`

Loads factory default values temporarily. Only available in terminal mode.

F-G Relaunch program

`generic-special-functions-relaunch-program`

The device is restarted. Powering the sensor off and on again is equivalent.

Appendix A Measurement phases

The measurement phase describes the status of the IDS-20d sensors. It is returned with the analysis values at indices 26 and 40 and has the following format:

AA.BC

The labels are coded as follows:

Label	Description
AA	Sensor status, see Sensor status
B	Icing verification result of sensor 2, see Icing verification results
C	Icing verification result of sensor 1, see Icing verification results

EXAMPLE

4.00	Cube 5 sensor is heating Icing-criteria for both sensors are satisfied
2.04	Cube 5 sensor is cooling down Icing-criteria of Rod T 80 sensor are satisfied Temperature of Cube 5 sensor is too high
0.44	Both sensors are in normal measurement mode Temperature of both sensors is too high
0.00	Both sensors are in normal measurement mode Icing-criteria for both sensors are satisfied

A.1 Sensor status

The sensor status AA can take the values listed in Sensor status.

A.2 Icing verification

The IDS-20d uses the prevailing environmental conditions to verify the icing measured by the ice-sensors. Ice can only accrete on a sensor surface if the following conditions are satisfied:

- The sensor surface temperature must be below the limit specified in Maximum temperature.
- The relative humidity must exceed the limit value specified in Minimum humidity.
- The water content on the sensor surface must be below the limit value specified in Maximum water.

The icing verification values B and C can take the values listed in Icing verification results.

Value	Description	Comment
-1	Measurements are off	Above a specified ambient temperature the IDS-20d does not perform any icing-measurements.
0	Measurement active	Normal measurement mode
1	Determination of icing rate	Determines icing rate after cool down
2	Cool down, waiting time	After a heating cycle the sensor cools down to ambient temperature.
3	Subsequent heating	Sensor is heated after heating phase 4, 5 or 6 to ensure that the surface is completely dry.
4	Heating triggered by Ice, maximum	Sensor exceeds Ice, maximum value. Heating is on until ice and water layer thickness fall below Ice, minimum and Water, minimum or Maximum heating time has elapsed.
5	Heating triggered by Water, maximum	Sensor exceeds Water, maximum value. Heating is on until ice and water layer thickness fall below Ice, minimum and Water, minimum or Maximum heating time has elapsed.
6	Heating triggered by Ice rate, minimum	Icing rate falls below Ice rate, minimum. Heating is on until ice and water layer thickness fall below Ice, minimum and Water, minimum or Maximum heating time has elapsed.
14	Heating triggered by frost suppression, ice	Sensor exceeds Ice, minimum, stays below Ice limit of relay A or B and exceeds time limit of Duration frost suppression. Heating is on until ice and water layer thickness fall below Ice, minimum and Water, minimum or Maximum heating time has elapsed.
15	Heating triggered by frost suppression, water	Sensor exceeds Water, minimum, stays below Water limit of relay A or B and exceeds time limit of Duration frost suppression. Heating is on until water layer thickness fall below Water, minimum or Maximum heating time has elapsed.

Sensor status

Value	Description		
0	all icing-criteria are satisfied		
1	water content too high		
2		relative humidity too low	
3	water content too high	relative humidity too low	
4			sensor temperature too high
5	water content too high		sensor temperature too high
6		relative humidity too low	sensor temperature too high
7	water content too high	relative humidity too low	sensor temperature too high
8	Switch on delay elapses		

Icing verification results

Appendix B Troubleshooting

B.1 Devices

B.1.1 The IDS-20d is not responding or returns unreadable characters

Reason	Solution
The power supply is not connected or turned off.	Check if the power supply is connected and on.
The polarity of connected power supply wires is wrong.	Check the polarity of connected wires.
Wrong sensor cable.	Use the original sensor cable configured by Sommer Messtechnik (only applicable to Sommer Messtechnik cables).
Power supply is insufficient. The IDS-20d requires a certain inrush-current that the power supply is not able to provide.	1. Use a power supply providing >0.5 A at 12 VDC or a fully charged battery. 2. In case of long sensor cables (>50 m) use a 24-VDC power supply. Please note that power supplied by the USB-port is insufficient to power the IDS-20d!
The power supply voltage is out of range.	Adjust the power supply to match the specified voltage range.

Reason	Solution
The polarity of the connected RS-485-A and RS-485-B wires is wrong.	Reverse the polarity of the connected RS-485-A and RS-485-B wires.
The port settings of the IDS-20d and the data acquisition system do not match.	Use the CommanderCommunication assistant or adapt port settings on your device. **NOTE** Sommer Messtechnik devices require the following Baud rates: ● Sensor: 9600 ● Data logger: 115200 ● Modbus: 19200 In case of doubt use the function Check port in the Communication assistant.
The IDS-20d is set to Modbus.	Connect to the sensor using the Communication assistant of the Commander and select the *Modbus* option in the *Serial connection*.
A sensor wire is not connected firmly to the terminal of the data acquisition device.	Check the firm connection of the sensor wires.
A pin of the connector plug is bent or broken.	Verify that all connector pins are straight.
The sensor cable is damaged.	Replace the sensor cable.
The COM-port has not been assigned correctly to the USB converter.	1. Make sure to use a Sommer Messtechnik USB converter. Third party converters are not supported. 2. Check the COM-port number using Windows Device Manager. 3. Plug in the USB converter first, then start Commander.
The USB converter is faulty.	Replace the USB converter.
The USB port on your PC is not working.	Use another USB port.
The driver of the USB converter was incorrectly installed	Reinstall the driver of the USB converter.

B.1.2 The IDS-20d reboots repeatedly

Reason	Solution
The power supply has not enough current to start the IDS-20d.	Verify that the power supply provides enough current. A IDS-20d consumes up to 140 mA @ 12 V. If required, power the IDS-20d by an additional or alternative supply.

B.2 Measurement data

B.2.1 Measurement data are not updated

The device is connected to the Commander, but the data are not updated.

Cause	Solution
Data traffic conflict	Reboot the device by interrupting the power supply.

B.2.2 No data from the ice detection sensor are returned

Cause	Solution
Ambient temperature is too high. This may be the case if the IDS-20d is tested in the summer.	Increase "OFF" turn off temperature to a value higher than ambient.

B.3 Firmware & software

B.3.1 Commander loads wrong setup

If the setup is reloaded from the device the Commander seems to display an old version.

Cause	Solution
The device has been connected to the same PC before and several different setup files have been loaded.	● In the Communication section of the Commander, select Mode *Connection* and click on the trash can icon on the right edge. Then, reload the setup from the device. ● Delete the setup files of the device that have been downloaded by Commander to the folder *C:\Users\Public\Documents\Sommer\Setup*. The respective files can be identified by the serial number in the file name and the file date.

B.3.2 Firmware update via RS-485 is aborted

Reason	Solution
USB to RS-485 converter cable is damaged or can only operate on 9600 baud.	Replace USB to RS-485 converter cable. The programmer requires 57600 baud.

B.4 RS-485

B.4.1 Configuration via terminal shows unexpected behavior

Accessing the parameter menus in the terminal leads to unexpected behavior, e.g. after entering a menu character the terminal displays repeated error messages or jumps out of the parameter menu.

Reason	Solution
The sensor, power supply and PC/laptop do not share the same ground.	Verify that all equipment is connected to the same ground.

B.5 SDI-12

B.5.1 The IDS-20d is not detected by a SDI-12 master device

Reason	Solution
The IDS-20d and the SDI-12 master have different grounds.	Verify that the IDS-20d and the SDI-12 master are connected by a ground (GND) wire.

B.5.2 Data logger receives no SDI-12 data

Reason	Solution
The sensor is set to Measurement trigger *interval*, but the data logger sends a `M!` command, i.e. the data logger polls data.	If data are polled from the sensor, Measurement interval must be set to *SDI-12/RS485*.
The sensor is set to Measurement trigger *SDI-12/RS485*, but the data logger sends an `R!` command, i.e. the sensor pushes data.	If the sensor pushes data, Measurement interval must be set to *interval*.

B.6 Modbus

B.6.1 Modbus function 04 returns obscure measurement values

Reason	Solution
Sensor does not run in its own measurement interval, i.e., MeasuremenSet Mt trigger is not set to *Interval*.	Set Measurement trigger of the sensor to *Interval*. A Modbus master can only read measurement data, it cannot trigger measurements.
A second Modbus muster is present in the RS-485 bus.	Make sure that only one Modbus master is communicating with the Modbus slaves.
The signal wires between the Modbus master and the slaves are long and/or the ground potentials of the devices are different.	● Connect the grounds of the devices with an additional wire. ● Reduce the cable length.
Endianness of the Modbus polling unit is swapped. Generally, test values and measurement values are set to big endian. Older firmware versions may return measurement values as little endian.	If the device runs on an older firmware, convert the measurement values to float with little endian.

Appendix C CRC-16 array

CRC-16 array

```
crc16tab[] =
{
0x0000, 0x1021, 0x2042, 0x3063, 0x4084, 0x50A5, 0x60C6, 0x70E7,
0x8108, 0x9129, 0xA14A, 0xB16B, 0xC18C, 0xD1AD, 0xE1CE, 0xF1EF,
0x1231, 0x0210, 0x3273, 0x2252, 0x52B5, 0x4294, 0x72F7, 0x62D6,
0x9339, 0x8318, 0xB37B, 0xA35A, 0xD3BD, 0xC39C, 0xF3FF, 0xE3DE,
0x2462, 0x3443, 0x0420, 0x1401, 0x64E6, 0x74C7, 0x44A4, 0x5485,
0xA56A, 0xB54B, 0x8528, 0x9509, 0xE5EE, 0xF5CF, 0xC5AC, 0xD58D,
0x3653, 0x2672, 0x1611, 0x0630, 0x76D7, 0x66F6, 0x5695, 0x46B4,
0xB75B, 0xA77A, 0x9719, 0x8738, 0xF7DF, 0xE7FE, 0xD79D, 0xC7BC,
0x48C4, 0x58E5, 0x6886, 0x78A7, 0x0840, 0x1861, 0x2802, 0x3823,
0xC9CC, 0xD9ED, 0xE98E, 0xF9AF, 0x8948, 0x9969, 0xA90A, 0xB92B,
0x5AF5, 0x4AD4, 0x7AB7, 0x6A96, 0x1A71, 0x0A50, 0x3A33, 0x2A12,
0xDBFD, 0xCBDC, 0xFBBF, 0xEB9E, 0x9B79, 0x8B58, 0xBB3B, 0xAB1A,
0x6CA6, 0x7C87, 0x4CE4, 0x5CC5, 0x2C22, 0x3C03, 0x0C60, 0x1C41,
0xEDAE, 0xFD8F, 0xCDEC, 0xDDCD, 0xAD2A, 0xBD0B, 0x8D68, 0x9D49,
0x7E97, 0x6EB6, 0x5ED5, 0x4EF4, 0x3E13, 0x2E32, 0x1E51, 0x0E70,
0xFF9F, 0xEFBE, 0xDFDD, 0xCFFC, 0xBF1B, 0xAF3A, 0x9F59, 0x8F78,
0x9188, 0x81A9, 0xB1CA, 0xA1EB, 0xD10C, 0xC12D, 0xF14E, 0xE16F,
0x1080, 0x00A1, 0x30C2, 0x20E3, 0x5004, 0x4025, 0x7046, 0x6067,
0x83B9, 0x9398, 0xA3FB, 0xB3DA, 0xC33D, 0xD31C, 0xE37F, 0xF35E,
0x02B1, 0x1290, 0x22F3, 0x32D2, 0x4235, 0x5214, 0x6277, 0x7256,
0xB5EA, 0xA5CB, 0x95A8, 0x8589, 0xF56E, 0xE54F, 0xD52C, 0xC50D,
0x34E2, 0x24C3, 0x14A0, 0x0481, 0x7466, 0x6447, 0x5424, 0x4405,
0xA7DB, 0xB7FA, 0x8799, 0x97B8, 0xE75F, 0xF77E, 0xC71D, 0xD73C,
0x26D3, 0x36F2, 0x0691, 0x16B0, 0x6657, 0x7676, 0x4615, 0x5634,
0xD94C, 0xC96D, 0xF90E, 0xE92F, 0x99C8, 0x89E9, 0xB98A, 0xA9AB,
0x5844, 0x4865, 0x7806, 0x6827, 0x18C0, 0x08E1, 0x3882, 0x28A3,
0xCB7D, 0xDB5C, 0xEB3F, 0xFB1E, 0x8BF9, 0x9BD8, 0xABBB, 0xBB9A,
0x4A75, 0x5A54, 0x6A37, 0x7A16, 0x0AF1, 0x1AD0, 0x2AB3, 0x3A92,
0xFD2E, 0xED0F, 0xDD6C, 0xCD4D, 0xBDAA, 0xAD8B, 0x9DE8, 0x8DC9,
0x7C26, 0x6C07, 0x5C64, 0x4C45, 0x3CA2, 0x2C83, 0x1CE0, 0x0CC1,
0xEF1F, 0xFF3E, 0xCF5D, 0xDF7C, 0xAF9B, 0xBFBA, 0x8FD9, 0x9FF8,
0x6E17, 0x7E36, 0x4E55, 0x5E74, 0x2E93, 0x3EB2, 0x0ED1, 0x1EF0
}
```

Glossary

I

IP-Call

A technology that provides communications services (voice, SMS, voice-messaging) over the Internet, rather than via the public telephone network.

M

Modbus

A serial communications protocol for connecting industrial electronic devices.

R

RS-485

A standard defining the signal transmission in serial communication systems.

S

SBP

Sommer Bus Protocol

SDI-12

Asynchronous serial communications protocol for intelligent sensors (Serial Digital Interface at 1200 baud)

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